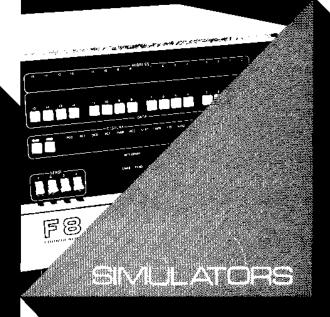


GUIDE TO PROGRAMMING









GUIDE TO PROGRAMMING

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INTRODUCTION

This manual explains how to write programs for the Fairchild F8 microprocessor system, and how these F8 programs cause a microprocessor system to function as a discrete logic replacement.

The Fairchild F8 family of logic devices consists of a Central Processing Unit and a number of complementary devices, manufactured using n-channel Isoplanar MOS technology. Components of the F8 family include the following devices:

- 1) The 3850 Central Processing Unit (CPU)
- 2) The 3851 Program Storage Unit (PSU)
- 3) The 3852 Dynamic Memory Interface (DMI)
- 4) The 3853 Static Memory Interface (SMI)
- 5) The 3854 Direct Memory Access (DMA)

Complete microprocessor based systems may vary in size and complexity from as little as two devices—the 3850 CPU and the 3851 PSU—to large systems incorporating the above five devices, plus any standard static and/or dynamic Random Access Memory (RAM) devices.

The following are some general characteristics of this microprocessor device set:

- 8-bit data organization
- 2 µs instruction cycle time
- Over 70 microprocessor instructions
- 64 general purpose registers in the CPU
- Binary and decimal arithmetic, and logic functions
- Up to 65,536 bytes of ROM and RAM, in any combination
- No need for special external interface devices
- Internal, programmable real time clocks
- Internal power on and reset logic
- Multi-level interrupt handling
- Clock and timing circuits

1.1 ASSUMED READER BACKGROUND

This manual has been written for logic designers with little or no background in programming.

The reader is assumed to understand the following:

- Binary, octal, binary coded decimal and hexadecimal number systems
- 2) Signed and unsigned binary arithmetic
- 3) Boolean logic
- 4) ASCII and EBCDIC character codes

For readers without the assumed background, a summary of this basic information is given in Appendix A.

1.2 SUPPORTING DOCUMENTATION

The following manuals provide additional information on the F8 microprocessor:

- F8 Circuit Data Book which provides electrical parameter data for all Fairchild F8 Microprocessor devices.
- F8 Timeshare Operating Systems Manual which explains how to assemble and debug F8 Microprocessor programs on NCSS and GE Timeshare Networks.
- F8 Circuit Reference Manual which describes the interactive timing and signal sequences which occur between devices in the F8 Microprocessor family.
- F8S and F8SEM Users Manuals which describe how to assemble and debug microprocessor programs on the F8S and F8SEM hardware modules.
- F8 Formulator Users and Reference Manuals which describe how to use and maintain Fairchild's F8 Formulator developmental hardware.

THE F8 MICROPROCESSOR SYSTEM

The purpose of a microprocessor system is to replace discrete logic; but in order to understand why a microprocessor system is effective as a logic design tool, it is first necessary to understand what is in a microprocessor system.

2.1 WHAT IS A MICROPROCESSOR?

After a product has been fabricated using discrete logic components, it consists of one or more logic cards; each card may be visualized as generating a variety of signals output at the card edge, based on signals input at the card edge. The logic devices on the card are specifically selected and sequenced to generate the required product.

If the same product is implemented using the F8 microprocessor, the F8 CPU and its five supporting devices can be made to function in the same way as any one of many millions of different discrete logic device combinations. In other words, the F8 CPU, optionally in conjunction with the supporting devices, has the capacity to duplicate the performance of any discrete logic design, limited only by speed considerations. F8 microprocessor systems have a 2 μ s instruction cycle time. The functions that will be performed by the F8 microprocessor system are established by a sequence of "instructions", stored in a memory device as a sequence of binary codes. Taken as a whole, the sequence of instructions are referred to as a "stored program".

2.2 SOME BASIC CONCEPTS

Any logic device may be reconstituted from some or all of the following basic functions:

- 1) Binary addition
- 2) The logical operations AND, OR and EXCLUSIVE-OR
- Shifts and rotates of binary digit sequences which are being interpreted as numerical entities (e.g., a byte = eight bits).

A general purpose logic device can be created by implementing the basic functions listed above on a single chip. If the single chip is to duplicate the performance of other logic devices, it must be provided with a sequence of instructions that enable the required logic in the proper order, plus as stream of data that is operated on by the specified logic. This is illustrated in Figure 2-1.

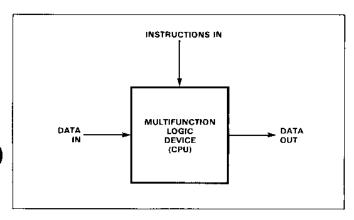


Fig. 2-1. Multifunction Logic Device

In order to function, the multifunction logic device will need the following parts:

- A) An Arithmetic Logic Unit (ALU), containing the necessary basic logic functions.
- B) A control unit, which decodes instructions and enables elements of the ALU, as needed.
- C) Registers to hold instruction codes and data, as needed.
- D) Data paths within the CPU, and between the CPU and external devices.

Parts A), B), C), and D) are the basic components of any Central Processing Unit (CPU). A CPU must be the focal point of any computer—maxi, mini or micro.

Referring to Figure 2-1, where do "instructions" and "data in" come from, and where will "data out" go? There are two possibilities: memory or external devices.

Refer to Figure 2-2. Memory is a passive depository of information where data or instruction codes may be stored. Memory must be divided into individually addressable locations, each of which can store one element of instruction code or one element of data. In an F8 system, each individually addressable location will be an 8-bit data unit (a byte), since the F8 is an 8-bit microprocessor.

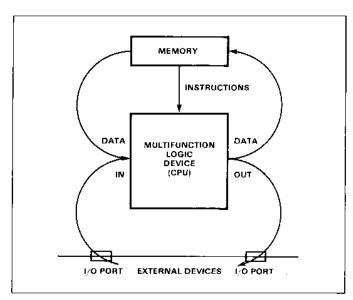


Fig. 2-2. Data and Instruction Paths in a Multifunction Logic Device

"External devices" refer to any data source or destination beyond the perimeter of the microprocessor system. Drawing an analogy with a logic card, "external devices" will refer to the world beyond the card edge connector. Data passes between the microprocessor system and external devices via Input/Output (I/O) ports.

2.2.1 Instructions, Programs, Data and Memory

For a microprocessor to perform any specified operation, it will receive and process a sequence of instructions. The sequence may be very long—numbering even into the thousands

of instructions. A sequence of instructions that can be taken as a unit is called a program; the purpose of this manual is to describe how a program is constructed out of a sequence of instructions.

Data may (and usually will) be stored in memory. In fact, the 256 possible combinations of eight binary digits (or byte) may represent any of the following types of information:

- 1) An instruction code
- 2) Numeric or address data that is part of an instruction's code
- Numeric or address data that is independent of instruction codes
- A coded representation of a letter of the alphabet, digit or printable character

It would be impossible to determine the content of any memory byte by random inspection. This does not cause problems, since a program will occupy one or more segments of contiguous memory bytes, and data resides in blocks of memory as assigned by the programmer.

2.2.2 Interrupts

The number of programs which may be stored in memory is limited only by the amount of memory available for program storage. If ten programs were stored in memory, by simply identifying one program, the same microprocessor system could be made to function in one of ten different ways.

If a microprocessor has more than one program available for execution, how is the one program which is to be executed identified? There are two separate and distinct ways in which a program may be identified for execution:

- A) Program identification may itself be a programmed function; for example, each program, upon completing execution, may identify the next program to be executed. The key to this method of program identification is that it is internally controlled, within the logic of the microprocessor system.
- B) Programs may be called into execution by external devices; this may happen even if another program is in the middle of execution. For example, take the simple case of a microprocessor that is recording data input by an external instrument; while receiving data from the external instrument, the microprocessor performs numerical operations on the collected data. Program executions are illustrated in Figure 2-3.

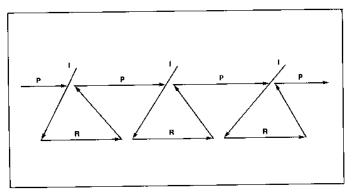


Fig. 2-3. Program P Being Interrupted to Execute Program R

In Figure 2-3, P represents the program performing numerical operations on the data. Data is collected by repeated execution of program R. Events occur as follows:

- 1) Program P is executing.
- 2) When the external instrument has data which it is ready to transmit, it sends an interrupt signal (I) to the microprocessor, along with the starting address of program R.
- 3) Upon receiving interrupt signal I, the microprocessor does some elementary "housekeeping"; for example, it saves the address of the program P instruction it was about to execute, plus any intermediate data being held in temporary storage registers.
- 4) The microprocessor completely executes program R.
- 5) Upon completion of program R execution, the microprocessor restores values saved in step 3, then continues program P execution from the point where interrupt I occurred. Thus execution of program P appears to have gone into "suspended animation" for the duration of program R execution.

The sequence of events illustrated in Figure 2-3 is quite common in microprocessor applications, and is called an external interrupt. Interrupt programming is described in Section 8.2.

2.2.3 Programmable Clocks

There are many microprocessor applications in which it is important that the microprocessor system be synchronized with the real time of the outside world. Such synchronization is accomplished using programmable clocks, which are registers that count at a known rate. When the shift register counts to zero, the event is marked by an interrupt (as decribed in Section 2.2.2); in this case the interrupt is defined as a "time out" interrupt. Since the rate at which the clock register counts will be known for any microprocessor system, setting a real time interval simply involves loading the register with the correct initial count.

2.2.4 Direct Memory Access

Notice from Figure 2-2 that data may be input to the microprocessor from memory or from an external device, via an I/O port.

It is easy to imagine how, in many applications, data will be transferred from an external device, via an I/O port and the CPU, to memory; the data will then be accessed from memory in the normal course of program execution.

It makes little sense to tie up the logic of the CPU while shunting data from an I/O port to memory; therefore, provisions are made for Direct Memory Access (DMA), whereby data is moved between memory and an "I/O port", bypassing the CPU entirely. The DMA "I/O port" is called a "DMA channel".

In order to implement DMA, the microprocessor system must have logic (outside the CPU) which provides the following three pieces of information:

- 1) A starting memory address for a data block.
- 2) A byte length for the data block.
- 3) The direction of the data movement.

If the microprocessor has this logic, data may be transferred between memory and an I/O port independent of, and in parallel with, unrelated CPU-memory operations.

2.2.5 A Complete Microprocessor System

To summarize, a complete microprocessor system will have the following logical components:

- A CPU, which is the multifunction logic device of the system.
- Memory (of various types and combinations), in which programs and data are stored.
- 3) Memory interface logic which identifies:
 - a) the next memory location which must be accessed to fetch instruction codes for the CPU, and
 - b) the memory location from which a byte of data will be read, or to which a byte of data will be written.

- I/O ports, through which bidirectional data passes between the microprocessor system and external devices.
- DMA logic, which provides a direct data path between memory and external devices, bypassing the CPU.
- 6) Interrupt logic, which causes the CPU to temporarily suspend current program execution. Along with each interrupt request signal, interrupt logic identifies the program which is to implement operations required by the source of the interrupt.
- Real time clock logic, which synchronizes the entire microprocessor system with the real outside world by generating interrupts at variably definable time intervals.

Figure 2-4 illustrates these seven logical components, with associated data flow paths.

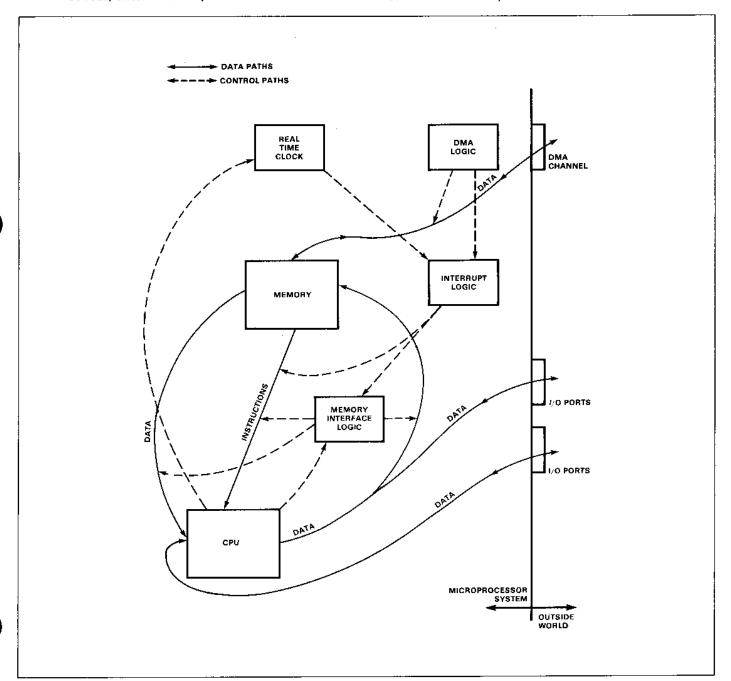


Fig. 2-4. Logical Components, Data Paths and Control Paths in any Microprocessor System

2.3 THE F8 SYSTEM

There is no one-for-one correspondence between the logical components of a microprocessor system, as illustrated in Figure 2-4, and the devices of the F8, or any other microprocessor product. In fact, it is counter-productive to extend the concept of isolating functions on separate devices because it reduces the flexibility of a microprocessor system to satisfy simple, as well as complex, applications needs. More than any other microprocessor product, the F8 combines many functions on single chips, thus allowing simple systems to be implemented with as few as two devices, and complex systems to be implemented using many devices.

Figure 2-5 illustrates the way in which F8 microprocessor system devices interconnect to give a variety of system configurations.

The simplest F8 system contains one 3850 CPU and one 3851 PSU.

Another very simple F8 system consists of one 3850 CPU, plus either one 3852 DMI interfaced to a single dynamic memory, or one 3853 SMI interfaced to a single static memory device.

A fully expanded F8 system may have one 3850 CPU, one 3852 DMI and one 3853 SMI device, up to four 3854 DMA devices, plus 3851 PSU and static or dynamic memory devices in any combination, providing not more than a combined total of 65,536 bytes of memory are directly addressed by the 3850 CPU. It is possible to address more than 65,536 bytes of memory using special techniques which are described in the F8 Circuit Reference Manual.

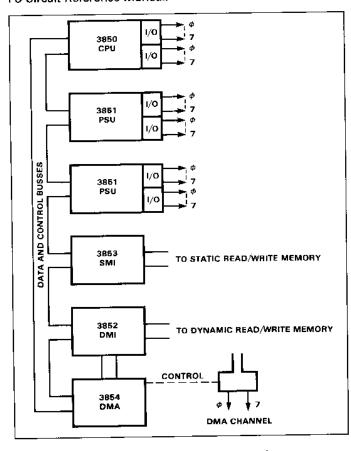
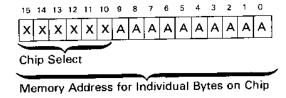


Fig. 2-5. F8 Microprocessor System Configurations

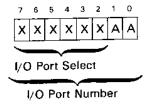
2.3.1 Chip and I/O Port Selection

Every 3851 PSU has two permanent select codes—a chip select code and an I/O port select code.

The 3851 PSU chip select code is a six digit binary number, which is always the highest six bits for memory addresses on that device:



The 3851 PSU I/O port select code is also a six digit binary number, and is independent of the chip select code. The I/O port select code is always the highest six bits for I/O port numbers on that device:



The 3852 DMI and 3853 SMI devices have a fixed (preassigned) I/O port select code, but have no on-board chip select code.

The dynamic and/or static memories associated with the 3852 DMI and 3853 SMI derive their select function from external logic. This allows the system designer complete freedom with respect to memory space partitioning.

Every F8 microprocessor system must have one memory device whose byte addresses start at 0; the first instruction executed when an F8 system is powered up is the instruction stored in memory byte 0.

2.4 THE 3850 CPU

Figure 2-6 illustrates the logical functions implemented on the 3850 CPU.

The heart of the F8 microprocessor system is the 3850 CPU, which contains data manipulation logic in an Arithmetic Logic Unit (ALU). Eight-bit instruction codes are decoded by a Control Unit (CU), which controls execution of logic internal to the 3850 CPU and generates signals controlling operations of other devices in the system.

2.4.1 Timing

System timing is illustrated in Figure 2-7. System timing is controlled by an external or internal clock, which provides clock pulses of not less than 500 ns and not more than $10\mu s$. In response to instruction codes, the CPU creates instruction timing cycles of either 4 or 6 clock pulses. The fastest instruction will execute in one short (4 clock pulse) cycle; the slowest instruction will execute in one short (4 clock pulse) cycle plus three long (6 clock pulse) cycles.

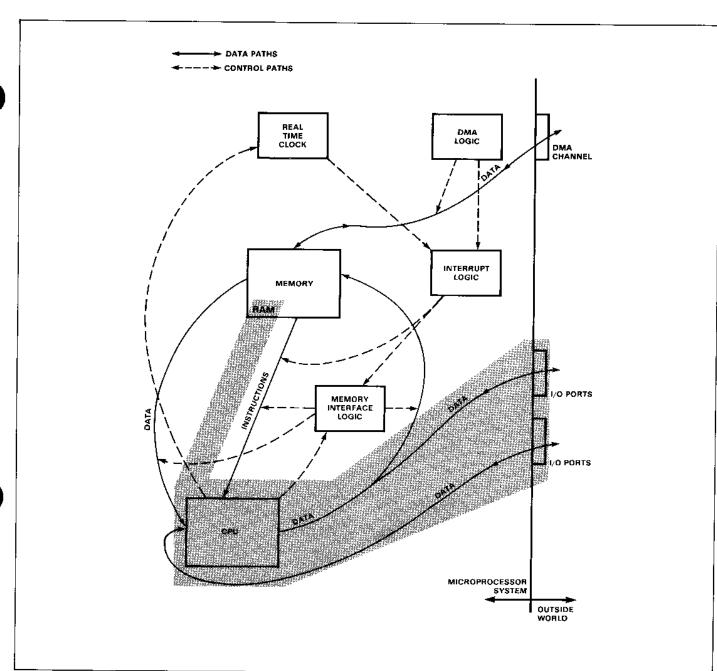


Fig. 2-6. Logical Functions of the 3850 CPU

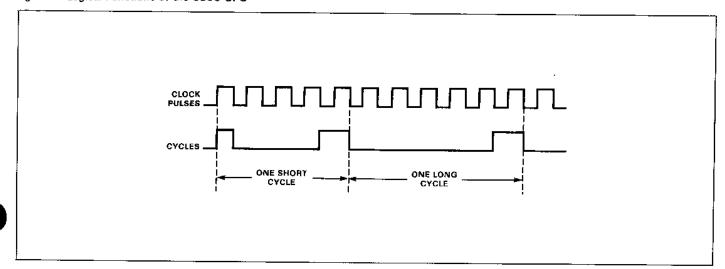


Fig. 2-7. Instruction Timing

2.4.2 CPU Registers

The 3850 CPU has an 8-bit Accumulator Register and a Scratchpad consisting of 64 8-bit registers. In addition there is a 6-bit Indirect Scratchpad Address Register (ISAR), which is used to address the scratchpad and a 5-bit Status Register (the W register), which identifies selected status conditions associated with the results of CPU operations. Figure 2-8 illustrates the CPU register.

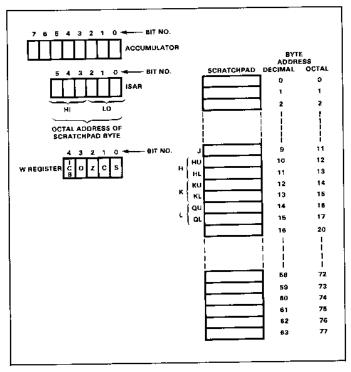


Fig. 2-8. 3850 CPU Programmable Registers

Data in the Accumulator may be manipulated by the ALU. Individual instructions allow the contents of the Accumulator to be operated on in a variety of ways. Data may be transferred between the Accumulator and other CPU registers, or between the Accumulator and data locations outside the CPU.

The Scratchpad is the principal depository of frequently accescessed data and, in small microprocessor configurations, may represent the system's only Read/Write Memory. Because the Scratchpad actually resides on the CPU, instructions that reference Scratchpad bytes execute in one short cycle; these are the fastest executing F8 instructions.

The first 16 Scratchpad bytes can be identified by instructions without using the ISAR. The remaining Scratchpad bytes are referenced via the ISAR; i.e., the ISAR is assumed to hold the address of the Scratchpad byte which is to be referenced. Observe that the first 16 bytes of the Scratchpad can also be referenced via the ISAR.

The ISAR should be visualized as holding two octal digits, Hi and LO. This division of the ISAR is important, since a number of instructions increment or decrement the contents of the ISAR when referencing Scratchpad bytes via the ISAR. This allows a sequence of contiguous scratchpad bytes to be easily referenced. However, only the low order octal digit (LO) is incremented or decremented; thus ISAR is incremented from 0'27' to 0'20', not to 0'30'. Similarly, ISAR is decremented

from 0'20' to 0'27', not to 0'17'. This feature of the ISAR greatly simplifies many program sequences, as will be described in Section 7.

Seven of the Scratchpad registers (9 through 15) have special significance. Data from register 9 may be moved directly between register 9 and the W register, bypassing the Accumulator. Registers 10 through 15 are connected to memory interface logic, as described in Sections 2.5, 2.6 and 2.7.

2.4.3 Status

A number of operations performed by the Arithmetic Logic Unit (ALU) generate results, selected characteristics of which are important to logic sequences. Table 2-1 summarizes the W register status bits, which are individually described next.

```
OVERFLOW = CARRY_7 \oplus CARRY_6

ZERO = \overrightarrow{ALU}_7 \ \overrightarrow{ALU}_6 \ \overrightarrow{ALU}_5 \ \overrightarrow{ALU}_4 \ \overrightarrow{ALU}_3 \ \overrightarrow{ALU}_2 \ \overrightarrow{ALU}_1 \ \overrightarrow{ALU}_0

CARRY = CARRY_7

SIGN = \overrightarrow{ALU}_7
```

Table 2-1. A Summary of Status Bits

SIGN

When the results of an ALU operation are being interpreted as a signed binary number, the high order bit (bit 7) represents the sign of the number (see Appendix A). At the conclusion of instructions that may modify the Accumulator bit 7, the S bit (W register bit 0) is set to the complement of the Accumulator bit 7.

CARRY

The C bit (W register bit 1) may be visualized as an extension of an 8-bit data unit; i.e., bit 8 of a 9-bit data unit. When two bytes are added and the sum is greater than 255, the carry out of bit 7 appears in the C bit. Here are some examples:

С	7	6	5	4	3	2	1	0
Accumulator contents:	0	1	1	0	0	1	0	1
Value added:								<u>0</u>
Sum: 0	1	1	0	1	1	0	1	1

There is no carry, so C is reset to 0.

С	7	6	5	4	3	2	1	0 ← Bit Number
Accumulator contents:	1	0	0	1	1	1	0	1
Value added:	1	1	0	1	0	0	0	1
Sum: 1	$\overline{\Omega}$	1	1	O	1	1	1	0

There is a carry, so C is set to 1.

ZERO

The Z bit (W Register bit 2) is set whenever an arithmetic or logical operation generates a zero result. The Z bit is reset to 0 when an arithmetic or logical operation could have generated a zero result, but did not.

Load instructions do not affect status bits.

a) The Accumulator contains 01101011. The value 00010101 is added to the Accumulator:

The result in the Accumulator is not zero, so the Z bit is reset to 0. (There is no carry, so C is reset to 0).

b) Next, the Accumulator contents are shifted left one bit position:

7 6 5 4 3 2 1 0 Bit number (before shift) shifted out 10 0 0 0 0 0 0 0 0 Shifted in after shift 0 0 0 0 0 0 0 0

Since the result in the Accumulator is now zero, the Z bit is set to 1.

c) Subsequently the value 1101111 is loaded into the Accumulator. Even though the Accumulator no longer contains zero, the Z bit remains set at 1 since an Accumulator load is neither an arithmetic nor a logical operation, therefore has no effect on the Z bit.

OVERFLOW

The high order Accumulator bit (bit 7) represents the sign of the number. When the Accumulator contents are being interpreted as a signed binary number, some method must be provided for indicating carries out of the highest numeric bit (bit 6 of the Accumulator). This is done using the O bit (W register bit 3). After arithmetic operations, the O bit is set to the EXCLUSIVE-OR of Carry Out of bits 6 and bits 7. This simplifies signed binary arithmetic as shown in Section 10.3 and in Appendix A. Here are some examples:

C 7 6 5 4 3 2 1 0 Bit Number

Accumulator contents: 1 0 1 1 0 0 1 1

Value added: 0 1 1 0 0 0 1

Sum: 1 0 0 1 0 0 1 0 0

There is a carry out of bit 6 and out of bit 7, so the O bit is reset to 0 (1 \oplus 1 = 0). The C bit is set to 1.

C 7 6 5 4 3 2 1 0 Bit Number

Accumulator contents: 0 1 1 0 0 1 1 1

Value added: 0 0 1 0 0 1 0 0

Sum: 0 1 0 0 0 1 0 1 1

There is a carry out of bit 6, but no carry out of bit 7; the O bit is set to 1 $(1 \oplus 0 = 1)$. The C bit is reset to 0.

When the Overflow bit is set, the magnitude of the number is too large for the 7-bit numeric field within the byte, and the sign bit has been destroyed. However, the 9-bit field made up of the Carry bit (high order) and the data byte give a valid 9-bit signed binary result.

ICB AND INTERRUPTS

External logic can alter the operations sequence within the CPU by interrupting ongoing operations, as described in Section 2.2.2. However, interrupts are allowed only when the ICB bit (W register bit 4) is set to 1; interrupts are disallowed when the ICB bit is reset to 0.

2.4.4 3850 Input/Output

The 3850 CPU communicates with the outside world in two ways:

To execute instructions, instruction codes must be input from the external storage device (probably a 3851 PSU) where they are being maintained. Data stored in a memory device may have to be loaded into the CPU in order to meet the requirements of the instruction being executed. This type of communication between the 3850 CPU and the outside world is of no immediate concern to an F8 programmer, since it involves data flows within the confines of the microprocessor system, and requires no special considerations beyond an understanding of instruction execution sequences.

Input/output programming, as the term is commonly used, refers to data transfers between the microprocessor system and logic beyond the microprocessor system. The 3850 CPU has two 8-bit, bidirectional ports, via which 8-bit parallel data may be transferred in either direction, between the 3850 CPU and logic external to the microprocessor system. The two 3850 CPU I/O ports are identified by the hexadecimal port addresses H'00' and H'01'.

2.5 THE 3851 PSU

Figure 2-9 illustrates the logical functions implemented on the 3851 PSU.

The 3851 PSU provides an F8 microprocessor system with 1024 bytes of Read Only Memory, 3851 memory is usually used to store instructions, but may also be used to store data that is read, but never altered. In addition, each 3851 PSU provides two 8-bit I/O ports, a programmable timer and external interrupt processing logic.

The 3851 PSU is the logic device which is modified and replaced to reflect a product's continuing engineering and field upgrades.

In microprocessor systems, instruction codes are usually stored in a PSU to prevent accidental erasure. As many as 64 3851 PSU's may be connected to one 3850 CPU, yet a single 3851 PSU interfaced to a 3850 CPU, provides a viable microprocessor system with the following capacities:

- 1024 bytes of program storage (on the 3851)
- 64 bytes of Read/Write Memory (on the 3850)
- 4 separately addressable, bidirectional I/O ports (2 on the 3850, 2 on the 3851)
- An external interrupt line
- A programmable clock

2.5.1 3851 Timing

Timing signals created by the 3850 CPU, and illustrated in Figure 2-7, control operation sequences in the 3851 PSU.

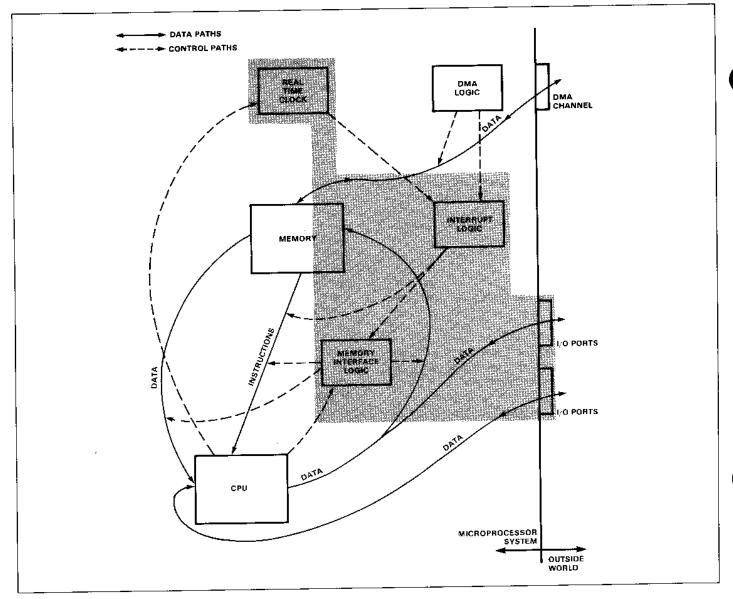


Fig. 2-9. Logical Functions of the 3851 PSU

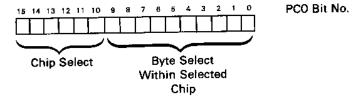
2.5.2 3851 Registers

In addition to 1024 bytes of ROM, the 3851 contains three 16-bit address registers, which are described next.

PROGRAM COUNTER (PCO)

This 16-bit register provides the address of the memory byte from which the next instruction code will be fetched for transmittal to the 3850 CPU. After each byte of instruction code is fetched, logic internal to the 3851 increments the contents of PCO to address the next memory byte.

Even though each 3851 PSU contains only 1024 bytes of memory, PCO preserves a 16-bit memory address. Thus PCO may be interpreted as follows:



Each 3851 device has a unique select code that is a permanent mask option; 3851 memory access logic is only activated when the six Chip Select bits of PCO match the 3851 select code. Thus, if more than one 3851 is present in an F8 system, every 3851 device's PCO register holds the address of the memory byte from which the next instruction code will be fetched for transmittal to the 3850 CPU; but an instruction fetch will actually be executed from one 3851 device only.

The PCO registers of the 3851 devices are logically connected to 3850 scratchpad bytes 12 and 13, designated as the K register, and bytes 14 and 15, designated as the Q register in Figure 2-8. Specific instructions allow the contents of the K or Q register to be loaded into every PCO register. Specific instructions allow the PCO registers' contents to be modified in order to control microprocessor logic sequences.

Note that in a correctly designed F8 microprocessor system, when there is more than one 3851 device, every PC0 register will always contain exactly the same address.

STACK REGISTER (PC1)

Every 3851 device has a 16-bit Stack Register, which is a buffer for the contents of PCO. This allows program execution sequence to be modified by changing the PCO registers' contents, while the previous contents of PCO are saved in PC1; thus programs may return to the prior instruction execution sequence.

The PC1 registers are logically connected to the 3850 scratchpad bytes 12 and 13, designated as the K register in Figure 2-8. Specific instructions allow the contents of the K register to be loaded into every PC1 register, or the PC1 registers' contents to be loaded into the K register.

DATA COUNTER (DC)

Every 3851 device has a 16-bit Data Counter register which contains the address of the memory byte (external to the 3850 CPU) from which data is to be accessed. For example, an instruction requiring a data byte to be loaded from external memory into the 3850 Accumulator will fetch the contents of the data byte addressed by the DC registers.

The DC registers are 16-bit registers, where the high order six bits (bits 15 to 10) are interpreted as chip select bits, and the low order nine bits (bits 9 to 0) provide the byte address.

The DCO registers are logically linked to the H and Ω registers in the same way that the PC1 registers are logically linked to scratchpad register K.

2.5.3 3851 Input/Output

Each 3851 PSU has two bidirectional, 8-bit I/O ports. Each port's address, using binary notation, is XXXXXXOO or XXXXXXO1, where the X binary digits are the device's unique I/O port select code. Note that every 3851 PSU has an I/O port select code and an independent chip select code.

2.5.4 3851 Local Timer and Interrupt

3851 programmable timer and interrupt logic are accessed via the binary port addresses XXXXXX11 and XXXXXX10, respectively; the X binary digits are the I/O port select codes described in Section 2.5.3.

The programmable timer port is a polynomial shift register which runs continuously, sending a signal to the interrupt control logic whenever the timer count equals zero.

Any numeric value between 0 and 255 may be loaded into the programmable timer port by an appropriate instruction code. If 255 (hexadecimal FF) is loaded into a timer port, the timer is stopped. Any other value loaded into a timer port is decremented once every 31 clock pulses (see Figure 2-7); therefore delays up to 7905 clock pulses may be programmed.

The local interrupt port is loaded by an appropriate instruction, with a control code; bits 0 and 1 of the control code are interpreted as follows:

Bit 1	Bit 0	Function
0	0	Disaflow all interrupts
0	1	Enable external interrupts
1	0	Disallow all interrupts
1	1	Enable timer interrupts;

If timer interrupts have been enabled and if the 3850 CPU has enabled interrupts (via the ICB status), then when the local timer decrements to 0, an interrupt request is transmitted to the 3850 CPU.

The way in which the local timer and interrupt ports are used is described in Section 8.3.

2.6 THE 3852 DYNAMIC MEMORY INTERFACE

Figure 2-10 illustrates the logical functions implemented on the 3852 DMI device.

The 3852 DMI device interfaces dynamic random access memory (e.g., Fairchild 3540 RAM) to a 3850 CPU. One 3852 DMI device interfaces up to 65,536 bytes of RAM memory to the 3850 CPU. However, recall that a combined maximum of 65,536 bytes of ROM and RAM may be addressed by the 3850 CPU unless special additional memory interfacing logic is added to the microprocessor system.

Only one 3852 DMI device will normally be present in an F8 microprocessor system.

The 3854 DMA device may be attached to the 3852 DMI device enabling data to be transferred between memory devices and any external device, bypassing the 3850 CPU.

2.6.1 3852 Timing

Timing signals created by the 3850 CPU, and illustrated in Figure 2-7, control operation sequences in the 3852 DMI.

2.6.2 3852 Registers

The 3852 DMI device has the same address registers as the 3851 PSU; however, the 3852 DMI has two Data Counter registers. Thus the 3852 has one Program Counter (PCO), one Stack Pointer (PC1) and two Data Counters (DCO and DC1).

There are two differences between the way in which 3852 registers and 3851 registers are used.

The 3852 has no chip select mask. This is because there will only be one 3852 device in a microprocessor system, and it passes the entire PCO address to attached RAM devices; the attached RAM devices interpret part of the PCO address as chip select lines.

Data Counter DC1 is a temporary storage buffer for Data Counter DC0. An instruction switches the DC0 and DC1 registers' contents; since 3851 PSU have no DC1 register, this switch instruction has no effect on 3851 PSU. Thus it is possible for the 3852 DMI Data Counter (DC0) to have contents which differ from 3851 PSU. Recall that the Data Counters are logically connected to the H and Q scratchpad registers within the 3850 CPU, so that Data Counters' contents may be transferred to the H or Q registers. The fact that the 3851 DC0 register and the 3852 DC0 register may not hold the same addresses may present a problem, since the contents of a Data Counter is transferred to the H or Q registers from any device with a device select code corresponding to the current DC0 contents.

Simultaneous use of 3851 PSU and 3852 DMI devices is discussed in detail in Section 7.2.

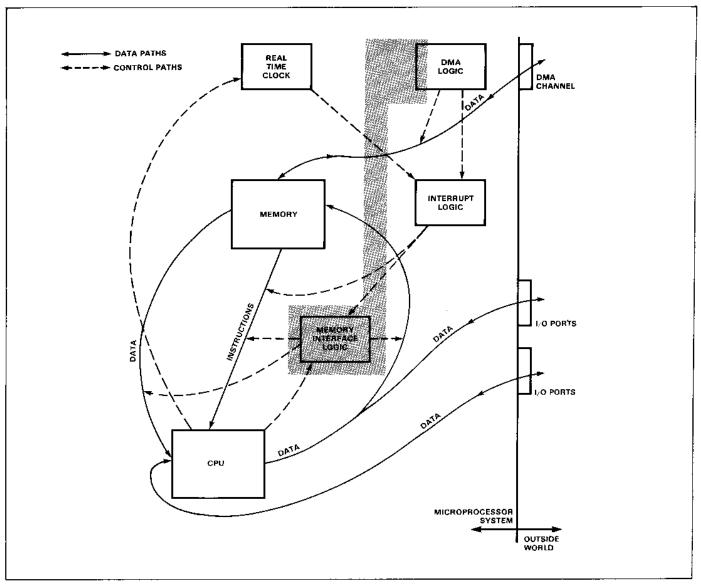


Fig. 2-10. Logical Functions of the 3852 DMI Device

2.6.3 3852 Direct Memory Access and Memory Refresh

The 3852 DMI device has two addressable ports which are used to enable direct transfer of data between memory devices and external devices. This transfer is referred to as Direct Memory Access (DMA), and requires the presence of the 3854 DMA device. For a discussion of DMA see Sections 2.2.4, 2.8 and 8.4.

The two addressable 3852 ports use hexadecimal addresses H'OC' and H'OD'. Port H'OC' requires a control byte to be loaded for interpretation as follows:

Bit No.

- 0 1 = DMA not allowed 0 = DMA allowed
- 1 1 = Refresh memory 0 = No memory refresh
- 2 1 = Refresh every fourth write cycle
 - 0 = Refresh every eighth write cycle

Another version of the 3852 DMI device, referred to as the SL 31116 device, uses port addresses H'EC' and H'ED' instead of H'OC' and H'OD'. This allows 3852 DMI and 3853 SMI devices to be used in the same microprocessor system.

2.7 THE 3853 STATIC MEMORY INTERFACE

Figure 2-11 illustrates the logical functions implemented on the 3853 SMI device.

The 3853 SMI device is similar to the 3852 DMI device, described in Section 2.5. There are four important differences, which are described below.

- The 3853 SMI device interfaces static memory (such as the Fairchild 2102 RAM) to a 3850 CPU.
- The 3853 SMI does not have a DMA interface capability.
- 3) The 3853 SMI has local timer and interrupt control, as described for the 3851 PSU in Section 2.4.4. However, the 3853 local timer port address is H'0F' and the interrupt control port address is H'0E'.
- 4) The 3853 SMI has two additional ports, addressed H'OC' and H'OD', which are programmable interrupt vector registers. The importance and use of these registers is discussed in Section 8.2.

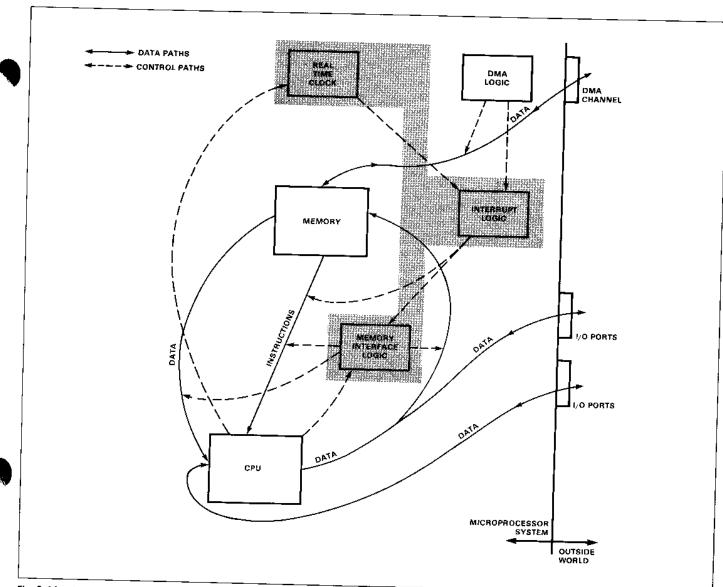


Fig. 2-11. Logical Functions of the 3853 SMI Device

Since the 3853, like the 3852, has two Data Counter registers, there are similar programming consequences, as described in Section 7.2.

2.8 THE 3854 DIRECT MEMORY ACCESS

Figure 2-12 illustrates the logical functions implemented on the 3854 DMA device.

The 3854 DMA device, in conjunction with the 3852 DMI device, sets up a data channel between a peripheral device and the memory associated with the DMI. DMA data transfers occur during the second part of each instruction cycle, therefore program execution speed is in no way degraded by parallel DMA data transfers. The concept of DMA data transfers is described in Section 2.2.4.

There may be up to four 3854 DMA devices in one micro-processor system.

Any external device may be attached to a 3854 DMA device. Also, two microprocessor systems may communicate with each other via a DMA device. For a description of how various DMA operations are programmed, see Section 8.4.

2.8.1 3854 Registers

The 3854 has three internal registers, addressed as four separate I/O ports. Addresses of the four I/O ports associated with the three 3854 registers are given in Table 2-2. The three registers are described next.

FUNCTION OF I/O PORT	FIRST 3854	SECOND 3854	THIRD 3854	FOURTH 3854
Address, L.O.				
Byte (BUFA)	FO	F4 :	F8	FC
Address, H.O.				'
Byte (BUFB)	F1	F5 i	F9	FD
Count, L.O.		_		
Byte (BUFC)	F2	F6	FA	FE
Count, H.O.				
Four bits, and	F3	F7	FB	FF
Control* (BUFD)				•••

^{*}The low order four bits of this port constitute the high order four bits of the byte count. The high order four bits of this port constitute the function code.

Table 2-2. Hexadecimal Addresses of Four I/O Ports Used as Registers by Four 3854 DMA Registers.

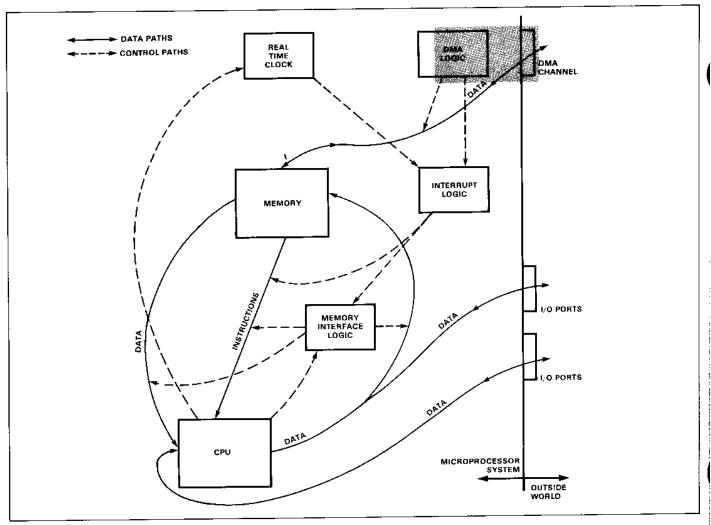


Fig. 2-12. Logical Functions of the 3854 DMA Device

BUFA, BUFB, BUFC and BUFD are buffer names used in Section 8.4.2, which describe DMA programming.

ADDRESS REGISTER

This is a 16-bit register which holds the address of the next memory byte to be accessed for a DMA data transfer.

Before a DMA operation is initiated, the beginning memory address for the data block which is to be transferred must be loaded (using appropriate F8 instructions) into the two ports set aside as the address register. As each data byte is transferred (input or output), the contents of the address register are automatically incremented.

BYTE COUNT REGISTER

This is a 12-bit register which acts as a counter, allowing blocks of up to 4096 data bytes to be transferred during a DMA operation. As described in Section 2.8.2, it is possible to execute DMA transfers without using the Byte Count register.

If the Byte Count register is in use, it is decremented as each byte of data is transferred, until it is decremented to 0; data transfer then stops.

CONTROL REGISTER

This is a 4-bit register which controls DMA operations as described next.

2.8.2 DMA Control Codes

The Control Register has four bits which control DMA operations as follows:

Bit 7 - ENABLE

This bit must be set to 1 in order to initiate a DMA operation; it is automatically reset to 0 when the DMA operation has run to completion.

Bit 6 - DIRECTION

If this bit is 0, data is transferred from main memory to the external device. If this bit is 1, data is transferred from the external device to main memory.

Bit 5 - INDEF

If this bit is 0, the Byte Count register controls the DMA transfer, which halts when the Byte Count register is decremented to 0. If this bit is 1, the Byte Count register is ignored and DMA transfer continues until the ENABLE bit is reset to 0 under program control.

Bit 4 - HIGHSPEED

If this bit is 0, the external device controls the rate at which data is transferred. If this bit is set to 1, a data byte will be transferred during every available DMA time slot; the external device must be capable of transmitting or receiving the data at the execution cycle speed of the F8 system.

F8 PROGRAMS

Individual instructions of the F8 assembly language instruction set exercise all of the capabilities of every device described in Section 2. Before studying individual instructions, however, it is necessary to understand what a program is, how a program is written, and how the written program becomes a PSU that drives the microprocessor system.

3.1 FLOWCHARTING

An application which is to be implemented using a microprocessor is specified using a flowchart; this differs from hardware logic diagrams only in the symbols used and the operations specified at each mode. The following four symbols will usually be sufficient in any microprocessor program flowchart:

1) Beginning and End

A program may have one or more initiation or termination points, identify each with the symbols:

START or STOP

2) Internal operations

Enclose words in a rectangular box to identify each step of a program. Here is an example:

Increment byte count

3) I/O operations

Use a parallelogram to identify I/O operations. Here is an example:

Input next data byte from I/O port 0

4) Decisions

Use a diamond to identify decisions. Here is an example:



Figure 3-1 flowcharts a very simple program that moves data from one buffer in RAM to another buffer in RAM.

Figure 3-2 flowcharts a program that performs a multibyte addition. Observe that arrows identify the possible logic flow paths.

3.2 ASSIGNING MEMORY

Having flowcharted an entire application, the next step is to identify and name every buffer and variable to be referenced by the program. Names must conform to the rules of symbol syntax, described in Section 4.2.3., and will be used by the program to specify individual buffers and variables.

Before starting to write a program, assign space in scratchpad and in ROM or RAM memory for each buffer and every variable. These assignments will probably change before the program is finalized; nevertheless, it is important to have a clearly mapped data area at all times. Note also that the same scratchpad or RAM memory bytes may be used by different variables within one program, providing the different uses never overlap.

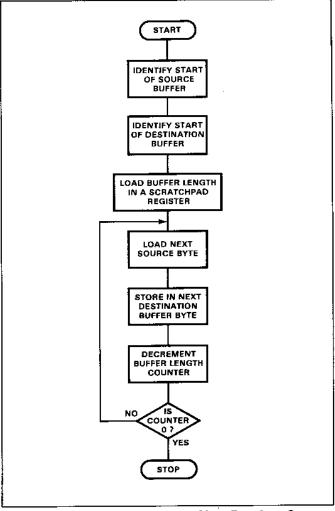


Fig. 3-1. Flowchart for a Program to Move Data from One RAM Buffer to Another

Recall that scratchpad registers are addressed by the ISAR register in the 3850 CPU, and are numbered from 0 to 63. ROM and RAM are addressed by the DCO register when accessing data. (Every 3851, 3852 and 3853 device has its own DCO register.) ROM and RAM bytes have addresses numbered from 0 to 65535.

With regard to addresses, note the following:

- The first 64 bytes of ROM/RAM may have addresses that are the same as the Scratchpad Register addresses. No confusion is possible since the scratchpad is addressed via ISAR while ROM and RAM are addressed via DCO.
- 2) ROM and RAM byte addresses must not overlap.
- 3) Memory addresses must be contiguous within one device, but need not be contiguous from device to device. For example, three 3851 PSU may decode addresses from 0 to 1023, from 2048 to 3071, and from 3072 to 4095. Addresses 1024 to 2047 may be unused. (Recall that each 3851 PSU contains 1024 bytes of memory.)

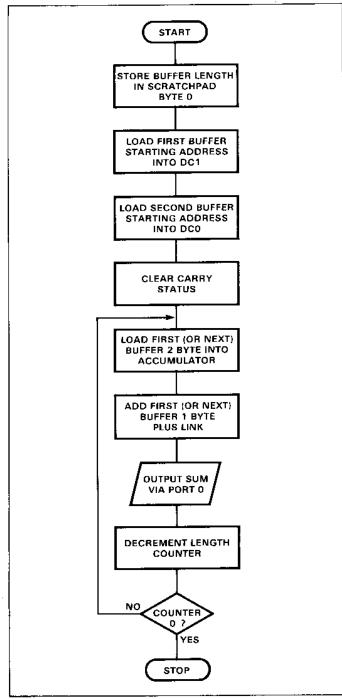


Fig. 3-2. Flowchart for Program to Add Two Multibyte Numbers and Output the Result

3.3 SOURCE AND OBJECT PROGRAMS

What eventually makes an F8 microprocessor system perform its assigned tasks is a sequence of binary digits, stored in memory and called an object program.

Since the F8 microprocessor accesses memory in 8-bit (or 1-byte) units, the binary digits of an object program are, by convention, collected into 8-bit units which are represented on paper as two hexadecimal digits (each hexadecimal digit is equivalent to four binary digits).

Upon examining the contents of any individual byte of memory, it would be impossible to determine what the eight binary

digits contained by the memory byte represented. A memory byte could hold any of the following types of information:

- An instruction code which the 3850 CPU is supposed to interpret as an instruction.
- Binary data which may be unsigned (representing numbers between 0 and 255) or signed (representing numbers between -128 and +127).
- Data, as in 2) above, which provide specific information needed by an instruction code as in 1) above.
- 4) Data which are to be interpreted as representing a character that may be displayed or printed. Character codes are given in Appendix B.

How, then, will an F8 system pick its way through the various types of data which may be found stored in memory?

The program counter register (PCO) which is included in every 3851, 3852 or 3853 device, will at all times contain the address of the next memory byte whose content is to be interpreted by the 3850 CPU as an instruction code. When an F8 system is first powered up, the program counter is initialized at zero. Therefore, the contents of the memory byte with address 0 will be interpreted as the first instruction code to be executed. PCO also addresses data bytes of type 3.

Whenever the content of a memory byte is to be interpreted as data of type 2 or 4, the address of the memory byte is contained in the data counter registers (DCO), which are also present on every 3851, 3852 or 3853 device.

It is not easy to immediately understand that the 3850 CPU is able to pick its way through object program numeric codes, as stored in memory, by suitably manipulating the program counter and data counter register contents; but fortunately, such understanding is not necessary in order to write F8 programs. In fact, even though microprocessor programs could be created directly as a sequence of hexadecimal digits, the potential for making errors when writing such programs is so overwhelming, that were an alternative method not available, the computer industry would never have gotten off the ground. The alternative is to write source programs.

A source program is a program written in a programming language. In the case of the F8, this manual describes what is called an assembly language. A programming language represents data and instruction sequences in a manner which is meaningless to a microprocessor but easily read and understood by a human.

Look at Figure 3-3. Upon first inspection, the part of the figure identified as a source program will not make much sense; the purpose of this manual is to explain how such source programs are written. Nevertheless, it is immediately evident that the source program is potentially much easier to read and understand than the equivalent object program.

The process of converting a source program to an object program is automatic and is handled by an assembler which is, itself, a computer program. The assembler interprets a source program, character-by-character, then generates an equivalent object program in a form that can be loaded into an F8 microprocessor system memory and executed.

		BUFA BUFB	EQU EQU ORG	H'0800' H'08A0' H'0100'	SET THE VALUE OF SYMBOL BUFA SET THE VALUE OF SYMBOL BUFB
0100 0101 0102	2A 08 00	ONE	CDI	BUFA	SET DCO TO BUFA STARTING ADDRESS
0103	2C	TWO	XDC		STORE IN DC1
0104	2A	THREE	DCI	BUFB	SET DC0 TO BUFB STARTING ADDRESS
0105	80				
0106	Α0				
0107	20	FOUR	LI	H,80,	LOAD BUFFER LENGTH INTO ACCUMULATOR
0108	80				
0109	51	FIVE	LR	1, A	SAVE BUFFER LENGTH IN SCRATCHPAD BYTE 1
010A	16	LOOP	LM		LOAD CONTENTS OF MEMORY BYTE ADDRESSED BY DCO
010B	2C	\$IX	XDC		EXCHANGE DC0 AND DC1
010C	17	ŞEVEN	ST		STORE ACCUMULATOR IN MEMORY BYTE ADDRESSED BY DCO
010D	2Ç	EIGHT	XDC		EXCHANGE DC0 AND DC1
010E	31	NINE	DS		DECREMENT SCRATCHPAD BYTE 1
010F	94		BNZ	LOOP	IF SCRATCHPAD BYTE 1 IS NOT ZERO, RETURN TO LOOP
0110	F9				
<u> </u>	<u> </u>		END		
			-		
					A COURCE BROCEANA
					A SOURCE PROGRAM
	- 1				

The Equivalent Object Program, represented as hexadecimal numbers.

Hexadecimal address of memory byte in which object program byte is to be stored.

Fig. 3-3. Source and Object Programs

After the assembler has created the object program equivalent of a source program, it will print its results, outputing a program listing. The program listing provides information used to detect errors in a source program.

The rest of this manual explains how source programs are written as follows:

Every line of a source program constitutes one instruction. In Section 4, the various parts of an instruction are defined.

Section 5 and 6 define two classes of instructions used by the F8 assembly language. The consequences of every executable instruction's execution are defined.

Section 7 describes how individual instructions are combined in order to create a program. Therefore, the source program in Figure 3-3 will not be meaningful until you have completed reading Section 7.

Section 8 explains how programs should be written to access the various input and output features of the F8 microprocessor system.

In summary, the process of writing an F8 program follows these steps:

- 1) Using pencil and paper, write a source program.
- 2) Enter the source program, as text, into the computer system being used to develop F8 object programs.
- 3) Assemble the source program entered in Step 2, and thus create an object program. This step merely involves executing a program called the Assembler, identifying the source program and assigning a name to the object program.
- 4) If the source program contains illegal steps, they will be identified in Step 3. Treating the source program as text, edit out the errors, then return to Step 3. If there are no errors indicated at the end of Step 3, go on to Step 5.
- 5) Using appropriate Fairchild provided debugging aids, run the program created in Step 4 in order to find logic errors. If errors are found, correct them in the source program and return to Step 3. When there are no errors, the program is complete.

This manual provides information needed to perform Step 1. The F8 Timeshare Operating Systems Manual provides information needed for Steps 2 through 5.

During Step 3, the program listing is printed out on a line printer or time share terminal. The program listing shows the source and equivalent object program instructions, as well as additional, optional material that may be specified using assembler directives described in Chapter 5. Use the program listing to visually check a program; mark on the program listing all changes that must be made to the source program.

ASSEMBLY LANGUAGE SYNTAX

A very specific set of rules apply to the way in which an assembly language source program is written.

An assembly language program consists of a number of instructions, each of which occupies one line of text. There are four parts (or fields) to an instruction; one or more fields may contain non-blank information. Definite rules cover the characters that may be used in an instruction and how each character will be interpreted, depending on in which field the character appears.

The rules covering the way in which assembly language source programs are written are referred to collectively as the syntax of the assembly language. Assembly language syntax will be described with reference to the data moving program flowcharted in Figure 3-1 and illustrated in Figure 3-3.

4.1 INSTRUCTION TYPES

There are three types of source program statements: comments, executable instructions and assembler directives.

4.1.1 Comments

Comment instructions are used to insert remarks in the program in order to identify the program, separate program sections or make the source program easier to follow. A comment instruction does not have any computer related function, nor does it generate any object code; therefore, there is no restriction on its format or characters. An asterisk (*) character in column 1 designates the line of text as a comment instruction. Following the asterisk, there can be up to 71 characters of comment. Figure 4-1 illustrates comment lines in a source program.

4.1.2 Executable Instructions

Executable instructions are the steps that implement the procedure being programmed. For every executable instruction, the assembler generates one, two or three bytes of object code.

4.1.3 Assembler Directives

Assembler directives provide the assembler with additional information about the program. They are used to control the assembly process and in some cases cause data, which is included in the object code, to be generated.

4.2 INSTRUCTION FIELDS

Executable instructions and assembler directives have the following four fields:

- 1. Label field
- 2. Mnemonic field
- 3. Operand field
- 4. Comment field

Executable instructions and assembler directives must be formatted in a specific manner in order to be properly interpreted by the F8 Assembler. This means that each part of a source program instruction must be placed in its designated position or "field".

4.2.1 Label Field

The label field provides a means for assigning a name to a specific instruction. Any valid symbol (see Section 4.3.2) may be used in the label field. The label field begins in column 1 and may have any length; however, only the first four char-

		BUFA	EQU	H'0800'	SET THE VALUE OF SYMBOL BUFA
		BUFB	EQU	H'08A0	SET THE VALUE OF SYMBOL BUFB
	191207		ORG	H'0100'	
			N. COMMING		
	***				MOVES DATA FROM ONE 128 BYTE TTE BUFFER
		DUTTE	n IV ANUI	150 U	G BUTTET
				territoria.	
0100	2A	ONE	DCI	BUFA	SET DCO TO BUFA STARTING ADDRESS
0101	08				
0102	00				
0103	2C	TWO	XDC		STORE IN DC1
0104	2A	THREE	DCI	BUFB	SET DCO TO BUFB STARTING ADDRESS
0105	08				
0106	ΑO				
0107	20	FOUR	LI	H'80'	LOAD BUFFER LENGTH INTO ACCUMULATOR
0108	80				
0109	51	FIVE	LR	1,A	SAVE BUFFER LENGTH IN SCRATCHPAD BYTE 1
010A	16	LOOP	LM		LOAD CONTENTS OF MEMORY BYTE ADDRESSED BY DCO
010B	2C	SIX	XDC		EXCHANGE DCO AND DC1
010C	17	SEVEN			STORE ACCUMULATOR IN MEMORY BYTE ADDRESSED BY DC0
010D 010E	2C 31	EIGHT NINE	XDC DS	1	EXCHANGE DC0 AND DC1 DECREMENT SCRATCHPAD BYTE 1
010E	94	HINE	BNZ	LOOP	IF SCRATCHPAD BYTE 1 IS NOT ZERO, RETURN TO LOOP
0110	FA		DITE	LOOP	IF SCHATCHFAD BYTE 1 IS NOT ZERO, RETURN TO LOUP
0110			END		
			LITE		

Fig. 4-1. Four Comment Lines (Shaded) in a Source Program

acters are recognized by the assembler. The label field is terminated by a blank character. Figure 4-2 identifies label fields.

Label fields are frequently optional. With reference to Figure 4-2, notice that only three instruction labels, BUFA, BUFB and LOOP are necessary; they are the only labels referenced by other instructions.

4.2.2 Mnemonic Field

The mnemonic field contains the Operation Code (op code), which identifies the operation to be performed. There are two classes of operations accepted by the Assembler:

- 1. Assembler directives (Section 5)
- 2. CPU instructions (Section 6)

The mnemonic field may begin in any column other than column 1, and is terminated by a blank space. Figure 4-3 identifies mnemonic fields in a program.

In Figure 4-3, assembler directives are identified; notice that these assembler directives generate no object code.

4.2.3 Operand Field

The operand field consists of additional information (e.g., parameters, addresses) required by the Assembler to interpret the mnemonic field completely. The operand field may contain a symbol or expression (see Sections 4.3.2 and 4.3.4). The operand field must be separated from the mnemonic field by at least one blank; also, the operand field must be terminated by a blank. Figure 4-4 identifies the operand fields of a program. Notice that many instructions require no information in the operand field.

Instruction FOUR in Figure 4-4 illustrates the function served by operand fields. When executed, this instruction causes the byte value specified in the operand field to be loaded into the 3850 CPU accumulator register. In response to the source program instruction, the assembler generates an object program byte of H'20' representing the mnemonic "LI", the numeric value in the operand field is placed, by the assembler, in the next object program byte.

4.2.4 Comment Field

The comment field is optional and provides additional information that makes the source program easier to read. This

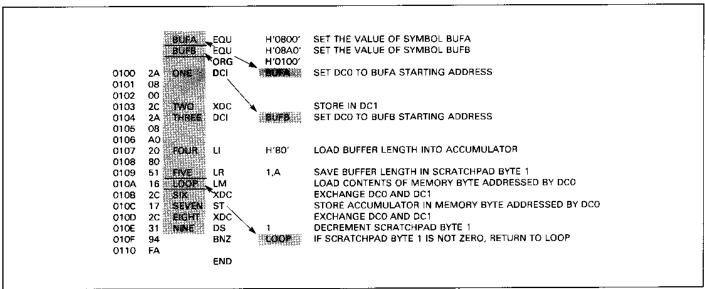


Fig. 4-2. Label Fields (Shaded) in a Source Program

Assembler		BUFA	EQU	H'0800'	SET THE VALUE OF SYMBOL BUFA
Directives	ĺ	BUFB	EQU ORG	H'08AD' H'0100'	SET THE VALUE OF SYMBOL BUFB
0100	2A	ONE	DCI	BUFA	SET DC0 TO BUFA STARTING ADDRESS
0101	08				
0102	00				
0103	2C	TWO	XDC		STORE IN DC1
0104	2A	THREE	pci	BUFB	SET DC0 TO BUFB STARTING ADDRESS
0105	08				
0106	A0				
0107	20	FOUR	LF .	H'80'	LOAD BUFFER LENGTH INTO ACCUMULATOR
0108	80				
0109	51	FIVE	LR	1,A	SAVE BUFFER LENGTH IN SCRATCHPAD BYTE 1
010A	16	LOOP	LM		LOAD CONTENTS OF MEMORY BYTE ADDRESSED BY DC0
010B	2C	SIX	XDC		EXCHANGE DC0 AND DC1
0100	17	SEVEN	ST		STORE ACCUMULATOR IN MEMORY BYTE ADDRESSED BY DCO
0100	2C	EIGHT	XDC		EXCHANGE DC0 AND DC1
010E	31	NINE	DS	1	DECREMENT SCRATCHPAD BYTE 1
010F	94		BNZ	LOOP	IF SCRATCHPAD BYTE 1 IS NOT ZERO, RETURN TO LOOP
0110	FA		46.00		
Assembler	1	*********	END		
Directive	.22230400	??222XXXX	*127288886444		. ALLES 2179 TO 1 - 15 TO 12 TO 1
	L		Object Pro-	oram	

Fig. 4-3. Mnemonic Field (Vertical Shaded) in a Source Program

field is ignored by the Assembler and generates no object code. The comment field must be separated from the operand field (or the mnemonic field if there is no operand field) by at least one blank; it continues to the end of the text line.

Figure 4-5 identifies the comment fields of a program.

4.2.5 Aligning Fields

Figure 4-6 illustrates the source program of Figures 4-1 to 4-5, with a single space code separating each field of every instruction.

Clearly the program in Figure 4-6 is hard to read. For clarity it is recommended that all fields be aligned within character positions of every line; here is one possibility:

Label field: Characters 1 to 6
Mnemonic field: Characters 7 to 11
Operand field: Characters 12 to 19
Comment field: Characters 20 to 72

BUFA EQU H'0800' SET THE VALUE OF SYMBOL BUFA
BUFB EQU H'08A0' SET THE VALUE OF SYMBOL BUFB
ORG H'0100'
ONE DCI BUFA SET DCO TO BUFA STARTING ADDRESS
TWO XDC STORE IN DC1
THREE DCI BUFB SET DCO TO BUFB STARTING ADDRESS
FOUR LI H'80' LOAD BUFFER LENGTH INTO ACCUMULATOR
FIVE LR 1,A SAVE BUFFER LENGTH IN SCRATCHPAD BYTE 1
LOOP LM LOAD CONTENTS OF MEMORY BYTE ADDRESSED BY DCO
SIX XDC EXCHANGE DCO AND DC1
SEVEN ST STORE ACCUMULATOR IN MEMORY BYTE ADDRESSED BY DCO
EIGHT XDC EXCHANGE DCO AND DC1
NINE DS 1 DECREMENT SCRATCHPAD BYTE 1
BNZ LOOP IF SCRATCHPAD BYTE 1 IS NOT ZERO, RETURN TO LOOP
END

Fig. 4-6. A Source Program with Unaligned Fields

		BUFA	EQU	H'0800'	SET THE VALUE OF SYMBOL BUFA
		BUFB	EQU	H'08AD'	SET THE VALUE OF SYMBOL BUFB
			ORG	H'0100'	THE THEOLOG OF THEOLOGO
0100	2A	ONE	DCI	BUFA	SET DC0 TO BUFA STARTING ADDRESS
0101	08			T .TC:::::	del boo to bolk bikitillo Applicos
0102	00				
0103	2C	TWO	XDC		STORE IN DC1
0104	2A	THREE	DCI	BUFB	
0105	08	ITINEE	DCI	DUTO	SET DC0 TO BUFB STARTING ADDRESS
	-				
0106	Α0				
0107	20	FOUR	LI	H'80'	LOAD BUFFER LENGTH INTO ACCUMULATOR
0108	80				
0109	51	FIVE	LR	1,A	SAVE BUFFER LENGTH IN SCRATCHPAD BYTE 1
010A	16	LOOP	LM	110000000000000000000000000000000000000	LOAD CONTENTS OF MEMORY BYTE ADDRESSED BY DCO
010B	2C	SIX	XDC		EXCHANGE DC0 AND DC1
010C	17	SEVEN	ST		STORE ACCUMULATOR IN MEMORY BYTE ADDRESSED BY DCO
010D	2C	EIGHT	XDC		EXCHANGE DC0 AND DC1
010E	31	NINE	DS	1	DECREMENT SCRATCHPAD BYTE 1
010F	94		BNZ	LOOP	IF SCRATCHPAD BYTE 1 IS NOT ZERO, RETURN TO LOOP
0110	FA				
			END		

Fig. 4-4. Operand Fields (Shaded) in a Source Program

		BUFA	EQU	H,0800,	SET THE VALUE OF SYMBOL BUFA
		BUFB	EQU	H'08A0'	SET THE VALUE OF SYMBOL BUFB
			ORG	H'0100'	
0100	2A	ONE	DCI	BUFA	SET OCO TO BUFA STARTING ADDRESS
0101	08				
0102	00				
0103	2C	TWO	XDC		STORE IN DC1
0104	2A	THREE	DCI	BUFB	SET DCO TO BUFB STARTING ADDRESS
0105	08				
0106	A0				
0107	20	FOUR	Li	H'BO'	LOAD BUFFER LENGTH INTO ACCUMULATOR
0108	80				
0109	51	FIVE	LR	1,A	SAVE BUFFER LENGTH IN SCRATCHPAD BYTE I
010A	16	LOOP	LM		LOAD CONTENTS OF MEMORY BYTE ADDRESSED BY DCD
010B	2C	SIX	XDC		EXCHANGE DCD AND DC1
010C	17	SEVEN	ST		STORE ACCUMULATOR IN MEMORY BYTE ADDRESSED BY DCO.
010D	2C	EIGHT	XDC		EXCHANGE DCC AND DC1
010E	31	NINE	DS	1	DECREMENT SCRATCHPAD BYTE 1
010F	94		BNZ	LOOP	IF SCRATCHFAD BYTE I IS NOT ZERO, RETURN TO LOOP
0110	FA				
			END		

Fig. 4-5. Comment Fields (Shaded) in a Source Program

4.3 LANGUAGE COMPONENTS

4.3.1 Valid Characters

The F8 Assembler accepts all characters available on an input terminal as valid characters. Alphabetic (A-Z), numeric (0-9), and special (all other terminal characters) characters are valid when correctly used; in other words, there is no character which will always be invalid.

Some characters have been assigned special meaning; the use of these special characters is therefore restricted, as described in the following sub-sections, and summarized in Table 4-1.

Restricted Character	Function	Example
D H B O C T * * * * * * * * * * * * * * * * * *	Specify decimal constants Specify hexadecimal constants Specify binary constants Specify octal constants Specify character constants Specify timer counts Current memory location Multiplication sign Exponentiation sign Addition sign Subtraction sign Division sign	D'1234' H'123A' B'10011101' O'23714' C'VALID' T'123' *+3 (VAL*2) (VAL*2) (VAL-2) (VAL-2)
()	Beginning of an expression End of an expression Separate operands	(VAL+2) (VAL+2) A,1

Table 4-1. A Summary of Restricted Characters

Restricted characters may be used in any way that does not directly conflict with the restricted use.

4.3.2 Constants

Constants represent quantities or data that do not vary in value during the execution of a program. The syntax for constants' representation is described below.

DECIMAL

A decimal number consists of a string of from one to five numeric characters. The number may be preceded by a minus "-" sign but no blanks are allowed within the number. The value of a decimal digit must fall in the range +32767 to -32768. Optionally, decimal numbers may be enclosed between single quotes, preceded by a D character.

Examples:

Valid	Invalid	Reason invalid
12	123456	Too many digits
-123	123-	Invalid character
12345	12.3	Invalid character
-5432	1263	Invalid character
23456	65432	Above +32767
D'12'	′12′D	D does not precede number in quotes
D'23456'	D'65432'	Above +32767

HEXADECIMAL

A hexadecimal number consists of a string of from one to four numeric characters and/or alphabetic characters (A to F inclusive) enclosed in single quotes and preceded by an H. No blanks are allowed within the number or between the H and the number. Hexadecimal numbers in the range H'O' to H'FFFF' are valid. Signed hexadecimal numbers are invalid.

Examples:

Valid	Invalid	Reason invalid
H'12'	'ABCD'	No preceding H
H'ABCD'	H'-12'	Invalid character (-)
H'1AFO'	H'12,A3'	Invalid character (.)

BINARY

A binary number consists of a string of from 1 to 16 ones or zeroes, enclosed within a pair of quotes and preceded by a B. No blanks are allowed between the apostrophe symbols, or between the B and the number. If there are less than 16 binary digits, leading 0 digits are assumed.

Examples:

Valid	Invalid	Reason invalid
B'101101' B'0010'	B1011101 B'10110111011100101' B'10021'	No quotes Too many digits Invalid digit (2)

OCTAL

An octal number consists of a string of from one to six numeric digits, excluding 8 or 9, enclosed between single quotes and preceded by an O. Octal numbers in the range O'O' to O'177777' are valid. Signed numbers are invalid.

Examples:

Valid	Invalid	Reason invalid
Oʻ17243ʻ Oʻ2462ʻ Oʻ177272ʻ	017243 '2462' 0'277272'	No quotes No preceding O Value exceeds maximum
0'23714'	O'23914'	Invalid character (9)

CHARACTERS

Any characters (other than the single quote character) may be enclosed in single quotes and preceded by a C, in which case the characters will be interpreted as ASCII characters (see Appendix B).

Examples:

Valid	Invalid	Reason invalid
C'VALID'	'VALID'	No preceding C
C'12345'	C12345'	No initial single quote
C'NAME'	C"NAME"	Double quotes

TIMER COUNTS

As described in Section 2, the 3851 PSU and the 3853 Memory Interface device each have a timer which may be loaded under program control. Depending on the value loaded into the timer, variable delays may be programmed, at the end of which a timer interrupt is transmitted to the 3850 CPU.

Timer counts may be entered, as decimal numbers between 0 and 255, enclosed in single quotes and preceded by a T. The assembler converts the timer count to the exact binary code which (based on the timer logic) will generate the required time delay. Appendix C provides the exact codes that correspond to each timer count entered using T'nn' format.

Recall that the exact time delay is given by the equation:

Delay = (timer counts) * 31 * Clock period

Examples:

Valid	Invalid	Reason invalid
T'25'	T25	No single quotes
T'127'	T'1 2A'	Invalid character (A)
T'254'	T'264'	Count too high

4.3.3 Symbols

A symbol is a character string of from one to four characters, the first of which must be alphabetic (A-Z). A symbol may have any number of characters; however, only the first four characters are interpreted by the assembler. A symbol cannot have the exact appearance of a number, as specified in Section 4.3.2.

Since a blank space acts as a field delimiter, it cannot be present as a character within a symbol.

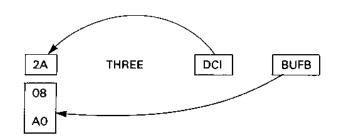
Examples:

Valid	Invalid	Reason invalid
ABCD	ABRCD	A blank present. AB is the assumed symbol
A812	12AB	A numeric first character
D12	D'12'	Would be interpreted as decimal 12
SYMBOLA	SYMBOLB	Both symbols are SYMB

Figure 4-7 illustrates a number of symbols in a source program. Observe that symbols may appear in the label field or the operand field of an instruction.

When a symbol appears in the label field of an instruction, it is either assigned a value by that instruction (EQU) or it is assigned a value equal to the location of that instruction, depending on the nature of the instruction. Sections 5.5 and 5.7 describe how this is done.

When a symbol appears in the operand field of an instruction, the assembler substitutes the assigned value for the symbol. For example, instruction THREE in Figure 4-7 causes the value associated with symbol BUFB to be loaded into the DCO registers of all memory and memory interface devices. Instruction THREE therefore generates the following object code:



4.3.4 Expressions

Expressions may appear in the operand field of an instruction, and are evaluated by the assembler to generate a constant which is used in the object program.

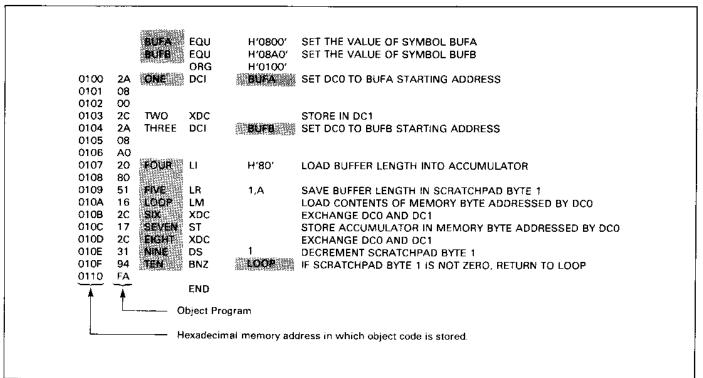


Fig. 4-7. Symbols in a Source Program

Unlike higher level languages, expressions do not represent equations to be resolved at execution time. By the time a program is executed, every expression in the source program will have been converted (by the assembler) to a constant in the object program.

An expression can have three types of numeric value, finked by six types of algebraic symbol.

These are the three types of numeric value:

- 1) Any symbol, as defined in Section 4.3.3.
- Any constant numeric value, as defined in Section 4.3.2.
- An asterisk (*), which will be interpreted as having the value of the memory address into which the first object program byte for this instruction will be stored.

These are the six algebraic symbols that are recognized:

- 1) + for add
- 2) for subtract

- 3) * for multiply
- 4) / for divide
- 5) ** for exponentiate
- (and) to enclose expression and subexpressions, which are to be evaluated as a constant.

Expressions and subexpressions must be enclosed in brackets. An exception is the simple (and most frequently used expression:

*±numeric constant

Subexpressions may be nested ten deep.

Use of complex expressions is pointless, since it is almost as simple to evaluate the expression and use the evaluated result in the object program. The one time when expressions are useful is when calculating instruction addresses. Referring to Figure 4-7, the following are substitutes for LOOP in the operand field of instruction TEN:

*-5 (equals H'010F' - 5) (FOUR+3) (equals H'0107' + 3)

ASSEMBLER DIRECTIVES

Assembler directives are instructions to the assembler; as such, they generate no object code. Assembler directives provide the assembler with the following three types of information:

- 1) Values of symbols
- 2) How memory is to be mapped
- 3) Assembly listings print options

Assembler directives are described in alphabetic order on the following pages. A summary of the assembler directives which are necessary, versus those which are optional, is given in Section 5.11; hints on good programming practice are also provided.

5.1 BASE - SELECT LISTING NUMERIC BASE

This is an optional directive which specifies the number system in which object program codes will be printed on the assembler printout. The following three options are provided:

Label	Mnemonic	Operand	Comment
	BASE	HEX	Select hexadecimal output
	BASE	OCT	Select octal output
	BASE	DEC	Select decimal output

If no base is specified, decimal output will be selected by default. If a base is specified, one BASE instruction should appear at the beginning of the program, as illustrated in Figure 5-1.

Since hexadecimal notation is the standard for the F8 microprocessor, it is strongly recommended that programmers use this numeric option.

5.2 DC - DEFINE CONSTANT

This directive causes the assembler to generate a one or two byte constant. The DC directive is an exception in that it causes one or two bytes of object code to be generated—identical to the one or two byte constant specified.

The DC directive will usually have a label, which becomes the symbol via which the constant is referenced. The general format of the DC directive is:

Label Mnemonic Operand LABEL DC VALUE

LABEL is any valid symbol. The label is optional. VALUE is any valid numeric value as described in Section 4.3.2.

For examples of DC directive use see Section 7.2.1. See also Section 5.5.1 for a discussion of when DC directives are used and when EQU directives are used.

5.3 EJECT - EJECT CURRENT LISTING PAGE

This directive has no effect on the program being assembled. It controls the line printer on which the assembler is printing out an assembly listing.

When the assembler encounters EJECT in the mnemonic field of an instruction, it immediately advances the line printer paper to the top of the next page.

If the assembler is not printing out an assembly listing, it will ignore the EJECT directive.

The format of the EJECT directive is:

Label Mnemonic Operand EJECT

		BUFA BUFB	TITLE MAXCPL SYMBOL XREF BASE EQU EQU ORG	"SAMPLI 50 HEX H'0800' H'08A0' H'0100'	E PROGRAM TO MOVE DATA BETWEEN BUFFERS" LIMIT OF 50 SECONDS CPU TIME SPECIFIED A SYMBOL TABLE WILL FOLLOW SOURCE PROGRAM SYMBOLS CROSS LISTING WILL FOLLOW SOURCE PROGRAM HEXADECIMAL NUMBERS SPECIFIED FOR ASSEMBLY LISTING SET THE VALUE OF SYMBOL BUFA SET THE VALUE OF SYMBOL BUFB
0100	2A	ONE	DC!	BUFA	SET DC0 TO BUFA STARTING ADDRESS
0101	80				The second state of the second
0102	00				
0103	2C	TWO	XDC		STORE IN DC1
0104	2A	THREE	DCI	BUFB	SET DC0 TO BUFB STARTING ADDRESS
0105	08				
0106 0107	A0				
0107	20	FOUR	LI	H'80'	LOAD BUFFER LENGTH INTO ACCUMULATOR
0109	80 51	EB/E	4.5		
010s	16	FIVE LOOP	LR	1,A	SAVE BUFFER LENGTH IN SCRATCHPAD BYTE 1
0108	2C	SIX	LM XDC		LOAD CONTENTS OF MEMORY BYTE ADDRESSED BY DCO
010C	17	SEVEN	ST		EXCHANGE DCO AND DC1
010D	2C	EIGHT	XDC		STORE ACCUMULATOR IN MEMORY BYTE ADDRESSED BY DCO
010E	31	NINE	DS		EXCHANGE DC0 AND DC1
010F	94	MINAT	BNZ	LOOP	DECREMENT SCRATCHPAD BYTE 1
0110	FA		DITE	LOOP	IF SCRATCHPAD BYTE 1 IS NOT ZERO, RETURN TO LOOP
2.10			END		

Fig. 5-1. Assembler Directives (Shaded) in a Source Program

5.4 END - END OF ASSEMBLY

An END directive must terminate every source program. Upon encountering this directive, the assembler stops reading source program instructions, and starts to perform various post-assembly computations.

Figure 5-1 illustrates use of an END directive.

Note that an END directive cannot, and must not, have a label.

The format of the END directive is:

Label Mnemonic Operand Must END be blank

5.5 EQU - EQUATE A SYMBOL TO A NUMERIC VALUE

Every symbol in a source program must be the label of an assembly language instruction or a DC directive, or the symbol must be assigned a value by an EQU directive. The general format of an EQU directive is:

Label Mnemonic Operand LABEL EQU VALUE

LABEL is any valid symbol.

VALUE is any valid numeric value as described in Section 422

Refer to Figure 5-1. The symbols BUFA and BUFB appear in instructions ONE and THREE, and are assigned values by two EQU directives. Therefore:

BUFA EQU H'0800'
--ONE DCI BUFA

is identical in its net effect to:

ONE DCI H'0800'

Why then are Equate directives used? In a real program, a symbol (such as BUFA) is likely to appear many times. If the value of the symbol changes, the program can be corrected by modifying one Equate directive, then re-assembling the program. If absolute values are used in instruction operands (instead of symbols), every instruction that references the absolute value must be changed in the source program if the absolute value changes; the source program nust be re-assembled.

For example, suppose there are 24 instructions in a source program that reference the symbol BUFA. The Equate directive could be eliminated, in which case each of the 24 instructions would have H'0800' where it had BUFA. However, if H'0800' had to be changed, instead of making the change in one Equate directive, the change would have to be made in each of the 24 instructions.

5.5.1 A Comparison of the EQU and DC Directives

A common error made by novice programmers is to misuse the EQU and DC directives. The difference between the two must be clearly understood. With reference to Figure 5-1, consider the following erroneous variation of the BUFA symbol's use:

BUFA	ORG DC	H'2FA0' H'0800'
	_	
	_	
	_	
	ORG	H'0100'
ONE	DCI	BUFA

The DC directive causes the two byte, hexadecimal value H'0800' to be stored in two memory bytes, with addresses H'2FA0' and H;2FA1'. In instruction ONE, BUFA acquires the value H'2FA0', not H'0800'.

Now consider how the DC directives might be correctly used in the Figure 5-1 program. BUFB has been equated to H'O8AO', which is the starting memory address of the source buffer. The source buffer contents could be specified, using DC directives, as follows:

BUFA	EQU	H'0800'
	ORG	H'0100'
ONE	DCI	BUFA
TWO	XDC	
THREE	DCI	BUFB
	_	
	_	
	ORG	H'08A0'
BUFB	DC	H'20A1'
	DC	H'143E'
	DC	H′5A62′

The symbol BUFB no longer needs to be equated to H'08A0' since it appears as a label at address H'08A0'. The DC directives cause the data string H'20A1143E5A62' to be loaded into memory starting at memory location H'08A0'.

NOTE: When a buffer's contents are specified by DC directives, the buffer's data becomes part of the program, and are loaded into memory when the program is loaded into memory.

5.6 MAXCPU - SPECIFY MAXIMUM CPU TIME

This directive is only meaningful when the source program is being assembled on a large host computer (e.g., an IBM 360 or 370). On such large computers, programs exist to simulate the F8 microprocessor; therefore once the source program has been assembled, the object program may be "run" using the host computer simulator.

A potential problem lies in executing an object program which, due to programming errors, may run for ever; a large amount of costly host computer time may be expended before the existence of the error is detected. The MAXCPU directive specifies a maximum number of seconds of host computer execution time, after which program execution will be terminated.

Figure 5-1 illustrates the use of the MAXCPU directive, specifying a maximum of 50 seconds of host computer CPU time. Note that the MAXCPU directive cannot, and must not, have a label.

The format of the MAXCPU directive is:

Label Mnemonic Operand Must MAXCPU CONSTANT be blank

CONSTANT is any numeric constant as described in Section 4.3.2.

5.7 ORG - ORIGIN A PROGRAM

As described in Section 4.3.3, a symbol which is an instruction label acquires a value equal to the memory address of the first object program byte for the instruction. With reference to Figure 5-1, therefore:

ONE acquires the value of H'0100' LOOP acquires the value of H'010A'

In order to assign values to instruction labels, the assembler has to know where the object program will be stored once it gets loaded into an F8 microprocessor system memory; this is done using the ORG directive.

When assembling a source program, the assembler maintains its own program counter, which tracks the memory addresses into which each byte of object program is destined to be stored. Whenever the assembler encounters an ORG directive, it resets its program counter to the address specified by the ORG directive. Thus in Figure 5-1 the ORG directive sets the effective memory address to H'0100' for the first object code byte of the first instruction that follows.

A program may have more than one ORG directive, depending on how subroutines and program modules have been mapped into memory. Any time there is a "gap" between one program module and the next, the new origin must be specified using an ORG directive.

The format of the ORG directive is as follows:

Label Mnemonic Operand Must ORG VALUE be blank

The ORG directive cannot and must not have a label.

VALUE is any valid numeric value as described in Section 4.3.2, or any valid expression as described in Section 4.3.4.

5.8 SYMBOL - ASSEMBLER PROVIDE A SYMBOL TABLE

This directive may optionally appear once, at the beginning of a source program, as illustrated in Figure 5-1.

If the assembler encounters SYMBOL in the mnemonic field of an instruction, it will print a symbol table at the end of the assembly listing. The SYMBOL directive cannot, and must not have a label.

A symbol table lists every symbol encountered in the source program, along with the value assigned to the symbol.

A symbol table allows errors in symbols to be spotted quickly. A misspelled symbol, for example, will appear in the symbol table as an extra, unexpected symbol.

5.9 TITLE - PRINT A TITLE AT THE HEAD OF THE ASSEMBLER LISTING

This is an optional directive, which, if present, causes a title to be printed at the top of every assembler listing page. The format of this directive is as follows:

Label Mnemonic Operand
Must TITLE "any heading"
be blank

The heading must be enclosed in double quotes. The TITLE directive cannot, and must not, have a label.

5.10 XREF - ASSEMBLER PROVIDE A SYMBOL CROSS REFERENCE LISTING

This directive may optionally appear once, at the beginning of a source program, as illustrated in Figure 5-1.

If the assembler encounters XREF in the mnemonic field of an instruction, it will print a cross reference listing of symbols at the end of the assembly listing. The XREF directive cannot, and must not, have a label.

A cross reference listing shows every symbol encountered in the source program, plus the statement number at which the symbol was referenced (i.e., appeared in an instruction's operand field).

A cross reference listing allows misplaced or misspelled symbols to be quickly spotted and corrected.

5.11 WHEN TO USE ASSEMBLER DIRECTIVES

The END assembler directive must be present in a source program. Without this directive the program will not assemble correctly.

The ORG, DC and EQU directives are almost always used in a program. Symbols equated to a numeric value (using the EQU directive) are recommended instead of having numeric constants in instruction operands.

The remaining assembler directives are optional, to be used for programming efficiency and convenience only.

THE INSTRUCTION SET

Because of the nature of the F8 family of devices, program sequences are very dependent on device configurations. Many instructions are important in some device configurations, but do not apply, or are rarely used in other device configurations. Therefore, individual F8 instructions should be visualized as contributions to one (or more) of a number of common, identifiable operation sequences, rather than as equal entities.

It would be impossible to describe operation sequences without first defining individual instructions; therefore, individual instructions are defined in this section, and example programs representing common operation sequences are given in Sections 7, 8, 9 and 10.

In this section instructions are described in alphabetic order of the instruction mnemonic. This makes it easy to locate any instruction. Examples in this section are very primitive, and merely illustrate the operations performed by each instruction. Programs in Sections 7 through 10 are referenced for comprehensive and realistic examples. Instructions are grouped by type in Appendix D.

When instruction format is defined, optional items are enclosed in square brackets. For example:

[LABEL] ADC

means that the instruction ADC may, or may not have a label.

Tables 6-1 and 6-2 identify the terms and abbreviations used in Section 6.

Nval3	 This symbol is used to indicate an instruction operand which defines the three low order bits of the instruction object code.
Nval4	 This symbol is used to indicate an instruction operand which defines the four low order bits of the instruction object code.
Nval8	 This symbol is used to indicate an instruction operand which defines the 8-bit second byte of the instruction object code.
Nval16	 This symbol is used to indicate an instruction operand which defines the 8-bit second byte, plus the 8-bit third byte of the instruction object code.

Table 6-1. Operand Symbols

Instructions described in the rest of Section 6 generate 1, 2 or 3 bytes of object code.

The first byte of object code is always the instruction operation code. Selected "short" instructions use three or four bits of the first byte to specify data.

The second byte of a 2-byte instruction provides either a signed, or an unsigned, binary number.

The second and third bytes of three byte instructions provide a 16-bit unsigned binary number.

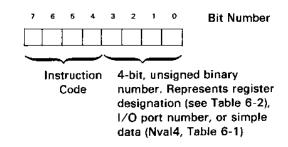
Value or Symbol for Sreg	Scratchpad Register Specified
0 through 11	The first 12 scratchpad registers are addressed directly.
12 or \$	The scretchpad register address is provided indirectly by ISAR.
13 or I	As 12, but the low order three bits of ISAR are incremented after the scratch-pad register is accessed.*
14 or D	As 12, but the low order three bits of ISAR are decremented after the scratch-pad register is accessed.*

Table 6-2. Operands Referencing Scratchpad Memory, as Specified by Symbol Sreg

Object code types are illustrated below, with the instructions using each object code type identified by instruction mnemonic.

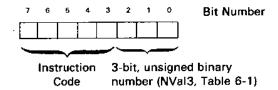
See Appendix D for actual object code byte contents.

One Byte, Type 1



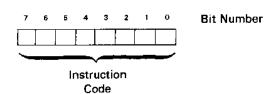
AS, ASD, CLR, DS, INS, LIS, LR (with Sreg), NS, OUTS, XS

One Byte, Type 2



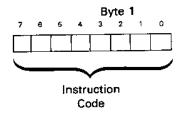
LISL, LISU

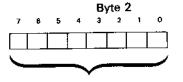
One Byte, Type 2



ADC, AM, AMD, CM, COM, DI, EI, INC, LM, LNK, LR (not with Sreg), NM, NOP, OM, PK, POP, SL, SR, ST, XDC, XM

Two Byte, Type 1



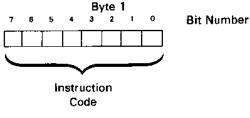


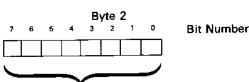
Bit Number

8-bit, binary data (Nval8, Table 6-1)

AI, CI, IN, LI, NI, OI, OUT, XI

Two Byte, Type 2

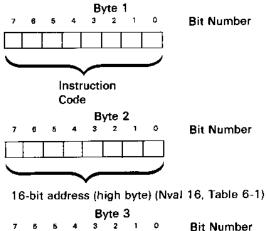




8-bit address displacement

BC, BF, BM, BNC, BNO, BNZ, BP, BR, BR7, BT, BZ

Three Byte



7 8 5 4 3 2 1 0 Bit Number

16-bit address (low byte) (Nval 16, Table 6-1) DCI, JMP, PI

6.1 ADC - ADD ACCUMULATOR TO DATA COUNTER

The contents of the accumulator are treated as a signed binary number, and are added to the contents of every DC0 register. The result is stored in the DC0 registers. The accumulator contents do not change.

FORMAT:

[LABEL] ADC

STATUS CONDITIONS:

No status bits are modified.

EXAMPLES:

Suppose the accumulator contains H'3E' and every DC0 register contains H'209A'. After execution of the ADC instruction, every DC0 register will contain H'20D8':

209A __3E H'20D8'

Suppose the accumulator contains H'A2' and every DC0 register contains H'213E'. In two's complement notation, H'A2' is a negative number, since the high order bit of the byte is 1:

H'A2' = 1 0 1 0 0 0 1 0

Sign Bit = 1, Value negative

Accordingly, after execution of the ADC instruction, every DCO register will contain H'20E0'C

213E FFA2 H'20E0'

See also Sections 7.3.4., 7.5.1, and 9.3.2.

6.2 Al - ADD IMMEDIATE TO ACCUMULATOR

The 8-bit (two hexadecimal digit) value provided by the instruction operand is added to the current contents of the accumulator. Binary addition is performed.

FORMAT:

[LABEL] AI Nval8

Nval8 is defined in Table 6-1

STATUS CONDITIONS:

Statuses modified: OVF, ZERO, CARRY, SIGN

Statuses unaffected: ICB

EXAMPLE:

Suppose the accumulator contains H'3F'. After execution of the instruction:

AI H'7E'

the accumulator will contain H'BD':

Bit No. C 7 6 5 4 3 2 1 0 H'3F' = 0 0 1 1 1 1 1 1 1 H'7E' = 0 1 0 1 1 1 1 0 1

There is no carry out of bit 7, so CARRY = 0. There is a carry out of bit 6 and no carry out of bit 7, therefore OVF = O + 1 = 1.

The result is not zero, so ZERO = 0. The high order bit of the result is 1, so SIGN = 0.

See also Sections 8.2.7 and 10.1.3.

6.3 AM - ADD (BINARY) MEMORY TO ACCUMULATOR

The content of the memory location addressed by the DCO registers is added to the accumulator. The sum is returned in the accumulator. Memory is not altered. Binary addition is performed. The contents of the DCO registers are incremented by 1.

FORMAT:

[LABEL] AM

STATUS CONDITIONS:

Statuses modified: OVF, ZERO, CARRY, SIGN

Statuses unaffected: ICB

EXAMPLE:

Suppose the accumulator contains H'C2', the DC0 registers contain H'213E' and memory location H'213E' contains H'2A'. After an AM instruction has been executed, the DC0 registers will contain H'213F', and the accumulator will contain H'EC'C

Bit No: C 7 6 5 4 3 2 1 0 H'C2' = 1 1 0 0 0 0 1 0 H'2A' = 0 0 1 0 1 0 1 0 H'EC' = 0 1 1 1 0 1 1 0 0

There is no carry out of bit 7, so CARRY = 0. There is no carry out of bit 6 or bit 7, so OVF = 0 \oplus 0 = 0. The result is not zero, so ZERO = 0. The high order bit of the result is 1, so SIGN = 0. See also Sections 7.2.2, 7.4.2, 10.2.2.

6.4 AMD - DECIMAL ADD, MEMORY TO ACCUMULATOR

The accumulator and the memory location addressed by the DCO registers are assumed to contain two BCD digits. The content of the address memory byte is added to the contents of the accumulator to give a BCD result in the accumulator, providing these steps are followed:

Decimal addition is, in reality, three binary events. Consider 8-bit decimal addition. Assume two BCD digit augend XY is added to two BCD digit addend ZW, to give a BCD result PQ:

XY +ZW =PQ Two carries are important: any intermediate carry (IC) out of the low order answer digit (Q), and any overall carry (C) out of the high order digit (P). The three binary steps required to perform BCD addition are as follows:

- STEP 1 Binary add H'66' to the augend.
- STEP 2 Binary add the addend to the sum from Step 1. Record the status of the carry (C) and intermediate carry (IC).
- STEP 3 Add a factor to the sum from Step 2, based on the status of C and IC. The factor to be added is given by the following table:

	s from p 2	
С	IC	Sum to be added
0	0	H'AA'
0	1	H'A0'
1	0	H'OA'
1	1	H'00'

In Step 3, any carry from the low order digit to the high order digit is suppressed.

For example, consider 21 + 67 = 88.

		00100001 01100111
STEP 1	H'21' + H'66' = H'87'	00100001 01100110 10000111
STEP 2	H'87' + H'67' = H'EE'	10000111 01100111 11101110
	c	= 0 IC =0
STEP 3	H'EE' + H'AA' ⁻ = H'88'	11101110 10101010 10001000
		Carry suppressed

DECIMAL ADD:

A decimal add is accomplished by executing a binary addition of H'66' to one of the two BCD numbers, then executing the AMD instruction, as follows:

Al H'66' Always precedes AMD for addition [LABEL] AMD

DECIMAL SUBTRACT:

Assume scratchpad byte 0 contains 1, the accumulator contains the subtrahend and DCO addresses the minuend. Decimal subtraction is performed as follows:

COM ONES COMPLEMENT SUBTRAHEND

AMD DECIMAL ADD MINUEND

AI H'66'

ASD 0 DECIMAL ADD 1 TO SUM

STATUS CONDITIONS:

Statuses modified: CARRY, ZERO Statuses not significant: OVF, SIGN

Statuses unaffected: ICB

EXAMPLES:

DECIMAL ADD:

Assume the accumulator contains H'57', the DC0 registers contain H'12FA' and memory location H'12FA' contains H'60'. After the execution of:

AI H'66' AMD

the accumulator will contain H'17', and the DC0 registers will contain H'12FB'.

There is a carry, so CARRY=1. This carry indicates that the result of the addition exceeded 99; therefore the carry must be added to the next high order digit.

Other status indicators are modified, but their condition is not significant.

DECIMAL SUBTRACT:

Assume the accumulator contains H'79', the DC0 registers contain H'32A7', memory location H'32A7' contains H'80' and scratchpad byte 0 contains H'01'.

After executing:

COM AMD

AI H'66' ASD 0

the accumulator contains H'01'.

There is no carry, so CARRY = 0. No Borrow was required.

Status indicators other than carry are modified, but their condition is not significant.

6.5 AS - BINARY ADDITION, SCRATCHPAD MEMORY TO ACCUMULATOR

The content of the scratchpad register referenced by the instruction operand (Sreg) is added to the accumulator using binary addition. The result of the binary addition is stored in the accumulator. The scratchpad register contents remain unchanged. Depending on the value of Sreg, ISAR may be unaltered, incremented or decremented.

FORMAT:

[LABEL] AS Sreg

Sreg is defined in Table 6-2.

STATUS CONDITIONS:

Statuses modified: OVF, ZERO, CARRY, SIGN

Statuses unaffected: ICB

EXAMPLE:

Suppose the accumulator contains H'34' and scratchpad register 11 contains H'72'. After the instruction:

AS 11

is executed, the accumulator will now contain H'A6':

Bit No: C 7 6 5 4 3 2 1 0 H'34' = 0 0 1 1 0 1 0 0 H'72' = 0 1 0 1 0 0 1 0 H'A6'' = 0 1 0 1 0 0 1 1 0

There is no carry out of bit 7, so CARRY = 0. There is a carry out of bit 6, but not out of bit 7, so $OVF = 0 \oplus 1 = 1$.

The result is non-zero, so ZERO = 0. The high order bit of the result is 1, so SIGN = 0.

Suppose the accumulator contains H'7E', ISAR contains O'27' and scratchpad register 23 (=O'27') contains H'A2'. After the instruction:

AS D

is executed, the accumulator will contain H'20', and ISAR will increment (low order octal digit only) to O'26':

Bit No: C 7 6 5 4 3 2 1 0 H'7E' = 0 1 1 1 1 1 1 0 H'A2' = 1 0 1 0 0 0 1 0 H'20' = 1 0 0 1 0 0 0 0

There is a carry out of bit 7, so CARRY = 1. There is a carry out of bit 6 and bit 7, so OVF = 1 (+) 1 = 0. The result is non-zero, so ZERO = 0. The high order bit of the result is 0, so SIGN = 1.

Had the AS instruction operand been I, ISAR contents would have been decremented to O'2O'; had the AS instruction operand been S, ISAR contents would have remained unchanged.

See also Sections 7.1.2, 7.1.4, and 7.2.2.

6.6 ASD - DECIMAL ADD, SCRATCHPAD TO ACCUMULATOR

The ASD instruction is similar to the AMD instruction, except that instead of adding the contents of the memory byte addressed by the DCO registers, the content of the scratchpad byte addressed by operand (Sreg) is added to the accumulator.

FORMAT:

DECIMAL ADD:

AI H'66' ALWAYS PRECEDES ASD FOR ADDITION

[LABEL] ASD Sreg

Sreg is defined in Table 6-2.

DECIMAL SUBTRACT:

COM ALWAYS PRECEDES ASD FOR SUBTRACTION

[LABEL] ASD Sreg

AI H'66'

ASD ONE SCRATCHPAD BYTE ONE

CONTAINS H'01'

STATUS CONDITIONS:

The status bits have the same significance as they do for the AMD instruction.

EXAMPLES:

DECIMAL ADD:

Assume the accumulator contains H'42', the ISAR contains 0'54', and scratchpad register 0'54' contains H'83'.

After the instruction sequence:

AI H'66' ASD D

is executed, the accumulator will contain H'25'. ISAR will contain O'53'.

There is a carry, so CARRY = 1.

Other status indicators are modified, but their condition is not significant.

6.7 BRANCH INSTRUCTIONS

The Branch instruction is used to modify a program's instruction execution sequence by altering the contents of the program counters, PCO. In a conditional branch instruction, alteration occurs when specified branch test conditions are met. In an unconditional branch instruction, a branch occurs simply as the result of the execution of the instruction.

All branch instructions are two-byte instructions. The first byte is the object code of the instruction mnemonic. The second byte is a displacement which is added to the program counter if a branch occurs.

Conditional branch mnemonics: 8C, BF, BM, BNC, BNO, BNZ, BP, BR7, BT, BZ

Unconditional branch mnemonics: BR

FORMATS:

[LABEL] OP DEST

OP is one of the mnemonics BC, BM, BNC, BNO, BNZ, BP, BR7 or BZ.

DEST is an expression which evaluates to the memory address to which a branch may occur. Frequently DEST labels the instruction to which a branch may occur.

[LABEL] OP t,DEST

OP is one of the mnemonics BF or BT.

t is a condition specification, as given in Table 6-5 for BT, or in Table 6-4 for BF.

DEST is as described above.

Relative branching is performed within a range of 127 address locations forward and 128 address locations behind the address of the branch instruction's second byte.

All branch instructions are similar in operation, the only difference is the conditions under which a branch occurs. The instruction BC - BRANCH ON CARRY will be used as an example of how the branch instructions are executed.

When a BC instruction is executed a branch occurs to the instruction whose label is specified in BC instruction operand, but only if the Carry bit is set at the time the BC instruction is executed.

First, consider a BRANCH FORWARD as indicated in the following instruction sequence:

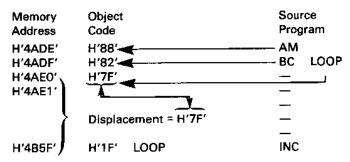


Fig. 6-1. Generation of a Displacement Object Program Byte in Response to a Forward Branch

Figure 6-1 illustrates source and consequent object program.

Assume the Carry bit is set as a result of the AM instruction execution and the contents of the program counters, PCO, are equal to H'4AEO', subsequent to the BC instruction operand fetch. A branch to H'4B5F' is indicated by the BC instruction as follows:

The displacement vector between H'485F' and H'4AE0' must be added to the program counters. This vector (+D'127') will have been calculated by the assembler and stored in the second byte of the BC instructions object code.

When a single byte displacement vector is added to the contents of the program counters, the most significant bit of the single byte displacement vector is propagated through the high order eight bits of the addition as follows:

Bit No: 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0 H'4AEO' 0 1 0 0 1 0 1 0 1 1 1 0 0 0 0 0 H'7F' 0 0 0 0 0 0 0 0 0 1 1 1 1 1 1 1 1 1 H'4B5F' 0 1 0 0 1 0 1 0 1 1 0 1 0 1 1 1 1

Next, consider a BRANCH BACKWARD as indicated in the following instruction sequence:

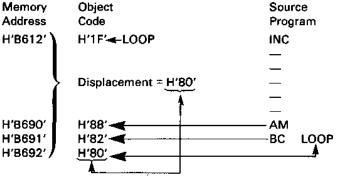


Fig. 6-2. Generation of a Displacement Object Program Byte in Response to a Backward Branch

Assume the carry bit is set and the program counters contain H'B692', subsequent to the BC instruction operand fetch. A branch to H'B612' is indicated by the BC instruction as follows:

The displacement vector between the address of the second byte of the BC instruction and the address of the instruction labeled LOOP is added to the PCO registers. The displacement vector will have been calculated by the assembler and stored in the second byte of the BC instruction object program. In the case of a BRANCH BACKWARD, the negative displacement will be a two's complement number. Since the high order (sign) bit of the displacement is 1, it will be propagated through the high order eight bits of the addition as follows:

Bit No:	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
H'B692'	1	0	1	1	0	1	1	0	1	0	0	1	0	0	1	0
H,80,	1	1	1	1	1	1	1	1	1	0	0	0	0	0	0	0
H'B612'	1	0	1	1	0	1	1	0	0	0	O	1	0	0	1	0

Table 6-3 lists the branch instruction mnemonics and the conditions under which a branch will occur.

INSTRUCTION MNEMONIC	BRANCH WILL OCCUR IF	EXAMPLE IN SECTION
BC - BRANCH ON		
CARRY	Carry bit is set	10.2.1
BF - BRANCH ON		
FALSE	See Table 6-4	
BM - BRANCH ON		
NEGATIVE	Sign bit is reset	
BNC- BRANCH IF		
NO CARRY	Carry bit is reset	
BNO- BRANCH IF		
NO OVERFLOW	OVF bit is reset	7.1.4, 7.3.3, 7.3.5
BNZ - BRANCH IF		
NOT ZERO	Zero bit is reset	7.1.3, 7.2.1, 7.2.2
BP - BRANCH IF		L
POSITIVE	Sign bit is set	7.3.4, 8.1.1, 8.1.3
BR - UNCONDITIONAL		
BRANCH	Always	7.1.4, 7.2.2, 7.3.4
BR7 - BRANCH	l	
ON ISAR	Any of the low	
	3 bits of ISAR	
l	are reset	7.1.1, 7.1.2, 8.2.7
BT - BRANCH		
ON TRUE	See Table 6-5	
BZ - BRANCH	<u></u>	
ON ZERO	Zero bit is set	7.2.1, 7.2.2, 7.3.4

Table 6-3. Branch Conditions

OPERAND	STA	TUS FL	AGS TES	STED		
t	OVF	ZERO	CARRY	SIGN	DEFINITION	COMMENTS
0	0	0	0	0	Unconditional Branch	
				'	relative	
1	0	0	0	1	Branch on negative	Same as BM
2 3	0	0	1	0	Branch if no carry	Same as BNC
3	0	0	1	1	Branch if no carry	
					and negative	
4	0	1	0	0	Branch if not zero	Same as BNZ
5 6	0	1	0	1		Same as t=1
6	0	1	1	0	Branch if no carry	
					and result is no zero	
7	0	1	1	1		Same as t=3
8	1	0	0	0	Branch if there is no	Same as BNO
					overflow	
9	1	0	0	1	Branch if negative and	
					no overflow	
Α	1	0	1	0	Branch if no overflow	
					and no carry	
В	1	0	1	1 1	Branch if no overflow,	
_			_	_	no carry & negative	
С	1	1	0	0	Branch if no overflow	
			_		and not zero	
D	1	1	0	1		Same as t=9
E	1	1	1	0	Branch if no overflow,	
	i	•			no carry & not zero	
F	1	1	1	1		Same as t=B

Table 6-4. Branch Conditions for BF Instruction

OPERAND	STATUS FLAGS TESTED				
t	ZERO	CARRY	SIGN	DEFINITION	COMMENTS
0	0	0	0	Do not branch	An effective 3 cycle NO-OP
1 1	0	0	1 1	Branch if Positive	Same as BP
2	0	1	0	Branch on Carry	Same as BC
3	0	1	1	Branch if Positive or on Carry	_
4	1	0	0	Branch if Zero	Same as BZ
5	1	0	1	Branch if Positive	Same as t=1
6	1	1	0	Branch if Zero or on Carry	
7	1	1	1	Branch if Positive or or on Carry	Same as t≐3

Table 6-5. Branch Conditions for BT Instruction

6.7.1 BF - Branch on False

The BF - BRANCH ON FALSE instruction will branch if the status bits selected by t in Table 6-4 are all reset. Selected bits are identified in Table 6-4 by 1 under "Status Flags Tested"; selected status bits must all be zero. Unselected status bits are ignored.

6.7.2 BT - Branch on True

The BT - BRANCH ON TRUE instructions will branch if any test conditions defined by t in Table 6-5 are met.

6.8 CI - COMPARE IMMEDIATE

The contents of the accumulator are subtracted from the operand of the Cl instruction. The result is not saved but the status bits are set or reset to reflect the results of the operation.

FORMAT:

[LABEL] CI Nval8

Nval8 is defined in Table 6-1.

STATUS CONDITIONS:

Statuses modified: OVF, ZERO, CARRY, SIGN

Statuses unaffected: ICB

EXAMPLE:

Assume the accumulator contains H'1B' and the second byte of the instruction contains H'D8'. The comparison is made as follows:

Bit No:	С	7	6	5	4	3	2	1	0
H'1B'		0	0	0	1	1	0	1	1
two's comp:		1	1	1	0	0	1	0	1
H'D8'		1	1	0	1	1	0	0	0
H'B0'	1	1	0	1	1	1	1	0	1

The H'BO' result is not saved. There is a carry out of bit 7, so CARRY = 1. There is also a carry out of bit 6, so OVF = 1 \oplus 1 = 0. The result is not zero, so ZERO = 0. The high order bit is 1, so SIGN = 0.

See also Sections 7.3.4, 8.2.7, 8.3.3.

6.9 CLR - CLEAR ACCUMULATOR

The contents of the accumulator are set to zero.

FORMAT:

[LABEL] CLR

STATUS CONDITIONS:

No status bits are modified.

EXAMPLE:

Assume the accumulator contains H'A0'. After the CLR instruction has executed, the accumulator contains H'00'.

See also Sections 7.1.1, 7.3.5, and 4.3.3.

6.10 CM - COMPARE MEMORY TO ACCUMULATOR

The CM instruction is the same as the CI instruction except the memory contents addressed by the DC0 registers, instead of an immediate value, are compared to the contents of the accumulator.

Memory contents are not altered. Contents of the DC0 registers are incremented.

FORMAT:

[LABEL] CM

See also Section 9.3.3.

6.11 COM - COMPLEMENT

The accumulator is loaded with its one's complement.

FORMAT:

[LABEL] COM

STATUS CONDITIONS:

Statuses modified: ZERO, SIGN Statuses reset: OVF, CARRY Status unaffected: ICB

EXAMPLE:

If the accumulator contains H'8B', after the COM instruction is executed, it will contain H'74'.

The Zero bit is reset to 0 since the result is not zero.

The Sign bit is set to 1 since the high order bit of the result is 0

The OVF and Carry bits are unconditionally reset to 0.

See also Sections 7.1.2, 7.2.2, and 7.4.2.

6.12 DCI - LOAD DC IMMEDIATE

The DCI instruction is a three-byte instruction. The contents of the second byte replace the high order byte of the DCO registers; the contents of the third byte replace the low order byte of the DCO registers.

FORMAT:

[LABEL] DCI Nval16

Nval16 is defined in Table 6-1.

STATUS CONDITIONS:

The status bits are not affected.

EXAMPLE:

After the instruction:

DCI H'2317'

is executed, the DC registers will contain H'2317'.

See also Sections 7.2.1, 7.2.2, 7.4.1.

6.13 DI - DISABLE INTERRUPT

The interrupt control bit, ICB, is reset; no interrupt requests will be acknowledged by the 3850 CPU.

FORMAT:

[LABEL] DI

STATUS CONDITION:S:

Statuses reset: ICB

Statuses unaffected: OVF, ZERO, CARRY, SIGN

6.14 DS - DECREMENT SCRATCHPAD CONTENT

The content of the scratchpad register addressed by the operand (Sreg) is decremented by one binary count. The decrement is performed by adding H'FF' to the scratchpad register.

FORMAT:

[LABEL] DS Sreg

Sreg is defined in Table 6-2.

STATUS CONDITIONS:

Statuses modified: OVF, ZERO, CARRY, SIGN

Statuses unaffected: ICB

EXAMPLE:

Assume the ISAR contains O'23' and the scratchpad register O'23' contains H'17'. After the instruction:

DS D

is executed, scratchpad register O'23' contains H'16' and the ISAR contains O'22'. The accumulator is unaffected.

There is a carry out from bit 7, so CARRY = 1.

There is a carry out from bit 6, so OVF = 1 (+) 1 = 0.

The result of the decrement is non-zero, so ZERO = 0.

The most significant bit is 0, so SIGN = 1.

See also Sections 7.1.3, 7.2.1 and 7.2.2.

6.15 EI - ENABLE INTERRUPT

The interrupt control bit is set. Interrupt requests will now be acknowledged by the CPU.

FORMAT:

[LABEL] EI

STATUS CONDITIONS:

ICB is set to 1.

All other status bits are unaffected.

See also Sections 8.2.7, 8.3.1, and 8.3.3.

6.16 IN - INPUT LONG ADDRESS

The data input to the I/O port specified by the operand of the IN instruction is stored in the accumulator.

The I/O port address assignments are given in Table 6-6. I/O ports with addresses 4 through 255 may be addressed by the IN instruction. I/O ports with port addresses 0 through 15 may be accessed by the INS instruction (see Section 6.17).

The IN instruction generates two bytes of object code, whereas the INS instruction generates one byte of object code.

If an I/O port or pin is being used for both input and output, the port or pin previously used for output must be cleared before it can be used to input data.

PORT ADDRESS (HEXADECIMAL)		MAY BE USED BY 3851 PSU	MAY BE USED BY 3852 DMI	MAY BE USED BY 3853 SMI	MAY BE USED BY 3854 DMA
00					
01					
02					
03					
04					
·		!			
ОВ					
oc					
OD .	i	(NOTE 1)	(NOTE 4)		
0E					
OF					
10					
EB					
EC					
ED		(NOTE 2)	(NOTE 4)	İ	
EE					
EF FO					
[
		(NOTE 3)		ļ	
		()			
FF					

Table 6-6. I/O Port Address Assignments

NOTE 1: These I/O port addresses may not be used by PSU's if a 3852 DMI or 3853 SMI device is used.

NOTE 2: These I/O port addresses may not be used by PSU's if a SL31116 DMI device is used.

NOTE 3: I/O port addresses used by DMA devices may not be used by PSU's.

NOTE 4: Two versions of the 3852 DMI device are available.

One uses port assignments H'OC' and H'OD'; the other uses port assignments H'EC' and H'ED'.

FORMAT:

[LABEL] IN Nval8

Nval8 is defined in Table 6-1.

STATUS CONDITIONS:

Statuses modified: ZERO, SIGN Statuses reset: OVF, CARRY Statuses unaffected: ICB

EXAMPLE:

Assume that the value H'C8' has been input by an external device to I/O port H'10'. After the instruction:

IN H'10'

is executed, the accumulator will contain H'37'. Note that the data is complemented between I/O pin and accumulator.

The overflow and carry bits are unconditionally reset, so OVF = CARRY = 0.

The accumulator content is non-zero, so ZERO = 0. The most significant bit is zero, so SIGN = 1.

See also Sections 7.6.2 and 8.4.3.

6.17 INC - INCREMENT ACCUMULATOR

The content of the accumulator is increased by one binary count.

FORMAT:

[LABEL] INC

STATUS CONDITIONS:

Statuses modified: OVF, ZERO, CARRY, SIGN

Statuses unaffected: ICB

EXAMPLE:

Assume the accumulator contains H'FF'. After an INC instruction execution, the accumulator contains H'00'.

There is carry out from bit 7, so CARRY = 1.

There is also a carry out from bit 6, so OVF = 1 (+) 1 = 0.

The result is zero, so ZERO = 1, and SIGN = 1.

See also Section 8.3.3 and 10.2.2.

6.18 INS - INPUT SHORT ADDRESS

Data input to the I/O port specified by the operand of the INS instruction is loaded into the accumulator. An I/O port with an address within the range 0 through 15 may be accessed by this instruction.

If an I/O port or pin is being used for both input and output, the port or pin previously used for output must be cleared before it can be used to input data.

FORMAT:

[LABEL] INS Nval4

Nval4 is defined in Table 6-1.

STATUS CONDITIONS:

Statuses modified: ZERO, SIGN Statuses reset: OVF, CARRY Statuses unaffected: ICB

EXAMPLE:

Assume that the 3850 CPU I/O port addressed by H'01' contains H'79'. Execution of the instruction:

INS 1

causes the accumulator to be loaded with H'86'.

The overflow and carry bits are reset, so OVF = CARRY = 0. The accumulator content is non-zero, so ZERO = 0. The most significant bit is 1, so SIGN = 0.

6.19 JMP - BRANCH IMMEDIATE

As the result of a JMP instruction execution, a branch to the memory location addressed by the second and third bytes of the instruction occurs. The second byte contains the high order eight bits of the memory address; the third byte contains the low order eight bits of the memory address.

The accumulator is used to temporarily store the most significant byte of the memory address; therefore, after the JMP instruction is executed, the initial contents of the accumulator are lost.

FORMAT:

[LABEL] JMP Nval16

STATUS CONDITIONS:

No status bits are affected.

EXAMPLE:

Assume the operand of the JMP instruction contains H'03A6'. After the instruction:

JMP H'03A4'

is executed, the next instruction will execute from address H'03A4'. At the completion of this execution, the accumulator contains H'03'.

See also Section 7.3.4 and 7.5.1.

6.20 LI - LOAD IMMEDIATE

The value provided by the operand of the LI instruction is loaded into the accumulator.

FORMAT:

[LABEL] LI Nval18

STATUS CONDITIONS:

No status bits are affected.

EXAMPLE:

Assume the second byte of the LI instruction contains H'C7'. The instruction:

LI H'C7'

causes the accumulator to be loaded with H'C7'.

See also Section 7.1.3, 7.2.1, and 7.2.2.

6.21 LIS - LOAD IMMEDIATE SHORT

A 4-bit value provided by the LIS instruction operand is loaded into the four least significant bits of the accumulator. The most significant four bits of the accumulator are set to "O".

FORMAT:

[LABEL] LIS Nval4

Nval4 is defined in Table 6-1.

STATUS CONDITIONS:

No status bits are modified.

EXAMPLE:

After the instruction:

LIS 3

has executed, the accumulator will contain H'03'.

See also Section 7.2.2, 7.3.4 and 9.3.2.

6.22 LISL - LOAD LOWER OCTAL DIGIT OF ISAR

A 3-bit value provided by the LISL instruction operand is loaded into the three least significant bits of the ISAR. The three most significant bits of the ISAR are not altered.

FORMAT:

[LABEL] LISL Nval3

Nval3 is defined in Table 6-1.

STATUS CONDITIONS:

No status bits are modified.

EXAMPLE:

Suppose ISAR contains the value O'72'. After the instruction: LISL 6

has executed, ISAR will contain the value O'76'.

See also Section 7.1.1, 7.1.2 and 8.2.7.

6.23 LISU - LOAD UPPER OCTAL DIGIT OF ISAR

A 3-bit value provided by the LISU instruction operand is loaded into the three most significant bits of the ISAR. The three least significant bits of the ISAR are not altered.

FORMAT:

[LABEL] Nval3

Nval3 is defined in Table 6-1.

STATUS CONDITIONS:

No status bits are affected.

EXAMPLE:

Suppose ISAR contains the value O'72'. After the instruction:

LISU 3

has executed, ISAR will contain the value O'32'.

See also Section 7.1.1, 7.1.2, and 8.2.7.

6.24 LM - LOAD ACCUMULATOR FROM MEMORY

The contents of the memory byte addressed by the DCO registers are loaded into the accumulator. The contents of the DCO registers are incremented as a result of the LM instruction execution.

FORMAT:

[LABEL] LM

STATUS CONDITIONS:

No status bits are modified.

EXAMPLE:

Assume the DCO registers contain H'37A2' and the memory location addressed by H'37A2' contains H'2B'. Execution of the LM instruction causes the accumulator to be loaded with H'2B'. The DCO registers subsequently will contain H'37A3'.

6.25 LNK - LINK CARRY TO THE ACCUMULATOR

The carry bit is binary added to the least significant bit of the accumulator. The result is stored in the accumulator.

FORMAT:

[LABEL] LNK

STATUS CONDITIONS:

Statuses modified: OVF, ZERO, CARRY, SIGN

Statuses unaffected; ICB

EXAMPLE:

Assume the accumulator contains H'84', and the CARRY bit is set. The instruction execution causes the accumulator to contain H'85'.

As a result of the instruction execution, there is no carry out of bit 7, so CARRY = 0.

There is also no carry out of bit 6, so OVF = $0 \oplus 0 = 0$. The result is non-zero, so ZERO = 0.

The most significant bit of the result is 1, so SIGN = 0.

See also Section 7.1.2, 7.1.4 and 7.2.2.

6.26 LR - LOAD REGISTER

The LR group of instructions move one or two bytes of data between a source and destination register. Instructions exist to move data between the following registers:

- a) A scratchpad register and the Accumulator
- b) Scratchpad registers and the Data Counter, DCO
- c) The Accumulator and the ISAR
- d) Scratchpad register 9 and the status register
- e) Scratchpad registers and Program Counter, PCO
- f) Scratchpad registers and stack register, PC1

An LR instruction's data source and destination is determined by the instruction operands as illustrated in Table 6-7. The number of data bytes moved (one or two) depends on the size of the source and destination registers (8 or 16 bits).

FORMAT:

[LABEL] LR D,S

S is the source register.

D is the destination register.

STATUS CONDITIONS:

No status bits are modified.

EXAMPLE:

Assume the ISAR contains O'76'. After the instruction:

LR A,IS

is executed, the accumulator contains O'76'. Scratchpad register O'76' remains unchanged. ISAR also remains unchanged.

6.27 NI - AND IMMEDIATE

An 8-bit value provided by the operand of the NI instruction is ANDed with the contents of the accumulator. The results are stored in the accumulator.

FORMAT:

[LABEL] NI Nvai8

LR INSTRUCT OPERAN DESTINATION	D\$	LOADS REGISTER	FROM REGISTER	WITH	EXAMPLE GIVEN IN SECTION
A, A, A, KU, KL, QU, QL, K, P,	KU KL QU A A A A P K	Accumulator Accumulator Accumulator Accumulator Accumulator Scratchpad register 12 Scratchpad register 14 Scratchpad register 15 Scratchpad register 15 Scratchpad register 12 Scratchpad register 13 High order byte of PC1 Low order byte of PC1 Accumulator	Scratchpad register 12 Scratchpad register 13 Scratchpad register 14 Scratchpad register 15 Accumulator Accumulator Accumulator Accumulator Accumulator Program Counter PC1 Program Counter PC1 Scratchpad register 12 Scratchpad register 13 ISAR	8-bit contents High order 8-bit byte Low order 8-bit byte 8-bit contents 8-bit contents 8-bit contents 00XXXXXX X's are contents of ISAR	7.3.4, 7.3.6 7.3.4, 7.3.6 8.4.3 8.4.3 7.3.4, 7.3.6 7.3.4, 7.3.6 7.3.4, 7.3, 7.3.6 8.4.3 7.3.4, 8.2.7
IS, PO,	A Q	ISAR High order byte of PCO	Accumulator Scratchpad register 14 Scratchpad register 15	Low order 6-bits. 8-bit contents 8-bit contents	7.3.4, 7.3.5, 8.2.7 7.3, 4.7.5
Q,	DC	Low order byte of PC0 Scratchpad register 14 Scratchpad register 15	Data counter registers DC0 Data counter registers DC0	High order byte	7.2.2, 7.3.6, 7.4.2
DC, DC,	О	High order byte DC0 Low order byte DC0 High order byte of DC0	Scratchpad register 14 Scratchpad register 15 Scratchpad register 10	8-bit contents 8-bit contents 8-bit contents	7.2.2, 7.3.3, 7.3.4
н,	DC	Low order byte of DC0 Scratchpad register 10 Scratchpad register 11	Scratchpad register 11 Data counter register Data counter register	High order byte Low order byte	7.2.2, 7.3.4, 7.3.6
W, J,	M J	Status register (w) Scratchpad register 9	Scratchpad register 9 Status register (w)	Low order 5 bits 000XXXXX X's are contents of status register	7.1.2, 7.2.2, 7.4.1 7.1.2, 7.2.2, 7.3.3
A, (Sreg)*	(Sreg)* A	Accumulator Scratchpad register (Sreg)	Scratchpad register (Sreg) Accumulator	8-bit contents 8-bit contents	7.1.2, 7.1.4, 7.4.1 7.1.1, 7.1.2, 7.1.3

^{*}Sreg is a hexadecimal digit representing a scratchpad register, as defined in Table 6-2.

Table 6-7. LR Instruction Operand Definitions

STATUS CONDITIONS:

Statuses reset to 0: OVF, CARRY Statuses modified: ZERO, SIGN Statuses unaffected: ICB

EXAMPLE:

Assume the second byte of the NI instruction contains H'36', and the accumulator contains H'2A' as a result of the instruction execution, the accumulator contains H'22'.

Bit No: 7 6 5 4 3 2 1 0 H'36' 0 0 1 1 0 1 1 0 H'2A' 0 0 1 0 1 0 1 0 H'22' 0 0 1 0 0 0 1 0

There is no carry out of bit 7, so CARRY = 0. There is no carry out of bit 6, so OVF = $0 \oplus 0 = 0$. The result is non-zero, so ZERO = 0. The most significant bit is zero, so SIGN = 1.

See also Section 7.1.2, 7.2.2 and 7.3.3.

6.28 NM - LOGICAL AND FROM MEMORY

The content of memory addressed by the data counter registers is ANDed with the content of the accumulator. The results are stored in the accumulator. The contents of the data counter registers are incremented.

FORMAT:

[LABEL] NM

STATUS CONDITIONS:

Statuses reset to 0: OVF, CARRY Statuses modified: ZERO, SIGN Statuses unaffected: ICB

EXAMPLE:

Assume the data counters contain H'49AC', the memory location addressed by H'49AC' contains H'67' and the accumulator contains H'A9'. After execution of the NM instruction, the accumulator contains H'21', and the data counters contain H'49AD'.

Bit No: 7 6 5 4 3 2 1 0 H'67' 0 1 1 0 0 1 1 1 H'A9' 1 0 1 0 0 0 1 H'21' 0 0 1 0 0 0 0 1

Also see Section 7.6.1.

6.29 NOP - NO OPERATION

No function is performed.

FORMAT:

[LABEL] NOP

STATUS CONDITIONS:

No status bits are modified.

EXAMPLE:

Assume the program counters contain H'2700'. After a NOP instruction is executed, the PCO registers contain 'H2701'.

Also see Section 8.4.3.

6.30 NS - LOGICAL AND FROM SCRATCHPAD MEMORY

The content of the scratchpad register addressed by the operand (Sreg) is ANDed with the content of the accumulator. The results are stored in the accumulator.

FORMAT:

[LABEL] NS Sreg

Sreg is defined in Table 6-2.

STATUS CONDITIONS:

Statuses reset to 0: OVF, CARRY Statuses modified; ZERO, SIGN Statuses unaffected; ICB

EXAMPLE:

Assume scratchpad register O'02' contains H'F2', and the accumulator contains H'2F'. Execution of the instruction:

NS 2

causes the accumulator to contain H'22'.

Bit No: 7 6 5 4 3 2 1 0 H'F2' 1 1 1 1 0 0 1 0 H'2F' 0 0 1 0 1 1 1 1 H'22' 0 0 1 0 0 1 0

There is no carry out of bit 7, so CARRY = 0. There is also no carry out of bit 6, so OVF = 0 \oplus 0 = 0. The result is non-zero, so ZERO = 0.

The most significant bit of the result is zero, so SIGN = 1.

Also see Section 7.6.1 and 7.6.2.

6.31 OI - OR IMMEDIATE

An 8-bit value provided by the operand of the I/O instruction is ORed with the contents of the accumulator. The results are stored in the accumulator.

FORMAT:

[LABEL] OI Nval8

Nval8 is defined in Table 6-1.

STATUS CONDITIONS:

Statuses modified: ZERO, SIGN Statuses reset: OVF, CARRY Statuses unaffected: ICB

EXAMPLE:

Assume the accumulator contains H'OA'. The execution of the instruction:

OI H'A3'

causes the accumulator to contain H'AB'.

Bit No: 7 6 5 4 3 2 1 0 H'AB' 1 0 1 0 0 0 1 1 H'OA' 0 0 0 1 0 1 0 H'AB' 1 0 1 0 1 0 1 1

The accumulator result is non-zero, so ZERO = 0. The most significant bit of the result is 1, so SIGN = 0. The overflow and carry bits are reset, so OVF = 0 and CARRY = 0.

Also see Section 7.6.1.

6.32 OM - LOGICAL "OR" FROM MEMORY

The content of memory byte addressed by the data counter registers is ORed with the content of the accumulator. The results are stored in the accumulator. The data counter registers are incremented.

FORMAT:

[LABEL] OM

STATUS CONDITIONS:

Statuses modified: ZERO, SIGN Statuses reset: OVF, CARRY Statuses unaffected: ICB

EXAMPLE:

Assume the DC registers contain H'FC19', the memory location addressed by H'FC19' contains H'16', and the accumulator contains H'81'. After execution of an OM instruction, the accumulator contains H'97' and the DC registers will contain H'FC1A'.

Bit No:	7	6	5	4	3	2	1	0
H′16′	0	0	0	1	0	1	1	0
H'81'	1	0	0	0	0	0	0	1
H'97'	1	Ö	0	1	0	1	1	1

The result is non-zero, so ZERO = 0.
The most significant bit of the result is 1, so SIGN = 0.
The overflow and carry bits are unconditionally reset, so OVF = 0 and CARRY = 0.

6.33 OUT - OUTPUT LONG ADDRESS

The I/O port addressed by the operand of the OUT instruction is loaded with the contents of the accumulator.

I/O ports with addresses from 4 through 255 may be accessed with the OUT instruction.

The OUT instruction generates two bytes of object code, whereas the OUTS instruction generates one byte of object code.

The I/O port addresses are defined in Table 6-6.

FORMAT:

[LABEL] OUT Nval8

Nval8 is defined in Table 6-1.

STATUS CONDITIONS:

No status bits are modified.

EXAMPLE

Assume the accumulator contains H'2A'. Execution of the instruction:

OUT H'F6'

will cause the I/O port H'F6' to be loaded with H'D5'. Note that the data at the I/O pins is complemented with respect to the accumulator.

6.34 OUTS - OUTPUT SHORT ADDRESS

The I/O port addressed by the operand of the OUTS instruction object code is loaded with the contents of the accumulator. I/O ports with addresses from 0 to 15 may be accessed by this instruction. The I/O port addresses are defined in Table 6-6. Outs 0 or 1 is CPU port only.

FORMAT:

[LABEL] OUTS Nval4

Nval4 is defined in Table 6-1.

STATUS CONDITIONS:

No status bits are modified.

EXAMPLE:

Assume the OUTS instruction operand (Nval4) is H'0F', and the accumulator contains H'32'. Execution of the instruction:

OUTS 15

will cause the I/O port H'OF' to contain H'CD'.

Also see Section 7.2.1, 8.1.1 and 8.1.3.

6.35 PI - CALL TO SUBROUTINE IMMEDIATE

The contents of the Program Counters are stored in the Stack Registers, PC1, then the 16-bit address contained in the operand of the PI instruction is loaded into the Program Counters. The accumulator is used as a temporary storage register during transfer of the most significant byte of the address. Previous accumulator results will be altered.

FORMAT:

[LABEL] PI Nval16

Nval16 is defined in Table 6-2.

STATUS CONDITIONS:

No status bits are modified.

EXAMPLE:

Assume that the operand of the PI instruction contains H'32A1', the program counter (PCO) registers contain H'ABCD', and the Stack registers (PC1) contain H'1234'. Execution of the instruction:

PI H'32A1'

causes the Stack registers (PC1) to contain H'ABCD', and the program counter registers (PC0) to contain H'32A1'.

Also see Section 7.3.3, 7.3.5 and 8.1.1.

6.36 PK - CALL TO SUBROUTINE DIRECT AND RETURN FROM SUBROUTINE DIRECT

The contents of the Program Counter Registers (PC0) are stored in the Stack Registers (PC1), then the contents of the Scratchpad K Registers (Registers 12 and 13 of scratchpad memory) are transferred into the Program Counter Registers.

FORMAT:

[LABEL] PK

STATUS CONDITIONS:

No status bits are modified.

EXAMPLE:

Assume Scratchpad Register 12 contains H'AB', Scratchpad Register 13 contains H'CD", and the Program Counter Registers (PCO) contain H'1234'. Execution of the instruction PK causes the Stack Registers to contain H'1234' and the Program Counter Registers to contain H'ABCD'.

Also see Sections 7.3.3, 7.4.1 and 8.2.7.

6.37 POP - RETURN FROM SUBROUTINE

The contents of the Stack Registers (PC1) are transferred to the Program Counter Registers (PC0).

FORMAT:

[LABEL] POP

STATUS CONDITIONS:

No status bits are modified.

EXAMPLE:

Assume the Stack Registers (PC1) contain H'ABCD' and the Program Counter Registers (PC0) contain H'1234'. When the POP instruction has been executed, the PC0 registers will contain H'ABCD' and PC1 will not be changed.

Also see Sections 7.3.3, 7.3.4 and 8.2.7.

6.38 SL - SHIFT LEFT

The contents of the accumulator are shifted left either one or four bit positions, depending upon the value of the SL instruction operand.

If the value of the operand is 1, the accumulator contents are shifted left one bit position. The least significant bit becomes a zero.

If the value of the operand is 4, the accumulator contents are shifted left four bit positions. The four least significant bits are filled with zeroes.

FORMAT:

[LABEL] SL Nval4

Nval4 = 1 or 4

STATUS CONDITIONS:

Statuses modified: ZERO, SIGN Statuses reset: OVF, CARRY Statuses unaffected: ICB

EXAMPLE:

Assume the accumulator contains H'81'. The execution of the instruction:

SL 1

causes the accumulator to contain H'02'. Execution of the instruction:

SL 4

causes the accumulator to contain H'10'.

in both examples the result is non-zero, so ZERO = 0. The most significant bit of the results is zero, so SIGN = 1.* The overflow and carry bits are unconditionally reset, so OVF and CARRY = 0.

Also see Sections 8.4.3, 8.3.2 and 10.3.

6.39 SR - SHIFT RIGHT

The contents of the accumulator are shifted right either one or four bit positions, depending on the value of the SR instruction operand.

If the value of the operand is 1, the accumulator contents are shifted right one bit position. The most significant bit becomes a zero

If the value of the operand is 4, the accumulator contents are shifted right four bit positions. The four most significant bits are filled with zeroes.

FORMAT:

[LABEL] SR Nval4

Nval4 = 1 or 4

STATUS CONDITIONS:

Statuses modified: ZERO, SIGN Statuses reset: OVF, CARRY Statuses unaffected: ICB

EXAMPLE:

Assume the accumulator contains H'81'. Execution of the instruction:

SR 1

causes the accumulator to contain H'40'. Execution of the instruction:

SR 4

causes the accumulator to contain H'08'.

In both examples the result is non-zero, so ZERO = 0. The most significant bit of the results is zero, so SIGN = 1. The overflow and carry bits are unconditionally reset, so OVF and CARRY = 0.

Also see Sections 10.1.2 and 10.3.

6.40 ST - STORE TO MEMORY

The contents of the accumulator are stored in the memory location addressed by the Data Counter (DC0) registers.

The DC registers' contents are incremented as a result of the instruction execution.

FORMAT:

[LABEL] ST

STATUS CONDITIONS:

No status bits are modified.

EXAMPLE:

Assume the accumulator contains H'69', and the DC0 registers contain H'ABBE'. Execution of the instruction ST causes the memory location H'ABBE' to contain H'69'; DC0 is incremented to contain H'ABBF'.

See also Sections 7.2.2, 7.3.4 and 7.4.2.

6.41 XDC - EXCHANGE DATA COUNTERS

Execution of the instruction XDC causes the contents of the auxiliary data counter registers (DC1) to be exchanged with the contents of the data counter registers (DCO).

This instruction is only significant when a 3852 or 3853 Memory Interface device is part of the system configuration.

FORMAT:

[LABEL] XDC

STATUS CONDITIONS:

No status bits are modified.

EXAMPLE:

Assume the data counters, DCO, contain H'ABCD', and the auxiliary data counter registers, DC1, contain H'1234', Execution of the instruction XDC causes the DCO registers to contain H'1234', and the DC1 registers to contain H'ABCD'. The PSU's will have DCO unaltered.

Also see Sections 7.2.2, 7.4.2 and 7.6.1.

6.42 XI - EXCLUSIVE-OR IMMEDIATE

The contents of the 8-bit value provided by the operand of the XI instruction are EXCLUSIVE-ORed with the contents of the accumulator. The results are stored in the accumulator.

FORMAT:

[LABEL] XI Nval8

Nval8 is defined in Table 6-1.

STATUS CONDITIONS:

Statuses modified: ZERO, SIGN Statuses reset: OVF, CARRY Statuses unaffected: ICB

EXAMPLE:

Assume the accumulator contains H'AB', and the operand of the XI instruction contains H'42'. Execution of the instruction:

XI H'42'

causes the accumulator to contain H'89'.

76543210 Bit No: 10101011 H'A8' H'42' 00100010 10001001 H'89'

The result is non-zero, so ZERO = 0. The high order bit of the results is one, so SIGN = 0.

The overflow and carry bit are unconditionally reset, so

OVF = 0 and CARRY = 0.

6.43 XM - EXCLUSIVE-OR FROM MEMORY

The content of the memory location addressed by the DCO registers is EXCLUSIVE-ORed with the contents of the accumulator. The results are stored in the accumulator. The DC0 registers are incremented.

FORMAT:

[LABEL] XM

STATUS CONDITIONS:

Statuses modified: ZERO, SIGN Statuses reset: OVF, CARRY Statuses unaffected: ICB

EXAMPLE:

Assume the DCO counters contain H'1DE4', the memory location addressed by H'1DE4' contains H'1D', and the accumulator contains H'A8'. Execution of the instruction XM causes the accumulator to contain H'B5'. DC0 is updated to H'1DE5'.

> 76543210 Bit No: H'1D' 00011101 H'A8' 10101000 10110101 H'B5'

The result is non-zero, so ZERO = 0.

The high order bit of the result is one, so SIGN = 0.

The overflow and carry bit are unconditionally reset, so OVF = 0 and CARRY = 0.

6.44 XS - EXCLUSIVE-OR FROM SCRATCHPAD

The content of the scratchpad register referenced by the operand (Sreg) is EXCLUSIVE-ORed with the contents of the accumulator.

FORMAT:

[LABEL] XS Sreg

Sreg is defined in Table 6-2.

STATUS CONDITIONS:

Statuses modified: ZERO, SIGN Statuses reset: OVF, CARRY Statuses unaffected: ICB

EXAMPLE:

Assume the scratchpad register 10 contains H'7C', and the accumulator contains H'61'. Execution of the instruction:

> XS 10

causes the accumulator to contain H'1D'.

Bit No. 76543210 H'7C' 01111100 01100001 H'61' H'1D' 00011101

The result is non-zero, so ZERO = 0.

The high order bit of the results is zero, so SIGN = 1. Overflow and carry bits are reset, so OVF = 0 and CARRY = 0.1

Also see Section 7.1.1 and 7.6.2.

PROGRAMMING TECHNIQUES

This section describes some basic programming techniques that will be useful in almost any F8 application.

NOTE: For easy reading, instructions in examples have labels which are repeated from one example to the next. it is important to understand that in a real program no label can be used more than once.

7.1 MANIPULATING DATA IN THE SCRATCHPAD

The Central Processing Unit's 64 byte scratchpad memory is the principle storage for data and addresses that are currently being accessed by the CPU. Table 7-1 illustrates the scratchpad memory. Notice that since the ISAR register is divided into two 3-bit units, octal numbers are the best suited to scratchpad addressing.

Scratchpad registers 0 through 8 are nine general purpose registers that should be used to store transient data (or addresses) currently being accessed.

Scratchpad registers 9 through 15 are used as temporary depositories for address and status register contents (DCO, PCO, PC1 and W). Special instructions move data between these scratchpad registers and their associated status or address registers.

Registers 16 through 63 are addressed via the ISAR register, and may be visualized as six, 8-byte buffers. The ISAR register can, of course, address any of the 64 scratchpad registers; however, usually only scratchpad registers 16 through 63 (0'20' through 0'77') are accessed via the address in ISAR.

BYTE !	NUMBER	
Octal	Decimal	FUNCTION
0 - 10	0 - 8	Nine general purpose scratch registers
11	9	Temporary storage for status register
12, 13	10, 11	HU and HL; temporary storage for the Data Counter registers (DCO)
14, 15	12, 13	KU and KL; temporary storage for the stack register (PC1)
16, 17	14, 15	QU and QL; temporary storage for Program Counter (PCO) or Data Counter Registers
20 - 27	16 - 23	First data buffer. ISAR = 0'2X'.
30 - 37	24 - 31	Second data buffer. ISAR = Q'3X',
40 - 47	32 - 39	Third data buffer, ISAR = 0'4X'.
50 - 57	40 - 47	Fourth data buffer. ISAR = 0'5X'.
60 - 67	48 - 55	Fifth data buffer. ISAR = 0'6X'.
70 - 77	56 - 63	Sixth data buffer. ISAR = 0'7X'.

Table 7-1. Scratchpad Memory Utilization

7.1.1 Simple Scratchpad Buffer Operations

Because of the way ISAR operates, registers 16 through 63 conveniently form six buffers, each capable of storing eight bytes. As described in Section 2.1, the ISAR is a 6-bit register, divided into 3-bit digits. When ISAR contents are in-

cremented or decremented, only the lower three bits are affected; therefore, once ISAR has been loaded with a scratch-pad address, it will only increment or decrement within an 8-byte address range. The end of any 8-byte buffer may be identified using the BR7 instruction.

To illustrate scratchpad buffer manipulation at its most elementary level, consider the following instruction sequence, which sets all eight bytes of a buffer to zero:

ONE TWO	CLR LISU	2	CLEAR THE ACCUMULATOR ADDRESS SCRATCHPAD BUFFER 1
THREE	LI\$L	7	
LOOP	LR	D,A	CLEAR SCRATCHPAD BYTE AND DECREMENT ISAR
FOUR	BR7	LOOP	RETURN FOR MORE BYTES

Instructions execute as follows:

ONE: Clear the accumulator, so scratchpad bytes may be cleared by loading 0 into each byte.

TWO Set the ISAR register to address the first byte THREE: of scratchpad buffer 1. This address is O'27'.

LOOP: Load the accumulator content (which is zero) into the scratchpad byte addressed by ISAR (initially byte O'27'). Because ISAR is identified in the operand via the address D, decrement the low order ISAR octal digit. (After the first execution of LOOP, ISAR contents are decremented to O'26'; after the second execution of LOOP, ISAR contents are decremented to O'25', etc.)

FOUR: If ISAR contains 7 as its' low order octal digit, continue; otherwise return to LOOP. In this case, continue if ISAR contains O'27' and return if ISAR contains O'20' through O'26'.

7.1.2 Incrementing Up, and Decrementing Down Scratchpad Buffers

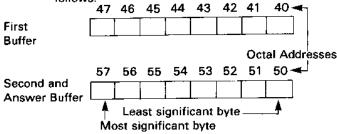
Now consider a simple variation of the above example; a 7-byte, positive number, stored in buffer 3, is added to another 7-byte, positive number, stored in buffer 4. Binary addition is performed as follows:

	COM		INITIALLY CLEAR THE
ONE	LISL	o	CARRY STATUS ADDRESS LOW ORDER BYTE OF EACH BUFFER
LOOP	LISU	4	ADDRESS FIRST BUFFER
TWO	LR	A,S	LOAD FIRST BUFFER BYTE INTO A
THREE	USU	5	ADDRESS SECOND BUFFER
FOUR	LNK		ADD ANY CARRY TO A
FIVE	LR	J,W	SAVE STATUS IN SCRATCHPAD BYTE 9
SIX	AS	S	ADD SAME BYTE OF SECOND BUFFER
SEVEN	LR	I,A	STORE ANSWER AND INCRE-
			MENT BYTE POINTER
EIGHT	LR	A,9	XOR CARRY BIT FROM
			SCRATCHPAD BYTE 9

TEN LR J,W WITH CURRENT CARRY BIT **ELEV** XS 9 **TWEL** LR 9.A THRT LR W,J BR7 LOOP **RETURN IF NOT END FORT**

Instructions in the above example execute as follows:

ONE Set the low order octal digit of ISAR to 0. Assume that numbers are stored in scratchpad buffers as follows:



LOOP Set the high order octal digit of ISAR to 4, thus addressing the next (initially least significant) byte of the first buffer.

TWO Load the next byte of the first buffer. By using S to identify ISAR as addressing the scratchpad, ISAR is not changed. This is important, since ISAR must not be incremented until the sum has been stored in the second buffer.

THREE By loading 5 into the ISAR high order digit, the corresponding byte of the second buffer is addressed.

FOUR Add any carry from the previous byte addition to the accumulator.

FIVE Save the status in J (scratchpad register 9).

SIX Add the second buffer byte (same byte number as first buffer) to the accumulator.

SEVEN Store the sum back into the second buffer, and this time increment the low order octal digit in ISAR, after storing the sum.

to tor by instruction FOUR, it is possible for 1 to be added to H'FF'. In this case the carry status would be set to 1 and the accumulator will be reset to 0. When the main addition is performed by instruction SIX, the carry status must be reset to 0. As a result the carry from FOUR will be lost. The correct carry to be used in the next byte addition is the OR of any carries from FOUR and SIX; EXCLUSIVE-OR is used since the two carry statuses cannot both be 1. The correct carry is created by instructions EIGHT through THRT, which perform these steps:

EIGHT Move status from FOUR to the accumulator.

TEN Move status from addition in instruction SIX to J, register 9 in the scratchpad.

ELEV EXCLUSIVE-OR J and the accumulator. The carry status can be 0

1

0 = 1 but never 1

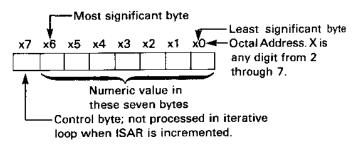
Return status to J.

THRT Return status to W.

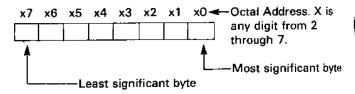
Note: instructions EIGHT to THRT can be simplified by replacing with BC FORT LR W, J

FORT If ISAR does not address the last byte of the second number buffer, return to LOOP; otherwise continue. (i.e., return to LOOP if ISAR holds O'50' through O'56'; continue if ISAR holds O'57'.)

This multibyte addition illustrates an important feature of scratchpad buffer utilization: increment ISAR if the high order buffer byte has a special significance; decrement otherwise. For example, as illustrated below numbers may use the high order buffer byte to hold sign, decimal point, or any other control information:



Consider now a variation of the multibyte addition, in which the significance of bytes is reversed:



By starting ISAR at x7, all eight bytes of the buffer will be processed identically, since ISAR will be decremented to x6 before the first execution of BR7. Thus the loop will be executed seven times, until ISAR decrements from x0 back to x7. Program steps are as follows:

Program	steps a	are as follo	ows:
	COM		INITIALLY CLEAR THE CARRY
			STATUS
ONE	LISL	7	ADDRESS LOW ORDER BYTE
			OF EACH BUFFER
LOOP	LISU	4	ADDRESS FIRST BUFFER
TWO	LR	A,S	LOAD FIRST BUFFER BYTE
			INTO A
THREE	LISU	5	ADDRESS SECOND BUFFER
FOUR	LNK		ADD ANY CARRY TO A
FIVE	L.R	J,W	SAVE STATUS IN SCRATCHPAD
			BYTE 9
SIX	AS	S	ADD SAME BYTE OF SECOND
			BUFFER
SEVEN	LR	D,A	STORE ANSWER AND DECRE-
			MENT BYTE POINTER
EIGHT	LR	A,9	OR CARRY BIT FROM SCRATCH-
		•	PAD BYTE 9
TEN	LR	J,W	WITH CURRENT CARRY BIT
ELEV	XS	9	
TWEL	LR	9,A	
THRT	LR	W,J	
FORT	BR7	LOOP	RETURN IF ISAR DID NOT DE-
			CREMENT FROM O'50' to 0'57'

Another variation of the same incrementing scratchpad addition is shown below. It takes advantage of the fact that the SUM is overstoring the second data buffer. If the result of the LNK instruction produces a carry the results in the accumulator must be zero; therefore, the sum is already correct and the following addition is needless. The carry bit logic is therefore simplified. This routine is only valid if the sum overstores one of the buffers.

	COM		
ONE	LISL	0	
LOOP	LISU	4	
TWO	LR	A,S	
THREE	LISU	5	
FOUR	LNK		
	BC	CKENK	
SIX	AS	S	
SEVEN	LR	S,A	
CKEND	LR	A,I	DUMMY INSTRUCTION TO INCISAR
	BR7	LOOP	

By changing:ONE LISL 0 to ONE LISL 7
and: CKEND LR A,I to CKEND LR A,D

The ISAR will be decrementing during the addition.

7.1.3 Using Scratchpad Registers as Counters

Scratchpad bytes 0 through 8 should be used for counters and pointers, and for short data operations that do not require data buffers.

Consider the simple use of a scratchpad byte as a counter. If an instruction sequence is to be executed some number of times between 1 and 256, proceed as follows:

ONE	LI	COUNT	LOAD COUNT INTO ACCUMULATOR
TWO	LR	0,A	MOVE TO SCRATCHPAD REGISTER 0
LOOP	_	_	START OF INSTRUCTION SE- QUENCE TO BE RE-EXECUTED
_			
_			
_			
TEST	DS	0	DECREMENT COUNTER
	RN7	LOOP	RETURN IF COUNTER IS NOT 0

COUNT is a symbol which must be equated to a numeric constant between 0 and 255. A value of 0 will cause 256 returns to LOOP, since TEST will decrement the counter to 255 on the first pass.

Note that scratchpad register 0 has been arbitrarily selected as the counter; any other register, up to register 8, could have been used.

7.1.4 Using Scratchpad Registers for Short Data Operations

Data operations that involve 4-byte (or smaller) data units are handled out of the first nine scratchpad registers.

Consider the addition of 16-bit signed binary numbers. Assume that the augend is stored in scratchpad registers 0 and

1 (1 most significant), and the addend is stored in scratchpad registers 2 and 3 (3 most significant). The result is to be returned in registers 2 and 3. Bit 7 of registers 1 and 3 holds the sign of the augend and addend, respectively. The addition program proceeds, directly accessing scratchpad registers:

ONE	LR	A,0	LOAD LOW ORDER AUGEND BYTE
TWO	AS	2	ADD ADDEND LOW ORDER BYTE
THRE	E LR	2,A	SAVE THE RESULT
FOUF	R LR	A,1	LOAD THE HIGH ORDER
			AUGEND BYTE
FIVE	LNK		ADD ANY CARRY FROM LOW
			ORDER BYTE ADD
SIX	BNO	EIGHT	IF THERE IS AN OVERFLOW,
SEVN	i BR	ERROR	THE RESULT IS TOO LARGE.
			MAKE AN ERROR EXIT
EIGH'	T AS	3	ADD THE HIGH ORDER
			ADDEND BYTE
NINE	LR	3,A	SAVE THE RESULT
TEN	BNO	OK	NO OVERFLOW, CONTINUE
ELEV	BR	ERROR	OVERFLOW, THE RESULT IS IN ERROR

The program executes as follows:

ONE	Load the low order augend byte into the accumulator,
-----	--

TWO add the low order addend byte and save the result.

THREE Carry is the only meaningful status after this addition. If the carry is set, it means that 1 must be added to the high order byte result.

FOUR Load the high order augend byte and add any carry

FIVE Now the overflow status is important, since it identifies a carry out of bit 6, the highest order data bit. (See Appendix A for clarification.)

SIX If the overflow status is set, branch out to an error SEVN handling program. If the overflow status is not set, continue. Only the overflow status need be tested.

If two positive numbers are being added, the important carry is out of bit 6, and there can be no carry out of bit 7, which must be 0 for both numbers.

If a positive and a negative number are being added, there can be no overflow.

If two negative numbers are being added, there must be a carry, since both 7 bits are 1. If there is no carry out of bit 6, an erroneous positive result is indicated, and the overflow bit is set.

EIGHT Add the high order addend byte and store the result. NINE

TEN Repeat of instruction SIX. OK is presumed to be the label of the instruction at which normal execution continues.

7.2 ROM, RAM AND DATA TABLES

There are two circumstances under which ROM and RAM memory outside the 3850 CPU scratchpad will be referenced to access data:

- In large or small F8 systems, data tables may be stored in ROM.
- In large F8 systems, data will be stored and retrieved out of RAM, via 3852 or 3853 interface devices; this allows large amounts of data to be stored and processed.

7.2.1 Reading Data Out of Tables in ROM

Various types of "table lookup" applications make extensive use of data tables stored in ROM, which will usually be a 3851 PSU device. There are two types of table lookup application, the sequential access and the random access.

Consider first text generation as an example of sequential access. Messages are stored, as ASCII character sequences, in ROM. The following instruction sequence outputs a message via the 3850 CPU I/O port 0:

	ORG	H'0600'	
MSG1	DC	C'PO'	
	DC	C'UL'	
	DC	C'TR'	
	DC	CAR,	
MSG2	DC	C'FI'	
WISUZ	DC	C'SH'	
	DC	C.RR.	
	UC	CBB	
	_		
	_	11/0400/	
0.1.	ORG	H'0400'	. C. LO. OLIFFED I FNOTH
ONE	LI	, ,	LOAD BUFFER LENGTH
TWO	LR	0,A	SAVE IN SCRATCH
			REGISTER O
THREE	DCI	MSG1	LOAD STARTING BUFFER
			ADDRESS INTO DCO
FOUR	CLR		INITIALIZE PORT O
	OUTS	0	
	INS	0	TEST FOR READY TO
			RECEIVE DATA
FIVE	BP	FOUR	ASSUME 1 IN BIT 7
			WHEN READY
SIX	LM		LOAD NEXT CHARACTER
SEVEN	OUTS	0	OUTPUT CHARACTER
EIGHT	D\$	0	DECREMENT CHARACTER
			COUNTER
NINE	BNZ	FOUR	RETURN FOR MORE
			CHARACTER\$

It is arbitrarily assumed that the eight ASCII characters 'POULTRYB' are stored in ROM, starting at memory location H'0600'; the program to output this character string starts at memory location H'0400'. The program proceeds as follows:

ONE The message length is computed by subtracting the symbol MSG1, which equals the starting address of 'POULTRYB', from the symbol MSG2, which equals the starting address of the next message, 'FISHB'. This message length is stored in scratchpad register O.

THREE The selected message starting address (provided by the symbol MSG1) is loaded into the DC0 registers.

FOUR These two instructions provide one of many ways in FIVE which programmed I/O may be set up. It is assumed that the receiving device connected to I/O port 0 has an I/O buffer containing all zeros until it is ready to receive data, at which time bit 7 of the I/O buffer is set to 1. The I/O buffer contents are continuously checked until bit 7 (the sign bit) is sensed as a 1 bit. The port is cleared prior to input when used for input and output. For details see Section 8.2.

SIX The contents of the ROM byte addressed by the DC0 registers is input to the accumulator; the DC0 registers contents are then incremented.

SEVEN. The accumulator contents are output to I/O port 0.

FIGHT The buffer length counter (in scratchpad byte 0) is decremented. If the result is not zero, return to instruction FOUR to process the next character.

Improved text writing programs are given in Section 10.2.

7.2.2 Accessing Data Tables in RAM

Two programming techniques need to be understood in connection with accessing RAM via 3852 or 3853 interface devices:

- a) Processing data between a source buffer and a destination buffer.
- b) Operating on data from two source buffers to create results that are stored in a destination buffer.

Consider first the example of data being moved from one RAM buffer to another. This procedure is very simple on the F8, requiring the following instruction sequence:

BUFA BUFB	EQU	H'2000' H'3080'	BUFFER ADDRESSES AND LENGTH HAVE BEEN ARBI- TRARILY SELECTED
CTHI	EQU	H'02'	CTHI AND CTLO TOGETHER
CTLO	EQU	H'80'	FORM A TWO BYTE BUFFER
	_		LENGTH COUNTER
ONE	LI	CTHI	USE SCRATCHPAD REG-
TWO	LR	1,A	ISTERS 0 AND 1 FOR THE
			BUFFER LENGTH
THREE	LI	CTLO	
FOUR	LR	0,A	
FIVE	DCI	BUFB	LOAD DESTINATION
			ADDRESS INTO DC0
SIX	XDC		SAVE IN DC1
SEVEN	DCI	BUFA	LOAD SOURCE ADDRESS
			INTO DC0
LOOP	LM		LOAD SOURCE BYTE
EIGHT	XDC		EXCHANGE ADDRESSES
NINE	ST		STORE IN DESTINATION
			BUFFER
TEN	XDC		EXCHANGE ADDRESSES
ELEV	DS	0	DECREMENT LOW ORDER
			COUNTER BYTE
TWEL	BNZ	LOOP	RETURN IF NOT ZERO
THRT	DS	1	DECREMENT H.O.
			COUNTER BYTE AND TEST IF

FRTN BC LOOP

IT WAS 0 RETURN IF H.O. BYTE WAS NOT 0

This program makes no assumptions regarding data buffer size or location. Decrementing 2-byte counters is illustrated in this program, enabling data to be moved between buffers of any size. Program steps proceed as follows:

ONE The two byte buffer length is loaded into scratchpad registers 1 (high order byte) and 0 (low order byte).

Notice that the 2-byte count must be loaded as two single byte quantities, since the LI instruction loads a single data byte into the accumulator.

FIVE Save the destination buffer starting address in DC1.

SIX First the address must be loaded into DC0 using a DCI instruction, then it is transferred to DC1 by the XDC instruction. Note that the DCI instruction has a 2-byte operand, therefore BUFA (and BUFB) are equated as 2-byte addresses.

SEVEN Load the source buffer starting address into DCO. (The destination buffer starting address is now in DC1.)

LOOP Transfer the contents of the memory byte addressed by the DCO registers to the accumulator. The address in the DCO registers is automatically incremented and now points to the next byte of the source buffer.

EIGHT Exchange addresses between the DC0 and DC1 registers. The DC0 registers now address the destination buffer.

NINE Store the contents of the accumulator in the memory byte addressed by the DCO registers. This is now the next destination buffer byte following the previous XDC instruction. After the data byte is stored in the destination buffer the address in the DCO registers is automatically incremented to address the next destination buffer byte.

TEN Exchange the contents of the DCO and DC1 registers so that the DCO registers again address the next source buffer byte.

to scratchpad registers 1 and 0, respectively, are decremented to zero. Until they decrement to zero, execution returns to LOOP. After they decrement to zero, execution continues at the instruction following FRTN.

Decrement logic proceeds as follows: the low order counter byte is decremented until it reaches zero. At this point the high order counter byte is decremented and simultaneously tested to see if it was decremented from 0. Since the DS instruction, in fact, adds H'FF' to the contents of the scratchpad byte, the carry status will be set unless H'FF' was added to H'00'. Therefore after executing a DS instruction, it is possible to test for a "decrement-from-zero" using the BC instruction. A branch-on-negative (BM) instruction would serve as well.

Consider the current case. Initially CTLO in scratchpad register 0 is decremented from H'80' to 0. At this point, CTHI in scratchpad register 1 contains 2 and there are 512 bytes of data remaining to be moved. The low order byte of the counter is again decremented from H'FF' through to 0, at which point CTHI in scratchpad register 1 contains 1, signifying that 256 bytes of data still remain to be moved. Now the high order byte of the counter in scratchpad register 1 is decremented from 1 to 0. Again the low order byte of the counter in scratchpad register 0 is decremented from H'FF' through to 0. This time no bytes remain to be moved; when the high order byte of the counter in register 1 is tested, it is found to be negative. As required, execution of the loop ceases and the branch occurs to instruction OUT, somewhere beyond the program.

Consider next a three buffer example; two positive, multibyte numbers are to be added and the sum is to be stored in a third multibyte buffer. This three buffer addition proceeds as follows:

BUFA BUFB BUFC	EQU EQU EQU	H'0838' H'0920' H'077C'	THE CONTENTS OF BUFA AND BUFB ARE ADDED. THE RESULT IS STORED IN BUFC.
CNT	_	H'0A'	10 BYTE BUFFERS ARE ASSUMED.
ONE TWO THREE FOUR	LIS LR DCI LR	CNT 0,A BUFC Q,DC	USE SCRATCHPAD REGISTER 0 AS A COUNTER SAVE THE ANSWER IN BUF- FER STARTING ADDRESS IN Q
FIVE SIX	DCI XDC	BUFA	SAVE THE SOURCE BUFFER ADDRESSES IN DC0 AND DC1
SEVEN EIGHT	DCI COM	BUFB	INITIALLY CLEAR THE CARRY BIT
LOOP	LR LM LR	L,W	INITIALIZE STATUS LOAD NEXT BYTE MOVE CARRY FROM
NINE	LNK		PRIOR ADD TO STATUS ADD ANY PREVIOUS CARRY
ten Elev Twel	LR XDC AM	J,W	SAVE STATUS IN J ADDRESS ADDEND BUFFER ADD CORRESPONDING ADDEND BYTE
THRT	XDC		READDRESS AUGEND BUFFER
FRTN	LR	H,DC	SAVE AUGEND ADDRESS IN H
FFTN	LR	DC,Q	LOAD ANSWER BUFFER ADDRESS
SXTN SVTN	ST LR	Q,DC	STORE THE ANSWER SAVE ANSWER BUFFER ADDRESS IN Q
EGTN	LR	DC,H	MOVE AUGEND ADDRESS BACK TO H
NNTN	BNC	TWT1	NO CARRY FROM AM INSTRUCTION
TWTY	LR	J,W	SAVE CARRY FROM AM INSTRUCTION

TWT1 DS 0 BNZ LOOP DECREMENT COUNTER RETURN FOR MORE

ELEV

to THRT

NNTN

TWTY

This program executes as follows:

ONE Scratchpad register 0 is used as a counter. Buffer TWO length has arbitrarily been assumed to be ten bytes.

THREE Since three 16-bit addresses have to be maintained, the following scheme will be used. At any time the buffer being accessed must have its address in DCO; however, DC1 plus the Q and H registers in the scratchpad memory are available to store addresses which are out of service. Accordingly, the answer buffer address will be saved in Q, the addend buffer address will be saved in DC1 and the augend buffer address will be saved in H whenever the answer buffer address is moved from Q to DCO. This scheme is illustrated in Figure 7-1.

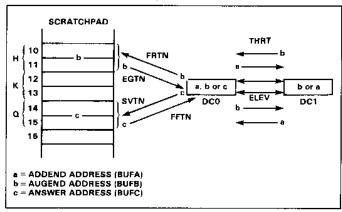


Fig. 7-1. Use of H, Q and DC1 Registers to Hold Three Buffer Addresses

Initially, it is necessary to load the answer buffer starting address into the Q registers, the addend buffer starting address into DC1 and the augend buffer address into DC0.

EIGHT The carry status must initially be set to 0 before the first two bytes are added. This is done by complementing whatever happens to be in the accumulator, since the complement instruction automatically sets the carry status to 0.

LOOP Load the next augend byte. The augend byte address is initially loaded into DCO and is returned to DCO at the end of the addition loop. After the augend byte has been loaded into the accumulator, DCO contents are automatically incremented.

NINE Add any carry from the previous byte addition to the augend byte in the accumulator. (Instruction EIGHT will have set the carry to 0 before the first two bytes are added.)

TEN As described in Section 7.1.2, addition logic must take account of the fact that when the link is added to the accumulator it is possible for the accumulator to contain H'FF' and the link to contain 1. In this case the result will be zero in the accumulator with 1 in the carry status. Subsequent addition of the addend byte will destroy the carry status. Instruction

TEN therefore saves the status register in the scratchpad J register (register number 9).

These three instructions switch the contents of the DCO and DC1 registers (DCO will now address the augend buffer). The contents of the next augend byte are added to the accumulator using binary addition. The augend buffer address in DCO is automatically incremented after performing the addition. Then the augend and addend addresses are exchanged so that after instruction THRT has been executed, DCO addresses the next addend byte and DC1 addresses the next augend byte.

FRTN The sum in the accumulator must now be saved in the next answer buffer byte. The answer buffer adto **EGTN** dress is in the scratchpad Q registers (registers 14 and 15). Before moving the answer buffer address to the DCO registers, the DCO registers contents are saved in the scratchpad H registers (registers 10 and 11). Instruction SXTN stores the answer byte in the accumulator into the answer buffer, then increments the answer buffer address in the DCO registers. Instruction SVTN saves the incremented answer buffer address back in the Q registers while instruction EGTN restores the augend address from the H register to the DC0 registers.

Observe that instructions FRTN through EGTN do not modify any of the status bits. As described in Section 7.1.2, the correct carry status to be used when adding the next two bytes is given by ORing the carry status from instructions NINE and TWEL If instruction TWEL created a 0 carry, then the carry saved by TEN is valid. If instruction TWEL created a 1 carry, it must be saved (by TWTY), to be recalled following LOOP. Since DS in TWT1 resets the carry to 0, it is necessary to save the carry status in 9, across the DS instruction. Note the difference in technique for preserving the carry status in this example, where DS resets the carry, as compared to Section 7.1.2, where statuses are not destroyed.

TWT1 The buffer length counter in scratchpad register 0 is now decremented. If it does not decrement to zero return to LOOP to add the next two bytes of the buffer.

7.3 SUBROUTINES

7.3.1 The Concept of a Subroutine

Any logic that will be used more than once can be written as a subroutine. For example, the 16-bit, signed binary addition program given in Section 7.1.4 may be needed at a number of different points within one large program. The routine may be repeated wherever it is needed. For example, the eleven instructions of the 16-bit signed binary addition routine may re-appear ten times within a program that uses this logic ten times. When the code is reproduced, without modification, it is wasting memory.

There are two ways in which an often used routine may be accessed by a program:

 The code can be reproduced with minor modifications, in which case it is treated as a Macro, as described in Section 7.4. The routine may be stored once, then accessed for execution each time it is needed. The routine is now called as a subroutine.

Figure 7-2 illustrates the concept of a subroutine.

There are four aspects of subroutines that must be considered; they are:

- The program steps of the logic being bundled as a subroutine.
- 2) How the subroutine is accessed. (This is termed "calling" the subroutine.)
 - 3) Returning from the subroutine after it has executed.
- 4) Passing data, as parameters, to the subroutine.

Each aspect of a subroutine will be examined with reference to the multibyte addition routine described in Section 7.2.2.

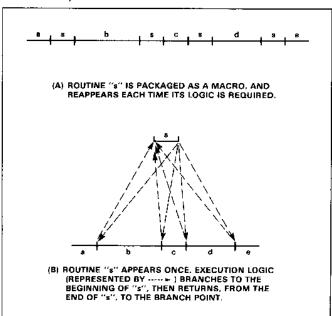


Fig. 7-2. Subroutine, as Compared to a Macro

7.3.2 Subroutine Program Steps

The instructions that implement any logic are the same within, or outside of, a subroutine. Compare the 16-bit addition program (AD16) in Section 7.3.3 with the equivalent program in Section 7.2.1; the only changes relate to entry and exit procedures.

7.3.3 Simple Subroutine Calls and Returns

As described in Sections 6.35 and 6.36, there are two instructions used to call a subroutine into execution.

Instruction PK saves the contents of the program counter (PC0) in the stack register (PC1), then loads the subroutine starting address from the K register (scratchpad registers 12 and 13) into the program counter.

Instruction PI saves the contents of the program counter in the stack register; it then loads the subroutine starting address (which is in the two object program bytes following the PI op code byte) into the program counter.

For straightforward returns from subroutines, the POP instruction, described in Section 6.37, moves the contents of the stack register back to PCO, thus effecting a return from a subroutine.

PK may also be used to return from a subroutine by having the return address in the K registers. LR PO,Q likewise may be used to return by having the return address in the Q register.

The starting address of a subroutine is identified by the subroutine name, which is the label of the first instruction to be executed in the subroutine.

Suppose the multibyte addition routine from Section 7.2.2 is to be named MADD, while the 16-bit addition routine from Section 7.1.4 is to be named AD16. These names are created by changing

ONE LI CNT USE SCRATCHPAD REGISTER 0

to the following equivalent instruction:

MADD LI CNT USE SCRATCHPAD REGISTER 0

For AD16, change

ONE LR A,O LOAD LOW ORDER AUGEND BYTE

to the following equivalent instruction:

AD16 LR A,0 LOAD LOW ORDER AUGEND BYTE

Note that although the first sequential instruction is also the first executed instruction for MADD and AD16, the first executed instruction may, in reality, be any instruction within the subroutine.

The last instruction executed by a subroutine must be POP, PK or LR PO,Q. Therefore, if for the moment the AD16 error return is ignored, subroutine AD16 becomes:

AD16	LR	A,0	FIRST INSTRUCTION EXECUTED FOR AD16
TWO	AS	2	EXECUTED FOR ADTO
THREE	LR	2,A	
FOUR	LR	A.1	
FIVE	LNK		
SIX	BNO	EIGHT	
SEVN	POP		IF THE RESULT IS TOO
			LARGE, RETURN
EIGHT	AS	3	
NINE	LR	3,A	
OUT	POP		RETURN AT END OF
			SUBROUTINE

Notice that a subroutine may have more than one exit.

MADD	LI	CNT	FIRST INSTRUCTION EXECUTED FOR MADD	MADD	ORG LI —	CNT CNT	USE SCRATCHPAD REGISTER 0
TWO	LR	0,Α			_		
	_			(rest of	subrout	ine follows h	ere)
(rant of	—	ine as in Section	nn 7 2 21				
(rest or		ine as in occir	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	·		OD THE MAI	IN DOOCDAM HAS BEEN
	_					SELECTED	IN PROGRAM HAS BEEN
TWT1	DS BNZ POP	O LOOP	RETURN FOR MORE RETURN AT END OF SUBROUTINE	*BÉFOR *ITS ST RÉGIS	E SUBI	H'1000' ROUTINE AD1 ADDRESS II	I 6 IS FIRST CALLED, LOAD NTO THE SCRATCHPAD K
using a	Pl instr	uction. Instruct	of subroutine AD16 being called ion sequences, with arbitrarily night be as follows:	ONE TWO THREE	LI LR LI LR —	H'09' KU,A H'80' KL,A	LOAD STARTING ADDRESS OF SUBROUTINE AD16 INTO K REGISTER
Memor Addres		N PROGRAM S	EGMENT	FOUR	 РК 		FIRST CALL TO SUBROUTINE AD16
	A' ONE	— Pl INC	AD16	FIVE	PI 	MADD	FIRST CALL TO SUBROUTINE MADD
		- 		SIX	— РК —		SECOND CALL TO SUB- ROUTINE AD16
H′2130	*SUE O' AD16		6 STARTS HERE A,0	SEVEN	PK		THIRD CALL TO SUB- ROUTINE AD16
Before	B' OUT	tion ONE is ex	ecuted, PCO contains H'102A'. xecuted, PCO contains H'2130'		etc		
and P	C1 cont at H'21	tains H'102D'.	Execution now proceeds from		ng" is	ed Subrouti the term app ther subroutin	plied to subroutines being called
and P	C1 stil	I contains H'1	Recuted, PCO contains H'213B' 02D'. Instruction OUT moves ng execution to TWO.	anothe prograi	r subro	outine. In factools, that it is	subroutine should not, itself, cal t, subroutines are such efficien s not uncommon to find subroutine , in large programs.
The fo	illowing I being (sequence illustrused to call MA	rates PK being used to call AD16, DD:	carry s	tatus fo	or multibyte : I CBIT. This s	se, where creation of the correct addition is packaged into a subsubroutine is equivalent to instruct the addition program in Section
*THIS			BEEN ARBITRARILY SELECTED	Subrou	tine CB	IT appears as	s follows:
AD16	ORG LR —	A,0	LOAD LOW ORDER AUGEND BYTE	CBIT	LR LR	A,9 J,W	MOVE STATUS FROM LNK ADDITION TO A MOVE STATUS FROM BYTE
	_						ADD TO W
(rest o	of subro	utine follows he	ere)		XS LR LR POP	9 A,9 W,J	EXCLUSIVE-OR STATUSES RETURN STATUS TO J VIAW

Subroutine MADD becomes:

*THIS ORIGIN FOR MADD HAS BEEN ARBITRARILY SELECTED

First try changing the addition program in Section 7.1.2 as follows:

COM		INITIALLY CLEAR THE
		CARRY STATUS
LISU	7	ADDRESS LOW ORDER
		BYTE OF EACH BUFFER
LISU	4	ADDRESS FIRST BUFFER
LR	A,S	LOAD FIRST BUFFER BYTE
		INTO A
LISU	5	ADDRESS SECOND BUFFER
LNK		ADD ANY CARRY TO A
LR	J,W	SAVE STATUS IN SCRATCH-
		PAD BYTE 9
AS	S	ADD SAME BYTE OF
		SECOND BUFFER
LR	D,A	STORE ANSWER AND INC-
		REMENT BYTE POINTER
PI	CBIT	CALL C STATUS SUB-
		ROUTINE
BR7	LOOP	RETURN IF NOT END
POP		RETURN FROM SUB-
		ROUTINE
	LR LISU LNK LR AS LR PI BR7	LISU 7 LISU 4 LR A,S LISU 5 LNK LR J,W AS S LR D,A PI CBIT BR7 LOOP

The addition routine has been converted into a subroutine named MADS.

When subroutine MADS is called, the return address is stored in PC1 to be returned to PC0 by POP instruction FIFT. Unfortunately, when CBIT is called at EIGHT, the PI instruction will also store a return address, the address of instruction FORT, in PC1. The POP at FIFT will no longer work, since it will branch execution back to FORT, thus forming an endless execution loop. (This type of program error is handled by the MAXCPU directive.)

When subroutines are nested one deep, (and this is often sufficient in simple F8 applications), the K registers in the scratchpad can be used to overcome the problem of wiping out PC1. For example, in Subroutine MADD, save PC1 in K upon entering MADS then use PK to return from MADD;

MADS	LR COM	K,P	SAVE RETURN ADDRESS INITIALLY CLEAR THE CARRY STATUS
	_		
	_		
	_		
EIGHT	PI	CBIT	CALL C STATUS SUB-
			ROUTINE
FORT	BR7	LOOP	RETURN IF NOT END
FIFT	PK		RETURN FROM SUB-
			ROUTINE FOR END

When subroutines are nested more than two deep, a stack is created in RAM to hold subroutine return addresses. When creating such a memory stack, it is wise to use PC1 and K as address conduits to the stack, never actually retaining address permanently in PC1 or K.

Consider the following simple, three-deep subroutine nest:

Arbitrary Memory Addresses

*MAIN PROGRAM

H'080A' ONE Ы SUB1 CALL FIRST SUBROUTINE H'080D' NXT1 FIRST SUBROUTINE RETURNS HERE ORG H'2073' *START OF FIRST SUBROUTINE H'2073' SUB1 FIRST INSTRUCTION OF SUB1 H'2082' TWO SUB₂ CALL TO SECOND SUB-ROUTINE H'2085' NXT2 SECOND SUBROUTINE RETURNS HERE H'2132' RET1 POP RETURN TO MAIN **PROGRAM** *START OF SECOND SUBROUTINE ORG H'12A4' H'12A4' SUB2 FIRST INSTRUCTION OF SUB₂ H'12B3' THRE PI SUB3 CALL TO THIRD SUB H'12B6' NXR3 THIRD SUBROUTINE **RETURNS HERE** H'12E2' RET2 POP RETURN TO FIRST SUBROUTINE *START OF THIRD SUBROUTINE ORG H'1558' H'1558' SUB3 FIRST INSTRUCTION OF SUB3

H'1596' RET3 POP RETURN TO SECOND SUBROUTINE

The sequence in which instructions are executed is given in Table 7-2, along with contents of PCO, PC1, and a "stack" in memory, where PC1 contents may be stored.

Notice that the first return address, H'080D', is passed to S0, the first two bytes of the memory stack. Similarly the second (H'2085') and third (H'12B6') return addresses are stored in the second and third byte pairs of memory stack. At all times, data in PC1 and K are merely the accidental result of logic needed to pass return addresses to the stack.

A memory stack "pointer" must be maintained. After each return address is stored in the stack, the stack pointer will identify the next free stack byte.

Return logic is the opposite of subroutine call logic. Before each call, the most recently stored return address (in the two stack bytes right behind the stack pointer) are moved to PC1, and the stack pointer address is decremented by 2.

The memory stack may either be in scratchpad memory, or in RAM memory.

REGISTERS/S					CONTE	NTS
INSTRUCTION	PCO	PC1	ĸ	First six	bytes o	f Memory Stack
LABEL 1)	, , ,	• • •	i "	so	S1	S2
· <u>-</u>	080A	7	7	?	7	?
ONE	2073	080D	?	?	. ?	?
SUB1	2073	0800	?	?	7	?
	2082	080D	0800	080D	?	?
TWO	12A4	2085	080D	080D	?	?
SUB2	12A4	2085	080D	080D	?	?
	12B3	2085	2085	080D	2085	?
THRE	1558	12B6	2085	080D	2085	?
SUB3	1558	1286	2085	0800	2085	7
	1596	12B6	1286	080D	2085	12B6
RET3	1286	12B6	12B6	080D	2085	12B6
NXT3	12B6	12B6	12B6	080D	2085	1286
	12E2	2085	2085	080D	2085	12B6
RET2	2085	2085	2085	080D	2085	1286
NXT2	2085	2085	2085	080D	2085	1286
	2132	080D	080D	080D	2085	12B6
RET1	080D	080D	080D	0800	2085	12B6

Table 7-2. Use of a Memory Stack for Executing Multiple Level Subroutines

Consider first a stack in scratchpad memory. By assigning one 8-byte buffer to serve as a memory stack, subroutines may be nested four deep. One byte at the beginning of scratchpad memory will serve as the stack pointer.

Subroutine CALL, described next, uses scratchpad bytes O'77' to O'70' as the memory stack, as illustrated in Figure 7-3. Scratchpad byte 8 is the stack pointer which must be initialized to H'77'.

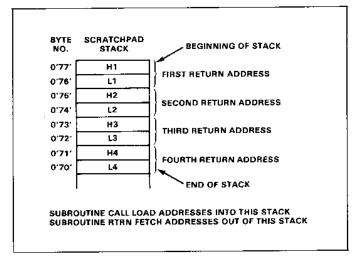


Fig. 7-3. Scratchpad Stack

Every subroutine must begin by saving PC1 contents in K, then calling CALL. This is illustrated as follows for subroutine MADD, which is the addition program from Section 7.2.2, converted into a subroutine:

MADD	LR	K,P	SAVE RETURN ADDRESS
			IN K
	PI	CALL	SAVE RETURN ADDRESS
			IN STACK
ONE	LIS	CNT	USE SCRATCHPAD
			REGISTER 0
TWO	LŔ	Ο,Α	AS A COUNTER
	_		
	_		
	_		

Since the call to CALL is preceded by PC1 contents being saved in K, PC1 is now free to hold the return address for CALL. Subroutine CALL has the following instructions:

CALL	LR	A,8	MOVE THE STACK POINTER TO ISAR
C1	LR	IS,A	
C2	CI	0′67′	CHECK FOR STACK OVERFLOW
C3	BZ	SFUL	STACK HAS OVERFLOWED. MAKE ERROR EXIT.
C5	LR	A,KU	MOVE KU TO STACK
C6	LR	D,A	
C7	LR	A,KL	MOVE KL TO STACK
C8	LR	S,A	DO NOT DECREMENT ISAR
C9	LR	A,IS	SAVE ISAR IN SCRATCH- PAD BYTE 8
C10	LR	8,A	
C11	DS	8	DECREMENT VALUE SAVED FOR ISAR
C12	POP		RETURN

The address of the next free stack byte is held in scratchpad byte 8. If this address is O'67', it means that O'70' is the

address of the last filled stack byte and the stack is full. Therefore when CALL is called, the stack address is tested for overflow by checking ISAR. A value of O'67' indicates the stack has overflowed. A value of O'77' indicates the stack is empty.

Subroutine CALL logic proceeds as follows:

CALL Move the stack address from scratchpad byte 8 to **ISAR**

Ċ1

C2 Test stack address for O'67'.

C3 It is assumed that SFUL is the label of an instruction which will handle stack full errors in any way required by program logic. This instruction branches execution to the instruction labeled SFUL.

C5 Move the contents of the K registers to the next two to free bytes of the stack. The ISAR is only decremented C8 once. The second decrement can be performed in the scratchpad, where O'70' will decrement to O'67' which is indicates stack full, rather than to O'77' which would erroneously indicate stack empty.

C9 Return the new contents of ISAR to scratchpad register A.

C10

C11 Decrement ISAR in scratchpad so that O'70' will decrement to O'67' which is full, not to O'77', which is empty.

C12 Return from subroutine CALL.

A subroutine that uses CALL to save its return address on the stack will use another subroutine, named RTRN, to return to the calling program. For example, subroutine MADD will now end with:

TWT2 ы **RTRN**

Since RTRN resets PCO, PI may be replaced with:

TWT2 **JMP** RTRN

Subroutine RTRN takes the address most recently stored in the stack and moves this address to PCO, effecting the desired return, as follows:

RTRN	LR	A,8	MOVE THE STACK POINTER TO ISAR
R1	LR	I\$,A	
	LR	A,I	INCREMENT ADDRESS TO
			LAST FILLED STACK BYTE
R2	LR	A,I	MOVE THE ADDRESS
R3	LR	QL,A	IDENTIFIED BY ISAR TO Q
R4	LR	A,S	
R5	LR	QU,A	
R6	LR	A,IS	RESTORE ISAR
R7	LR	8,A	
R8	LR	PO,Q	MOVE Q TO PCO

Subroutine RTRN executes as follows:

RTRN Move the stack pointer address from scratchpad R1 register 8 to ISAR. Increment ISAR to move address from the first free stack byte to the last occupied stack byte.

R2 Move the address identified by ISAR to QL and QU. Increment ISAR to point to the prior address. Leave to ISAR addressing what is now the first free byte. R5

R6 Save the new value of ISAR in scratchpad register 8. R7

R8 The subroutine that called RTRN now wishes to return to the address which RTRN has moved to the Q registers. RTRN can simply move this address from Q to PCO in order to effect the desired return.

For large stacks, RAM memory may be used for the memory stack. Only minor logic modifications are required to CALL and RTRN if the stack is in RAM. Assuming that the stack pointer is maintained in scratchpad registers 8 (high) and 7 (low), subroutine CALR and RTRR perform the same functions as CALL and RTRN but, for a RAM stack, that may be more than 256 bytes long.

As for the scratchpad stack, the RAM stack begins at a high RAM address, and the stack address is decremented as the stack gets filled. The end of the RAM stack is identified by a low address, represented using the symbols SPHI and SPLO for the high and low order bytes of the address.

The stack pointer address identifies the last filled stack byte.

*VERSION OF SUBROUTINE CALL FOR RAM STACKS, WITH *THE STACK POINTER IN SCRATCHPAD REGISTERS 8 AND 7.

			THE RESIDENCE TO STATE OF THE PROPERTY OF THE	
CALR	LR	A,7	LOAD LOW ORDER BYTE OF	
			STACK ADDRESS	
	LR	11,A	MOVE TO HL	
	CI	SPLO	COMPARE WITH END-OF-	
			STACK L.O. BYTE	
	LR	A,8	LOAD HIGH ORDER BYTE OF	
			STACK ADDRESS	
	LR	10,A	STORE IN HU	
	BNE	CA8	IF LOW ORDER BYTE DOES	
			NOT EQUAL STACK END,	
			CONTINUE	
	CI	SPHI	COMPARE HIGH ORDER	
			BYTES	
	BEQ	CA20	IF EQUAL, STACK HAS	
			OVERFLOWED	
CA8	LR	DC,H	MOVE H TO DC	
*SUBTRACT 2 FROM THE STACK ADDRESS, SINCE IT INCRE-				
*MENTS \	WHEN ME	MORY IS A	ACCESSED. BY SUBTRACTING	
				

*2, DCO ADDRESSES THE SECOND FREE STACK BYTE.

Li	H'FE'	
ADC		
LR	A,KU	MOVE KU TO STACK
ST		
LR	A,KL	MOVE KL TO STACK
ST		

*SUBTRACT 2 FROM STACK ADDRESS, SINCE IT HAS INCRE-*MENTED TO BEGINNING OF PREVIOUS ADDRESS.

LI	H'FE'	
ADC		
LR	H,DC	RESTORE STACK POINTER
LR	A.11	

	LR	7,A	
	LR	A,10	
	LR	8,A	
	POP		RETURN
CA20	JMP	SFUL	STACK FULL ERROR

The logic of CALR differs from the logic of CALL only in the way stack overflow is handled. Rather than leaving the stack pointer addressing the next free byte of the stack, the stack pointer addresses the last used byte of the stack. Stack overflow is tested for by comparing the contents of the stack pointer with an address that has been specified as the end of the stack. This end of stack address can be equated to any value that is convenient to program logic.

Notice that whenever memory is accessed via the DC registers the address in the DC registers is automatically incremented. The stack in RAM has arbitrarily been selected to begin at a high address and end at a low address, which is the opposite direction as seen by the DC registers. Since the DC registers address the last filled byte of the stack, two must be subtracted from this address so that two bytes of address data may be loaded into the stack without overloading the last filled byte. Also, after the two bytes of address have been loaded into the stack, two must again be subtracted from the address in the DC registers so that the address once again identifies the last filled byte of the stack.

Although the sense of direction of the stack is inverted with regard to the DC registers when CALR is executed, stack direction will agree with the DC registers when RTRR is executed. Since stack access involves a forward and then a reverse direction, it makes no difference what is chosen to be forward and what reverse; either CALR or RTRR must access the stack by decrementing addresses. This is contrary to the sense of the DC registers which only increment addresses.

*VERSION OF SUBROUTINE RTRN FOR RAM STACKS, WITH *THE STACK POINTER IN SCRATCHPAD REGISTERS 8 AND 7.

*THE ST	ACK POII	NTER IN SCI	RATCHPAD REGISTERS 8 AND 7.
RTRR	LR	A,8	MOVE THE STACK POINTER
			TO H
	LR	10,A	
	LR	A,7	
	LR	11,A	
	LR	DC,H	MOVE THE STACK POINTER TO DC
	LM		LOAD HIGH ORDER BYTE
	LR	QU.A	OF RETURN ADDRESS
			INTO QU
	LM		LOAD LOW ORDER BYTE
	LR	QL,A	OF RETURN ADDRESS
			INTO QL
	LR	H.DC	SAVE STACK POINTER IN
	LR	A,10	SCRATCHPAD BYTES 8
			AND 7
	LR	8,A	
	LR	A,11	
	LR	7,A	
	LR	PO.Q	MOVE Q TO PCO

In F8 systems that have a 3852 and/or 3853 Memory Interface device, if DC1 is not used to address data buffers, it can be used effectively as a RAM stack pointer.

7.3.5 Multiple Subroutine Returns

Observe that the 16-bit addition subroutine in Section 7.1.4 requires two returns, one for an overflow in the answer, the other for a valid execution.

Frequently subroutines may execute with more than one possible outcome. The most efficient way of handling such logic is to build multiple returns into the calling program and into the called subroutine. Here are some examples. First, an error return:

U (1)	_	
	• •	 ERROR RETURN FROM SUB1 NON-ERROR RETURN FROM

Next, multiple valid returns:

Pl	SUB2	
BR	PLUS	RESULT IS POSITIVE
BR	ZERO	RESULT IS ZERO
_		RESULT IS NEGATIVE
_		

Subroutines RTRN and RTRR can easily be rewritten to handle multiple returns. Instructions will be added that return, to PCO, the last address entered into the stack, plus any displacement that is in QL (scratchpad register 15) when the subroutine is called. RTRN will now appear as follows, renamed RTRD:

RTRD	LR	A,8	MOVE STACK POINTER TO ISAR
	LR	IS,A	
	LR	A,l	INCREMENT ADDRESS TO
			LAST FILLED BYTE
	LR	A,QL	LOAD LOW ORDER
			ADDRESS BYTE
	AS	l l	ADD DISPLACEMENT IN QL
	LR	QL,A	STORE RESULT IN QL
	LR	A,S	LOAD HIGH ORDER
			ADDRESS BYTE
	LNK		ADD ANY CARRY FROM LO
			BYTE ADDITION
	LR	QU,A	STORE RESULT IN QU
R6	LR	A,IS	RESTORE ISAR
R7	LR	8,A	
	LR	PO,Q	MOVE Q TO PCO

Taking advantage of RTRD, the 16-bit addition subroutine will become:

AD16	LR	K,P	SAVE RETURN ADDRESS IN K
	PI	CALL	SAVE RETURN ADDRESS IN SCRATCHPAD STACK
	LR	A,0	LOAD LOW ORDER AUGEND BYTE
	AS	2	ADD ADDEND LOW ORDER BYTE
	LR LR	2,A A,1	SAVE THE RESULT LOAD HIGH ORDER

			AUGEND BYTE	
	LNK		ADD ANY CARRY FROM	
			LOW ORDER BYTE ADD	
	BNO	EIGHT	IF THERE IS A CARRY OR	
			AN OVERFLOW, RETURN	
			WITHOUT DISPLACEMENT	
	BR	ERR		
EIGHT	AS	3	ADD THE HIGH ORDER	
			ADDEND BYTE	
	LR	3,A	SAVE THE RESULT	
	LI\$	2	FOR A GOOD RETURN, ADD	
			2 TO RETURN ADDRESS	
	BNO	OK	AGAIN IF THERE IS A	
			CARRY OR OVERFLOW	
ERR	CLR		FOR AN ERROR RETURN,	
			ADD 0 TO RETURN	
			ADDRESS	
OK	LR	QL,A	SAVE THE DISPLACEMENT	
			IN QL	
	PI	RTRD		
Now AD1	Now AD16 will be called as follows:			
	_			

— PI AD16
BR ERROR ERROR RETURN
— GOOD RETURN

7.3.6 Passing Parameters

Subroutine MADD, as described so far, is of limited value, since the starting addresses of buffers BUFA, BUFB and BUFC are fixed. MADD will only add the contents of two fixed buffers and store the result in a third, fixed buffer. The subroutine would be far more useful if buffer locations and lengths could be specified at the time the subroutine is called. This can be done and is called parameter passing.

The parameters to be passed to a subroutine are listed, in the calling program, after the subroutine call. For example, the call to MADD would appear as follows:

VALA VALB VALC COUNT	EQU EQU EQU	H'2080' H'2088' H'2800' H'08'
	_	
	_	

*CALL TO MADD IN MAIN PROGRAM

O MADI	JIN MAIN FI	NUGRAIVI
Pl	MADD	CALL SUBROUTINE MADD
DÇ	VALA	VALA IS A TWO BYTE
		AUGEND BASE ADDRESS
DC	VALB	VALB IS A TWO BYTE
		ADDEND BASE ADDRESS
DC	VALC	VALC IS A TWO BYTE
		ANSWER BASE ADDRESS
DÇ	COUNT	COUNT IS A ONE BYTE
		BUFFER LENGTH
BR	ERROR	RETURN HERE IF THERE IS
_		AN ERROR
_		RETURN HERE FOR
_		SUCCESSFUL EXECUTION

Once MADD is entered, the return address in PC1 is in fact, the address where the augend buffer starting address will be found. Before entering into the body of the subroutine, MADD will load parameters into H, Q and DC1. This is illustrated below for subroutine MADD with parameters, renamed MADP.

MADP	LR	K,P	SAVE THE RETURN ADDRESS
	PI	CALL	SAVE THE RETURN ADDRESS
	LR	A,KU	IN THE STACK MOVE THE RETURN ADDRESS FROM K
	LR	10,A	TO DCO. DCO WILL NOW ADDRESS THE FIRST OF THE
	LR	A,KL	TWO BYTES IN WHICH VALA IS STORED, FOLLOWING
	LR LR	11,A DC,H	THIS CALL TO MADP LOAD PARAMETER ADDRESS INTO DCO
	LM		LOAD VALA INTO H
	LR	10,A	· · · · · · · · · · · · · · · · · ·
	LM	-,-	
	LR	11,A	
	XDC	, ,	MOVE VALA FROM H TO DC1 BY
	LR	DC.H	EXCHANGING DC0 WITH DC1
	XDC	20,1	MOVING VALA TO DCO, THEN
	LM		AGAIN EXCHANGING DC0 AND DC1
	LR LM	10,A	NEXT LOAD VALB INTO H
	LR	11,A	
	LM		LOAD VALC INTO Q
	LR	QU,A	
	LM		
	LR	QL,A	
	LM .		LOAD COUNT INTO SCRATCHPAD BYTE 0
	LR	0,A	
	LR	DC,H	MOVE VALB TO DCO
*THE MU		ADD MAY I	NOW BEGIN
	COM		INITIALLY CLEAR THE CARRY BIT
	LR	J,W	
LOOP	LM		LOAD THE NEXT AUGEND BYTE
	LR	W,J	ADD AND DODING CARRY
	LNK	1367	ADD ANY PRÉVIOUS CARRY
	LR	J,W	SAVE STATUS IN J
	XDC		ADDRESS ADDEND BUFFER
	AM		ADD CORRESPONDING
	XDC		ADDEND BYTE READDRESS AUGEND BUFFER
	LR	H,DC	SAVE AUGEND ADDRESS IN H
	LR	DC,Q	LOAD ANSWER BUFFER ADDRESS
	ST		STORE THE ANSWER
	LR	Q,DC	SAVE THE ANSWER BUFFER ADDRESS IN Q
	LR	DC,H	MOVE AUGEND ADDRESS BACK FROM H
	BNC LR	TWT1 J,W	NO CARRY FOR NEXT BYTE

TWT1	DS		DECREMENT COUNTER
	BNZ	LOOP	RETURN FOR MORE
	LR	W,J	
	LIS	9	LOAD A FOR A GOOD
			RETURN
	BNC	OUT	TEST FOR A FINAL CARRY
	LIS	7	THERE IS A CARRY,
			PREPARE FOR ERROR
OUT	LR	QLA	SAVE THE DISPLACEMENT
			IN QL
	PI	RTRD	RETURN FROM SUBROUTINE

Parameter passing works as follows:

A subroutine that expects to receive parameters will initiate execution with the return address pointing to the first byte of the parameter list, and not to the instruction which must be executed once program control returns to the calling program. In other words, after subroutine CALL has executed, the address saved on the stack is the address of the first parameter, not the address of the next instruction to be executed in the calling program. Initial subroutine logic must therefore move the address of the first parameter to the DCO registers, and must then appropriately load parameters into registers where they will be needed for execution of the subroutine. This process is straightforward data movement and requires no special explanation.

Observe that when subroutine RTRD is called to effect a return to the calling program (in this case the main program which called MADP) the return address, as stored in the stack, is still the address of the first parameter byte. Therefore, before RTRD is called, the value loaded into the accumulator is not zero or a displacement representing multiple returns. It is the number of bytes of parameters, or the number of bytes of parameters plus the displacement of the multiple returns. For example, subroutine MADP requires seven bytes of parameter information to follow the call to MADP. Therefore, an error return from MADP requires the value 7 to be loaded into the accumulator before RTRD is called; a value of 9 must be loaded into the accumulator before RTRD if there is no error.

7.4 MACROS

Observe in Figure 7-2(A) that an instruction sequence may reappear in a program each time it is reused. Such an instruction sequence may be identified as a macro.

Refer to Figure 7-2. If the instruction sequence represented by "s" is a subroutine (we will assume that it is named SUB1), then wherever the logic of SUB1 is required, a PI or PK instruction in the main program will cause execution to branch to one set of code, as illustrated in Figure 7-2(B) and described in Section 7.3. If, on the other hand, the logic of SUB1 is to be treated as a macro, then the name SUB1 will appear in the mnemonic field of the source program as though SUB1 were the mnemonic for an instruction. In the object program, the assembler will actually insert the sequence of instructions represented by SUB1 wherever SUB1 appears in the source program, as illustrated in Figure 7-2(A).

7.4.1 Defining and Using Macros

Beginning with a very simple example, suppose the instruction sequence which creates the correct carry status in multibyte addition routines is to be identified as a macro named CBIT, rather than as a subroutine named CBIT. The macro is defined in the source program by enclosing the instructions of the macro between assembler directives MACRO and MEND, as follows:

MACRO		
CBIT		
LR	A,9	MOVE STATUS FROM LNK
		ADDITION TO A
NI	H'02'	MASK OUT ALL BUT C BIT
LR	J,W	MOVE STATUS FROM BYTE
		ADD TO W
AS	9	ADD STATUSES
LR	9,A	RETURN STATUS TO J VIA W
LR	W,J	
MEND		

In theory, a macro definition, as illustrated above, could appear anywhere in a source program; the assembler simply takes everything between the MACRO and MEND directives and holds it to one side, inserting the instructions whenever it sees the macro name appear in the mnemonic field of an instruction. In practice, it is good programming to collect macro definitions either at the very beginning or at the very end of a source program.

As an example of how a macro works, subroutine MADD could specify CBiT as a macro, rather than as a subroutine, as follows:

(Body of subroutine MADD) MOVE AUGEND ADDRESS **EGTN** LR DC,H BACK TO H SAVE PC1 IN K LR K.P INSERT INSTRUCTIONS CBIT NNTN FROM CBIT MACRO HERE DECREMENT COUNTER TWT1 DS 0 LOOP RETURN FOR MORE BNZ RETURN FROM SUBROUTINE TWT2 PK

When the assembler assembles the above instruction sequence, instruction NNTN will be replaced directly by the six instructions listed between MACRO CBIT and MEND. For this reason, the programmer may look upon a macro simply as a short-hand method of writing source programs (i.e., a method of taking the tedium out of re-writing the same instruction sequence again and again).

FOR END

7.4.2 Macros with Parameters

A simple macro, as illustrated for CBIT in Section 7.4.1, is of limited value; it makes an object program longer, but it makes writing the source program easier. The program executes faster since the PI and POP instructions are not executed.

Macros with parameters are more useful. Refer to subroutine MADP, in Section 7.3.6. In order to make the multibyte addition program MADD useful, it was modified so that the call to subroutine MADD could be followed by seven bytes

of parameter data, including three 2-byte addresses and a single byte buffer length counter. Instructions at the beginning of subroutine MADP transfer these parameters to the H, Q and DC1 registers before performing the multibyte addition, thus allowing subroutine MADP to perform multibyte additions on the contents of buffers that can have any length and can be anywhere in memory.

The multibyte addition may also be specified as a macro, where the macro name is followed by a number of parameters. In this case, the parameters would again be three addresses and a byte count. Now when the assembler substitutes the instruction sequence of the multibyte add for the macro name appearing in an instruction mnemonic, it changes instructions within the sequence according to parameter specifications.

When a macro is defined, macro parameters are listed after the macro name with an ampersand as the first character of each parameter and one space separating parameters. This is illustrated for macro MADP below:

	MACRO		
	MADP	&VALA &	VALB &VALC &CNT
ONE	ĻI	&CNT	USE SCRATCHPAD
			REGISTER O
TWO	LR	0,A	AS A COUNTER
THREE	DCI	&VALC	SAVE THE ANSWER BUFFER
FOUR	LR	Q,DC	STARTING ADDRESS IN Q
FIVE	DCI	&VALA	SAVE THE SOURCE BUFFER
SIX	XDC		ADDRESSES IN DC0 AND DC1
SEVEN	DCI	&VALB	
EIGHT	COM		INITIALLY CLEAR THE
			CARRY BIT
	LR	J,W	
LOOP	LM		LOAD THE NEXT AUGEND
			BYTE
	LR	W,J	CARRY FROM PRIOR ADD
			TO STATUS
NINE	LNK		ADD ANY PREVIOUS CARRY
TEN	LR	J,W	SAVE STATUS IN J
ELEV	XDC		ADDRESS ADDEND BUFFER
TWEL	AM		ADD CORRESPONDING
			ADDEND BYTE
THRT	XDC		READDRESS AUGEND
			BUFFER
FRTN	LR	H,DÇ	SAVE AUGEND ADDRESS
			IN H
FFTN	LR	DC,Q	LOAD ANSWER BUFFER
01/71	^-		ADDRESS
SXTN	\$T	DO 11	STORE THE ANSWER
EGTN	LR	DC,H	MOVE AUGEND ADDRESS
	BNC	TWT1	BACK TO H NO CARRY FOR NEXT BYTE
TWTY	LR	J.W	SAVE CARRY FROM AM
17711	LN	3,00	INSTRUCTION
TWT1	DS	0	DECREMENT COUNTER
14414	BNZ	LOOP	RETURN FOR MORE
	MEND	2001	TOTAL TOT WORL

Any program can tell the assembler to insert the instruction sequence specified by macro MADP, changing the symbols &CNT, &VALA, &VALB and &VALC to any four symbols specified in the operand field of the instruction that references macro MADP. For example, in order to reproduce the multibyte addition instruction sequence as illustrated in Section 7.2.2, the following instruction would have to appear:

MADP BUFA BUFB BUFC CNT

When the assembler encounters the above instruction, it will substitute all of the instructions listed between MACRO MADD and MEND; however wherever it finds &CNT it will replace it with CNT, wherever it finds &VALA, &VALB or &VALC it will substitute BUFA, BUFB or BUFC, respectively.

7.4.3 Rules for Defining and Using Macros

The following few rules apply to the use and definition of macros:

- No macro can be referenced in a program unless it has been defined as a macro, using the MACRO and MEND assembler directives.
- When a macro is defined, it can reference another macro so long as the other macro is defined separately elsewhere.
- 3) If a macro is defined with parameters, then every time the macro is specified within the body of a program, the specification must have a valid symbol in the operand field, corresponding to every parameter in the macro definition.

7.4.4 When Macros Should be Used

There are two circumstances when macros are more efficient as a programming tool than subroutines.

Short instruction sequences that are frequently used within a program are often better represented as macros, if subroutine addresses are being maintained in a stack. It takes a certain amount of time to store a return address in a stack, then at the end of a subroutine to retrieve the address from the stack. If the body of the subroutine is quite short, the time taken to maintain the stack may become excessive. Under such circumstances it is better to reproduce the instruction sequence as a macro wherever it is needed within a program.

Subroutines which require a large number of parameters to be passed from the main subroutine are frequently better represented as macros; a considerable number of instructions may be needed to move the parameters from the parameter list that follows the subroutine call, to the registers or memory locations out of which the subroutine will access the parameters. Consider subroutine MADP; if this subroutine is called only two or three times it is probably more efficient to represent it as a macro rather than as a subroutine.

Macros always result in faster program execution than subroutines. Macros may result in longer programs than subroutines. Therefore, in an application where speed is important, macros should be used in preference to subroutines.

7.5 JUMP TABLES

A jump table is a programming device which is particularly useful in microprocessor applications. A jump table allows an index number to be loaded into the accumulator after which program execution jumps to a memory location which is dedicated to that index number.

Jump tables are commonly used in switching applications, where data may be received from, or control signals may have to be sent to, one of many external devices.

7.5.1 Jump Table Using Jump Instructions

The F8 instruction set is well-suited to execution of jump tables. As illustrated, one jump table may serve an entire application of diverse operations. The jump table consists of nothing more than a large number of jump instructions. To execute the jump table, a program simply loads an I.D. number into the accumulator, then jumps to the table logic. The table logic adds the contents of the accumulator, three times, to the address of the first jump instruction, which is stored in the DCO registers. The sum is moved (via the Q registers) to the program counter and the jump is effected.

*JUMP TABLE PROGRAM. JUMP NUMBER IS ASSUMED TO *BE IN THE ACCUMULATOR.

DE 114 1	IIL MOOO	WICETION	•
JUMP	DÇI	JMPO	LOAD THE FIRST JUMP
			ADDRESS INTO DCO
	ADC		ADD THREE TIMES THE
			BRANCH
	ADC		INDEX TO DCO, FOR THE
	ADC		THREE BYTES OF A JMP
			INSTRUCTION
	LR	Q,DC	MOVE DC0 TO PC0
	LR	P0,Q	JUMP OCCURS HERE
JMP0	JMP	AO	
	JMP	A1	
	JMP	A2	
	JMP	A3	
	JMP	A4	
	etc.		

7.5.3 Jump Table Using Displacement Tables

Under some circumstances the addresses of the jump table may all be within 256 bytes of each other. When this situation exists, only a displacement need be created in the table. This displacement, when added to some base address, will produce the address required for the jump. Notice that in the following example, entry FOUR and FIVE go to the same location. This is a variation that is quite useful. Perhaps the values 4 and 5 are invalid and an error routine needs to be called. The jump table will satisfy this condition in a most efficient manner without a separate compare instruction for each invalid value. Also notice that the entry points need not be in any particular sequence; however, in this example A1 must be the first entry point encountered, and it must have the lowest address in order for the arithmetic to be valid.

This displacement table is most efficient since the table values are only one byte each. If an entry is beyond the 256 range it is possible to treat it as a special case within the table. Notice that A6 is more than 256 bytes beyond the start of A1 and is too large to insert before A4. To include it insert a JMP A6 prior to the coding at A4. If this instruction is labeled A66, an entry in the table would be:

SIXS DC (A66-A1-128) = 82

The value of THRE would now become 85.

7.5.2 Jump Table Using Address Constants

Another jump table technique uses a table of addresses which are indexed as in the previous example. However, instead of a JUMP (LR PO,Q) to the jump table, the address is loaded from memory into Q. The LR PO,Q instruction then causes a direct jump to the address in Q. The major advantage of this technique is that the table is only two bytes per entry, as compared to three bytes in the previous example. It also executes using fewer instruction cycles.

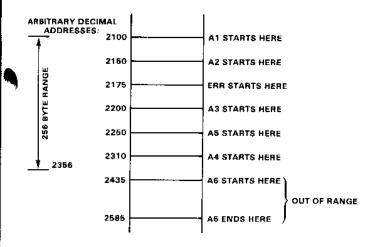
*THE JUMP NUMBER IS ASSUMED TO BE IN THE

*ACCUMULATOR			
JUMP	DCI	JMPO	LOAD THE FIRST JUMP
			ADDRESS INTO DCO
	ADC		ADD TWICE THE JUMP
	ADC		NUMBER, DC0 NOW AD-
			DRESSES A JUMP ADDRESS
	LM		LOAD FIRST BYTE OF JUMP
			ADDRESS
	LR	QH,A	STORE IN QH
	LM		LOAD SECOND BYTE OF
			JUMP ADDRESS
	LR	QL,A	STORE IN QL
	LR	PO,Q	BY MOVING Q TO PO, FORCE
			JUMP
JMP0	DC	A0	
	DC	A1	
	DC	A2	
	DC	A3	
	DC	A4	
	etc.		•

*THE JUMP NUMBER IS ASSUMED TO BE IN THE *ACCUMULATOR

JUMP	DCI	ZERO	LOAD FIRST TABLE
			LOCATION INTO DC0
	ADC		ADD VALUE FROM
			ACCUMULATOR
	LM		LOAD TABLE VALUE
			TO ACCUMULATOR
	DCI	(A1+128)	LOAD FIRST ORIGIN
	ADC		ADD DISPLACEMENT
			VALUE ADDED TO DO
	LR	Q,DC	RECALL DC TO Q
	LR	P0,Q	JUMP TO ROUTINE
ZERO	DC	(A1-A1-128)	VALUE = -128
ONE	DC	(A2-A1-128)	VALUE = - 78
TWO	DC	(A5-A1-128)	VALUE = 22
THRE	DC		VALUE = 82
FOUR	DC	•	VALUE = - 53
FIVE	DC	(VALUE = - 53
SIX	DC	(A3-A1-128)	
SVEN	DC	(A6-A1-128)	VALUE = 207
			TOO LARGE!

Values are displaced by -128 to take into account the fact that the DCI instruction points to the middle of the table (A1+128). Therefore, addresses are created as shown on the following page.



7.6 STATUS, BITS AND BOOLEAN LOGIC

The F8 instruction set is rich in boolean logic instructions which are very useful in applications manipulating bits and control lines.

Examples given in the following subsections demonstrate some elementary uses of boolean logic instructions, along with some less obvious but commonly needed routines.

7.6.1 Manipulating Individual Bits

Immediate boolean instructions specify data in the operand of the instruction; they may be used to set or reset individual bits within the accumulator.

To reset one or more bits within the accumulator, AND the accumulator contents with a mask which is the complement of the bits to be reset. For example, the following instructions will reset bit 3 of scratchpad byte 1:

LR	A,1	LOAD SCRATCHPAD BYTE
		1 INTO A
NI	H′F7′	MASK OUT BIT 3
LR	1,A	RETURN TO SCRATCHPAD
		BYTE 1

Similarly, individual bits can be set by ORing the accumulator with a mask which has a 1 in every bit position that is to be set. For example, bit 3 of scratchpad byte 1 contents can be set to 1 as follows:

LR	A,1	LOAD SCRATCHPAD BYTE
		1 INTO A
OI	H'04'	SET BIT 3
LR	1,A	RETURN TO SCRATCHPAD
		RYTE 1

Masks may also be accessed out of RAM or scratchpad memory. The following instruction sequence takes every byte from a buffer CNT bytes long, starting at BUFA; it sets to 0 the bits specified by a mask stored in a memory byte addressed by MASK. BUFA, CNT and MASK are symbols which have been given arbitrary values below.

EQU EQU	H'2380' H'08FF' 50
	EQU

	DCI	MASK	STORE THE MASK ADDRESS IN H
	LR	H,DC	
	DCI	BUFA	STORE THE BUFFER
			STARTING ADDRESS IN Q
	LR	Q,DC	
	LI	CNT	USE SCRATCHPAD BYTE
			0 AS A
	LR	0,A	COUNTER
LOOP	LM		LOAD NEXT BYTE
L1	LR	DC,H	LOAD MASK ADDRESS
L2	NM		AND ACCUMULATOR WITH
			MASK
L3	LR	ĐC,Q	RELOAD BYTE ADDRESS
L4	ST		STORE MASKED BYTE IN
			ORIGINAL BYTE POSITION
L5	LR	Q,DC	SAVE INCREMENTED
			BUFFER ADDRESS IN Q
L6	DS	0	DECREMENT COUNTER
L7	BNZ	LOOP	RETURN FOR MORE

In addition to demonstrating use of the NM instruction, the above example shows how to process data in a single buffer, restoring a modified byte to its original byte position.

The program proceeds as follows:

The instructions preceding LOOP load the mask address into H and the beginning buffer address into Q. The buffer length is loaded into scratchpad byte A which is used as a counter.

- LOOP The data counter holds the initial buffer address when this instruction is first executed and the next byte address on all subsequent executions of this instruction. This instruction therefore loads the next byte from BUFA.
- Load the mask address from the H registers into the data counter, wiping out the incremented buffer address that resulted from instruction LOOP.
- AND the contents of the accumulator with the mask byte. The fact that the AND with memory instruction will increment the address in the data counters is not consequential since this incremented address is not saved. On the next execution of this instruction, the original mask address stored in the H registers will be reused.
- L3 Reload the buffer address from the Q registers. This is the same address that was used by instruction LOOP.
- L4 Store the contents of the accumulator back in the buffer. Since the address loaded by L3 is the same address as was used by instruction LOOP, the masked byte will be stored back in the same memory location from which it was loaded.
- L5 This time save the incremented address in the data counters back in the Q registers.
- L6 Decrement the counter in scratchpad byte 0. If
 L7 the result is zero, end. If the result is not zero process the next byte of the buffer.

By using the NM instruction, the above example is resetting (to 0) selected bits from every byte in BUFA. By merely replacing the NM instruction with an OM instruction, selected bits from every byte of BUFA could be set to 1.

By storing the mask byte in a scratchpad register, the program can be greatly simplified. The instruction sequence below is similar to the previous example, but the mask byte is stored in scratchpad register 1, and the DC1 registers are used to hold the buffer address, rather than the Q registers.

Notice that at the LM instruction (LOOP), DC0 is incremented; prior to the ST instruction, DC0 and DC1 are exchanged. The ST instruction then increments DC0, thus both addresses remain synchronized.

MASK BUFA CNT	EQU EQU	B'any bina H'2380' 50	ary value'
	_		
	_		
ONE	LI	MASK	
TWO	LR	1,A	
	DCI	BUFA	STORE BUFFER ADDRESS
	XDC		IN DC0 AND IN DC1
			REGISTERS
	DCI	BUFA	
	LI	CNT	USE SCRATCHPAD BYTE 0
	LR	0,A	AS A COUNTER
LOOP	LM		LOAD NEXT BYTE
THREE	NS	1	AND WITH MASK IN
			SCRATCHPAD BYTE 1
	XDC		
	ST		STORE IN ORIGINAL LOCATION
	DS	0	DECREMENT COUNTER
	BNZ	LOOP	RETURN FOR MORE

Again this routine can be simplified even further by deleting instructions ONE and TWO and changing instruction THREE to one of the following:

NI	MASK	AND WITH MASK
OI.	MASK	OR WITH MASK
ΧI	MASK	EXCLUSIVE OR WITH MASK

This change would result in saving two bytes, however the loop time would be increased by 1.5 cycles.

7.6.2 Testing for Status

The EXCLUSIVE-OR instruction is very useful as a means of detecting changed statuses. There are many applications in which it will be necessary to keep a record of status for various control lines, and to detect when individual control line statuses change and how they change. As illustrated in the instruction sequence below, eight control lines have their statuses maintained in scratchpad byte 3. When new statuses are input from I/O port 0, they are temporarily saved in scratchpad byte 4. By EXCLUSIVE-ORing the new and old statuses, the accumulator identifies those status bits which have changed. By ANDing the changed status indicators with the old status, those indicators which went from "on" to "off" are identified. By EXCLUSIVE-ORing this result with the changed status indicators, those statuses which went from "off" to "on" are identified.

	IN	0	INPUT NEW STATUS
S2	LR	4,A	SAVE IN SCRATCHPAD BYTE 4
S3	XS	3	EXCLUSIVE-OR ACCUMU- LATOR WITH OLD STATUS
S4	LR	5,A	SAVE "CHANGED
			STATUSES" INDICATORS IN 5
S5	NS	3	AND WITH OLD STATUSES
S6	LR	6,A	SAVE "STATUSES TURNED OFF" IN 6
\$7	XS	5	EXCLUSIVE-OR WITH "CHANGED STATUSES"
S8	LR	7,A	SAVE "STATUSES TURNED ON" IN 7
S9	LR	A,4	NEW STATUS FROM SAVE
S10	LR	3,A	OLD STATUS FROM NEXT USAGE.

Suppose the old status was:

		7	6	5	4	3	2	1	0	Bit No.
Old Status	Ξ	1	0	1	1	1	0	0	0	

Suppose the new status is:

		7	6	5	4	3	2	1	0	Bit No.
Mayer Status	=	1	1	Ω	1	Λ	1	1	Λ	

Bits 6, 2 and 1 have turned on. Bits 5 and 3 have turned off. Bits 6, 5, 3, 2 and 1 have changed.

Here is the result of instruction S3:

	7	6	5	4	3	2	1	0	Bit No.
Old Status	1	0	1	1	1	0	0	0	
New Status	1	1	0	1	0	1	1	0	
Changed Statuses	\overline{o}	1	1	O	1	1	1	n	

Here is the result of instruction \$5:

	7	6	5	4	3	2	1	0	Bit No.
Changed Status	0	1	1	0	1	1	1	0	
Old Status	1	0	1	1	1	0	0	0	
Turned Off	ō	ō	1	0	1	0	0	ᢐ	

Here is the result of instruction S7:

	7	6	5	4	3	2	1	0	Bit No.
Turned Off	0	0	1	0	1	0	0	0	
Changed Statuses	0	1	1	0	1	1	1	0	
Turned On	ō	1	0	0	0	1	1	0	

7.7 POWERING UP AND STARTING PROGRAM EXECUTION

When power is turned on, all PCO registers in an F8 microprocessor system are set to 0. Therefore the first instruction executed is located at memory byte 0.

Every F8 microprocessor system must, therefore, have a memory device (either a 3851 PSU, 3852 DMI or 3853 SMI). The first program to be executed must be originated at H'00', as illustrated on the following page.

ORG H'00'

START

FIRST INSTRUCTION EXECUTED

The power on detect circuit for an F8 system is located in the CPU. This circuit insures that all critical control circuits and registers are in a valid operating condition when power is first applied. It performs the following functions:

- Pushes previous contents of the program counter to the stack register
- Resets the program counter to address "0000"

- Resets the Interrupt Control Bit (ICB)
- Sets control block on the 3852 MI circuit

When power is connected to the circuit or the reset line goes low, the CPU clears the program counter (PCO), pushing its previous contents into the stack register (PC1). Therefore, the instruction in location zero is executed first. The interrupt control bit is also cleared at this time. The rest of the F8 system is initialized under program control. The local interrupt block of the individual memory devices must be loaded before allowing any interrupts to occur. Output latches must be reset to zero before they may be used to input data.

INPUT/OUTPUT PROGRAMMING

Input/output programming covers program steps that cause data to be transferred between the F8 microprocessor system and the world beyond the microprocessor system.

There are three separate and distinct types of input/output (I/O) programming: Programmed I/O, Interrupt I/O and Direct Memory Access (DMA).

Programmed I/O is characterized by the 3850 CPU executing an instruction to initiate and control the I/O transfer of a single byte of data, via an I/O port. The key feature of programmed I/O is that it is initiated by the CPU, on a byte-by-byte basis.

Interrupt I/O is characterized by an external device issuing an interrupt to the 3850 CPU; (this concept is discussed in Section 2.2.2). The interrupt does not itself cause any input or output data transfer to occur; rather it initiates execution of a program which performs any required programmed I/O.

DMA has been described conceptually in Sections 2.2.4, 2.6.3 and 2.8. DMA transfers data between a memory device within the microprocessor system and any device external to the microprocessor system, in parallel with other microprocessor operations. DMA is initiated using programmed I/O and, optionally, may terminate with an interrupt.

The use of software clocks is also covered in this chapter. Even though software clocks have nothing to do with transfer of data between the microprocessor system and the outside world, they do allow events within the microprocessor system to be synchronized with real time.

8.1 PROGRAMMED I/O

A programmed input or output operation moves a byte of data from the 3850 CPU accumulator either to an I/O port (OUT), or from an I/O port to the accumulator (IN).

Four instructions enable programmed I/O: INS and IN enable input, while OUTS and OUT enable output. (See Sections 6.16, 6.18, 6.33 and 6.34.)

Note that a number of I/O ports are accessed by I/O instructions, but transfer no data between the microprocessor system and the outside world. These I/O ports hold control information used by interrupt I/O, DMA and real time clocks. Section 6.16 summarizes the I/O port addresses used by the F8, and indicates how the individual port addresses may be used.

Programmed I/O is a very open ended subject, since it is dependent on how external circuitry accesses the I/O ports. The following subsections describe some general approaches to I/O programming as seen by the CPU. Actual applications will usually require modified versions of the given programming techniques.

8.1.1 Polling on Status

A key feature of programmed I/O is that the microprocessor system and external devices operate at different speeds; the external device must transfer data at a rate which is slower than the I/O program's execution speed.

The simplest way of handling programmed I/O, when external devices run slower than the microprocessor, is to have the external device input a "status byte" to the I/O port when it is

ready to transmit or receive data. The 3850 CPU continuously inputs a byte of data from the port until the "ready status" appears. For example, suppose a 1 in the high order bit (bit 7) of the I/O port signifies a ready status; the following routine will input a byte of data via port 0:

*ROUTINE TO INPUT A BYTE OF DATA VIA PORT 0, POLLING *ON STATUS TO SYNCHRONIZE WITH THE EXTERNAL *DEVICE.

INO	LIS	0	FIRST CLEAR THE PORT
	OUTS	0	
LOOP	INS	0	INPUT STATUS
	BP	LOOP	RETURN IF BIT 7 is 0
LO	INS	0	BIT 7 IS 1, INPUT A DATA
			BYTE
	ST		STORE IN MEMORY BYTE
			ADDRESSED BY DC0
L1	PI	TEST	BRANCH TO END OF INPUT
			TEST
L2	BR	LOOP	RETURN FROM TEST FOR
			MORE INPUT
L3			RETURN FROM TEST FOR
			END

Three features of the above routine need to be explained. The first two instructions clear the output port. This is necessary because data being input at an I/O port is ORed with whatever is already in the port. If, by chance, the high order bit of the last data byte input was 1, this would be interpreted as a ready status.

The data which is input to the accumulator by instruction LOOP will be interpreted as a byte of status. While in this simple application only the high order bit of the status byte is being interrogated, in any real application all eight bits of the status byte could be assigned meaning. In this case, when bit 7 of the status byte is tested to be 1, a byte of data is input by instruction LO to the accumulator. This routine assumes that the time delay between execution of instructions LOOP and LO is sufficient for the external device to transmit a data byte.

This routine assumes that an indeterminate number of characters are expected on input. A subroutine named TEST is called to determine if more bytes of data are expected. The operations performed by subroutine TEST are immaterial to the I/O routine. Subroutine TEST must have two returns; to instruction L2 if another byte of data is to be input, or to instruction L3 if data input is complete.

Each byte of data that is input to the accumulator in subroutine INO must be stored in some read/write memory location. INO assumes that the DCO registers address a RAM byte into which the data must be stored. This assumes that before INO is called as a subroutine, the beginning address of a RAM data buffer is loaded into the DCO registers. Data bytes, as they are input, will be stored in ascending bytes of the addressed RAM data buffer. Scratchpad bytes can also be used to hold data being input.

Subroutine OUTO, described below, is a variation of subroutine INO. OUTO outputs data from a RAM buffer. The only difference between subroutines INO and OUTO is that in OUTO, once a ready status has been detected, the data byte which

is to be output must first be transferred from memory to the accumulator before being output to port 0.

Both subroutines INO and OUTO can address any port that the INS and OUTS instructions can address. In order to address other ports it is only necessary to replace the INS and OUTS instructions with IN and OUT instructions.

*ROUTINE TO OUTPUT A BYTE OF DATA VIA PORT 0, POL-*LING ON STATUS TO SYNCHRONIZE WITH THE EXTERNAL *DEVICE

*DEVICE OUTO	LI OUTS	0	FIRST CLEAR THE PORT
LOOP1	INS BP LM	0 LOOP1	INPUT STATUS RETURN IF BIT 7 is 0 BIT 7 IS 1. READ FROM MEMORY THE BYTE TO BE
M0 M1	OUTS Pl	1 TEST	OUTPUT OUTPUT THE DATA BYTE BRANCH TO END OF INPUT TEST
M2	BR	LOOP1	RETURN FROM TEST FOR MORE INPUT
МЗ			RETURN FROM TEST FOR END

8.1.2 Data, Status and Controls

Observe that in Section 8.1.1, a byte input by an external device may be interpreted as status information or as data. Similarly, the 3850 CPU may output a byte which is to be interpreted as control signals or as data.

To illustrate, consider an F8 microprocessor system being used to read data input from a keyboard, block the data into 256 byte records, then write the records out to a cassette. Events would proceed as follows:

- Using a programmed input sequence such as INO, interpret a byte input from the keyboard as status. When a ready status is sensed, interpret the next byte arriving from the keyboard as data.
- A subroutine such as TEST is called to create a 256 byte record in RAM, in the format needed for output to the cassette.
- 3) When the microprocessor is ready to write a record to the cassette, it must first turn the cassette drive motor on, since the cassette drive will be stationary during the intervals when records are not being written out. The microprocessor will turn the cassette drive on by outputting an appropriate control byte whose bit pattern is determined by the specifications of the cassette drive controller.
- 4) The cassette drive will respond to the control byte, commanding the drive be turned on by transmitting back a status byte indicating that the command was successfully executed and the drive is now ready to receive data.
- 5) Upon receiving back the ready status from the cassette drive the microprocessor will output 256 bytes of

data. Depending on the design of the cassette drive, the cassette drive controller may transmit a status byte back to the microprocessor after each individual data byte has been received. This status byte reports that the previous data byte has been recorded accurately, and the controller is ready to receive and record the next byte of data.

- 6) After the microprocessor has completed transmittal of an entire record of data, it must send a control signal to the cassette drive commanding the cassette drive to stop forward movement.
- 7) When all records have been written to the cassette drive, the microprocessor will issue a third control command which causes the cassette drive to mechanically rewind.

Observe that this simple application receives either data or status from the keyboard, then outputs either controls or data to the cassette drive; additional status information may come back from the cassette drive.

Any external device may transmit two types of information to the microprocessor system: data or status.

Any external device may receive two types of information from the microprocessor system: data or controls.

Thus there are four types of information that may be transferred between the microprocessor system and an external device. They are:

- a) data in
- b) status in
- c) data out
- d) control out

An external device may communicate with the microprocessor system using one, two, three or all four of the above types of information. For example, the keyboard uses "data in" and "status in" but does not use "data out" or "controls out". The cassette drive in the illustrated application uses "status in", "data out" and "controls out" but does not use "data in". Of course the cassette drive would be capable (at another time) of using "data in", when the data which was recorded on the cassette is subsequently read back into the microprocessor system.

It is feasible to use one port for all four of the information transfer types listed above when communicating with any one external device. For example, one I/O port could be used to receive status and data from the keyboard, and could also be used to receive status or data from the cassette drive and to output controls or data to the cassette drive. However, if more than one type of information is to go through one I/O port, external logic must have the means of multiplexing information in or out. A scheme that uses more I/O ports, but less external logic, allocates one port for data in or out and another port for status in or controls out. For example, I/O port 0 may be assigned to keyboard status in, I/O port 1 may be assigned to keyboard data in, I/O port 4 may be assigned to cassette status in and controls out and I/O port 5 may be assigned to cassette data in and out.

8.1.3 Parallel Data and Control Ports

Many applications will require data to be handled on paths that are more than eight bits wide. Sixteen-bit data, for example, is a common word size. Less frequently, it will be necessary to handle more than eight control lines at a time.

Data paths that are more than eight bits wide can be handled in 8-bit units, sequentially through a single port. Alternatively, two or more ports may be assigned to one external data bus so that, whenever the microprocessor inputs data from an external device or outputs to the external device, it accesses each I/O port allocated to the data bus. This is illustrated below in subroutine IN16, which inputs data in 16-bit units via ports 4 (bits 0-7) and port 5 (bits 8-15).

*ROUTINE TO INPUT 16 BITS OF DATA VIA PORTS 4 AND 5,
*POLLING ON STATUS VIA PORT 0 TO SYNCHRONIZE WITH
*THE EXTERNAL DEVICE

	ILLE EV	IERNAL	DEVICE	
IN	116	LIS	0	FIRST CLEAR THE STATUS
		OUTO	_	PORT TO REMOVE PREVIOUS
		OUTS	0	READY STATUS
L(OOP	INS	0	INPUT STATUS
		BP	LOOP	RETURN IF BIT 7 IS 0
LC)	INS	4	BIT 7 IS 1. INPUT FIRST DATA
				BYTE
		ST		STORE IN MEMORY BYTE
				ADDRESSED BY DCO
		INS	5	INPUT SECOND DATA BYTE
		ST		STORE IN NEXT MEMORY
				BYTE (ADDRESSED BY DCO)
L1		Pl	TEST	BRANCH TO END OF INPUT
				TEST
L2		BR	LOOP	RETURN FROM TEST FOR
				MORE INPUT
L3				RETURN FROM TEST FOR NO
				MORE INPUT
				·- · · · ·

8.2 INTERRUPT I/O

Two circumstances under which interrupts are commonly used to control I/O operations are:

The programmed I/O, described in Section 8.1, has the severe disadvantage that the microprocessor system spends a great deal of its time reading a status byte and waiting for the status byte to signal "ready". If the external device operates at speeds close to that of the microprocessor, the wasted time may be unavoidable. For example, if the microprocessor can only execute ten instructions between each byte transmitted or received by the external device, it is probable that these ten instructions can be effectively used testing or processing each data byte as it is transferred. On the other hand, if the 3850 CPU can execute approximately one hundred instructions between bytes of data being transmitted to or from the external device, there is sufficient time between data transfers for the microprocessor to be doing other useful work which may or may not be related to the data transfer taking place. If instead of sending a ready status, the external device transmits an interrupt request signal every time it is ready to transmit or receive a data byte, this signal can be used by the 3850 CPU to suspend executing whatever program was being executed, process a single byte of data, then return to the suspended program.

The transfer of a sequence of data bytes at a known data rate constitutes a sequence of predictable events. In many applications an external device's need for access to the micro-

processor system cannot be predicted. For example, an external device may only communicate to the microprocessor under distress circumstances, at which time the microprocessor must execute a program to compute and output needed correction data. When the external device's need for access to the microprocessor system cannot be predicted, an interrupt is the only reasonable way in which the external device can gain control of the microprocessor system.

8.2.1 The Interrupt Sequence

Each 3851 PSU in an F8 microprocessor system has an external interrupt line, as does the 3853 SMI device, if present.

The sequence of events surrounding an interrupt is as follows:

- For interrupts to be processed, interrupts must be enabled within the 3850 CPU and at the device receiving the interrupt request signal. At the 3850 CPU, all interrupts are enabled or disabled. At each 3851 or 3853 device, the individual interrupt line at that device is enabled or disabled. This is described in Section 8.2.2.
- 2) More than one device may simultaneously request to interrupt the 3850 CPU; that is, interrupt request signals may be true, simultaneously, at more than one device. When this happens, priorities are arbitrated as described in Section 8.2.3.
- 3) When a valid interrupt request signal is detected by the 3850 CPU, it ceases current program execution at the conclusion of the instruction currently being executed. (Certain instructions are exempt, as described below.)
- 4) The 3850 CPU sends out an interrupt acknowledge signal. The way in which this signal is trapped implements interrupt priority when more than one interrupt request line is true, as described in Step 2.
- 5) When the 3850 CPU sends out an interrupt acknowledge signal, it clears the interrupt enable status within the 3850 CPU, thus disabling all subsequent interrupts. As described in Section 8.2.4, interrupts must be re-enabled, under program control, when such a step is appropriate to program logic.
- 6) Each device that has an interrupt request line also has a 16-bit address register which holds the address of the first instruction to be executed following the interrupt. The 3851 address register is a non-programmable mask option. The 3853 address register is made up of two I/O ports which are loaded with an address by appropriate I/O instructions. As described in Section 8.2.4, bit 7 of the interrupt address will always be 1 for an external interrupt, and will always be 0 for a local timer interrupt.

The device that traps the interrupt acknowledge signal output in step 5 responds by transmitting the contents of its interrupt address register as the next contents of PCO registers.

7) PSU and MI logic, under CPU control, moves the contents of PC0 to PC1, then loads the address from step 6 into PC0; thus a program dedicated to the acknowledged interrupt request line is executed.

An interrupt will not be acknowledged at the conclusion of any of the following instructions:

PK
PI
POP
JMP
OUTS (if not port 0 or 1)
OUT (if not port 0 or 1)
EI
LR W,J

An instruction other than one of the above must be executed before an interrupt will be acknowledged.

When power is first turned on, interrupts are disabled.

8.2.2 Enabling and Disabling Interrupts

As described in Section 2.4.3, bit 4 of the 3850 CPU W register is an Interrupt Control bit. When this bit is set to 1, interrupt requests to the CPU are enabled; when this bit is reset to 0, no interrupt request to the CPU will be acknowledged. ICB is set to 1 by the El instruction or by a LR W,J instruction; it is reset to 0 by the DI instruction or by a LR W,J instruction.

Individual interrupt request lines are controlled at each device via an I/O port which is set aside as an interrupt control buffer.

For the 3851 PSU's, the interrupt control I/O port address is B'xxxxxx10'; xxxxx is the I/O port select code, which may be any number from 1 to H'3F'. The 3853 interrupt control I/O port address must be H'0E'. This address is also available on a 3851 PSU; when xxxxxx is H'03', the 3851 interrupt control I/O port address becomes H'0E'.:

B'xxxxxx10' = B'00001110' = H'0E'

When a 3853 SMI device is present, a 3851 PSU with a chip select of H'03' cannot also be present.

The following two instructions load the interrupt control I/O port:

LI VAL

IPRT must be equated to the interrupt control I/O port address.

VAL must be equated as shown in Table 8-1.

Value VAL is equated to	Effect		
H′00′	Interrupts disabled at this device.		
H'01'	External interrupt enabled, timer interrupt disabled.		
H'02'	Interrupts disabled at this device (same as H'00').		
н′03′	External interrupts disabled, timer interrupt enabled.		

Table 8-1. Contents of Interrupt Control I/O Ports

Timer interrupts are described in Section 8.4.

8.2.3 Interrupt Priorities

When an F8 microprocessor system has more than one interrupt line, priorities are determined on the basis of "daisy chaining", as illustrated in Figure 8-1.

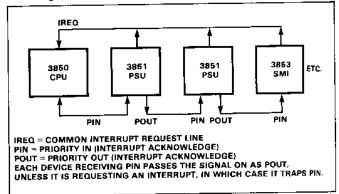


Fig. 8-1. Daisy Chaining and Interrupt Priority Determination

The daisy chain sequence is a hardware feature of an F8 microprocessor system; when the system is configured, the interrupt acknowledge signal from the CPU is chained from one device to the next. This determines interrupt priorities.

The only thing a programmer can do to modify interrupt priorities is to disable external interrupts at selected devices by appropriately loading the interrupt control I/O port at that device with some value other than H'O1'. (See Section 8.2.2 and Table 8-1.)

It should be clearly understood that interrupt priorities, as described in this section, apply only to interrupt request signals competing for the 3850 CPU's next interrupt service.

There is nothing to prevent an interrupt from interrupting a previous interrupt; however, this type of nested priority is a function of how programs have been written. Once an interrupt has been acknowledged and is being serviced, and the ICB bit in the CPU is set to 1, the current interrupt service routine can itself be interrupted.

In order to prevent an interrupt service routine from being itself interrupted, the ICB bit in the CPU W register must be left at zero until the interrupt service routine has completed execution.

Figure 8-2 illustrates the concept of nested interrupts.

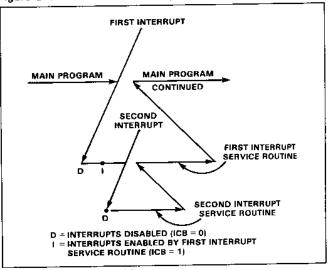


Fig. 8-2. Two Levels of Interrupt

The 3853 SMI device will not pass on an interrupt acknowledge signal; therefore, it must be at the end of the daisy chain, and will have lowest interrupt priority.

8.2.4 Program Response to an Interrupt

There are three program steps which may be needed prior to an interrupt in order to prepare to receive interrupts. They are:

1) If a 3853 SMI device is present, the interrupt address register of the 3853 must be loaded with the address of the first instruction to be executed after an interrupt from the 3853 is acknowledged. As described in Sections 2.7 and 6.16, I/O port addresses H'OC' and H'OD' have been reserved for the upper and lower interrupt address bytes, respectively; therefore the post-interrupt execution address can be loaded as follows:

LI ADHI
OUTS H'OC'
LI ADLO
OUTS H'OD'

ADHI and ADLO are symbols which must be equated to the high and low bytes of the selected execution address. Note that the 3851 PSU has the post-interrupt execution address as a permanent feature of the chip mask; therefore, each 3851 PSU has a fixed post-interrupt execution address associated with it.

- Interrupts must be selectively enabled or disabled at 3851 and 3853 interrupt control ports, as described in Section 8.2.3.
- The 3850 CPU master interrupt enable bit (ICB) must be set to 1, as described in Section 8.2.3.

When an interrupt is acknowledged, events within the 3850 CPU proceed exactly as if a subroutine had just been called: the content of PCO is moved to PC1, and the content of the selected device's post-interrupt address register is moved to PCO. Interrupts should therefore be handled as though a subroutine had just been executed, as described in Section 7.3. For example, the first instructions executed following an interrupt might be:

LR	K,P	SAVE CONTINUATION
Pi	CALL	ADDRESS IN K SAVE CONTINUATION
•	CALL	ADDRESS IN STACK

Returning from an interrupt to the interrupted program is identical to returning from a subroutine to the calling program; however, since a program may be interrupted any time interrupts have been enabled, parameter passing and multiple returns do not apply to post-interrupt programs and should not be used.

Remember that the first interrupt service routine must enable ICB if second level interrupts are to be allowed (as illustrated in Figure 8-2).

8.2.5 Making 3851 PSU Interrupt Address Programmable

The fact that the 3851 PSU's interrupt address is a permanent feature of the device is not a problem in applications where this address may have to be varied. Using a branch table (as described in Section 7.5), a number of possible post-interrupt service routine execution addresses may be maintained. The following routine shows how an external device may use a PSU I/O port to provide an index identifying the service routine which must be executed following the interrupt. I/O port 4 has been arbitrarily selected as the I/O port address. The data byte at I/O port 4 selects an address from a branch table, as follows:

*POST II	NTERRUP	T SERVICE	ROUTINE FOR PSU 1
RC1I	LR	K,P	SAVE RETURN ADDRESS ON THE STACK
	PI	CALL	
	INS	4	INPUT PROGRAM SELECT BYTE
	LR	RX	SAVE INDEX VALUE
	PI	BRANCH	CALL BRANCH TABLE SUB- ROUTINE

8.2.6 Simple I/O Interrupts

In Section 8.1.2, a simple application was described, where data is input at a keyboard and recorded in 256 byte records on a cassette.

A cassette may record data at a rate of approximately 200 bytes/second. With time taken to start and stop the cassette, two or three seconds may elapse each time a record is output to the cassette. Preventing data from being input at the keyboard while it is being output to a cassette is both inconvenient and unnecessary. Simple I/O interrupts may be used to output data to the cassette, byte-by-byte. These few instructions are sufficient to service each interrupt.

*PROGRAM TO WRITE ONE BYTE TO A CASSETTE, FOLLOW-*ING AN INTERRUPT

	,	
LM		LOAD NEXT BYTE ADDRESSED BY DCO OUTPUT TO CASSETTE RETURN FROM INTERRUPT
OUT Ei POP	CASS	
	OUT	OUT CASS

The key concept here is that the F8 is uniquely suited to processing a large number of simple interrupts. If the post-interrupt program will not itself be interrupted, and if it will call no subroutines, then merely ending it with a POP instruction turns it into a complete interrupt service routine. Do not save the return address in the stack; do not call any starting or ending subroutines (e.g., CALL or RTRN).

For example, see Section 2.8.7.

8.2.7 A Sample Program

Figure 8-3 illustrates a configuration for the key to cassette application described in Section 8.1.2, except that 32 byte records are to be written to the cassette.

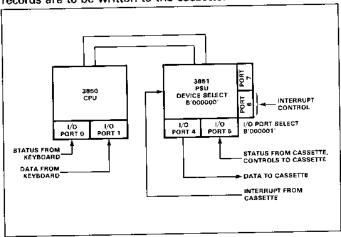


Fig. 8-3. Two Devices Servicing a Keyboard to Cassette Application

- *PROGRAM TO RECEIVE DATA FROM THE KEYBOARD USING *PROGRAMMED I/O
- *SCRATCHPAD BYTES 0'40'TO 0'77' MAKE UP THE 32 BYTE *BUFFER.
- *SCRATCHPAD BYTES 0'20' TO 0'37' ARE USED AS A TEM-*PORARY BUFFER TO HOLD DATA WHILE THE MAIN BUFFER *IS BEING WRITTEN TO CASSETTE

10 000114	O		_
	ORG	H,0000,	
START	LISU	3	INITIALIZE ISAR TO
S1	LISL	7	TEMPORARY BUFFER
S2	LIS	H'01'	ENABLE EXTERNAL INTER-
0-			RUPTS AT PSU
	OUTS	6	
	ΕÍ		ENABLE INTERRUPTS
S3	PI	INKB	INPUT NEXT EIGHT BYTES
00	• •		FROM KEYBOARD
S5	LISU	2	DECREMENT UPPER DIGIT
55	2.00	_	OF ISAR
S6	PI	INKB	INPUT NEXT EIGHT BYTES
50	• •		FROM KEYBOARD
* *	INIDALITEIN	10 10 BVT	S FROM THE KEYROARD, IT IS

*AFTER INPUTTING 16 BYTES FROM THE KEYBOARD, IT IS *ASSUMED THAT ANY RECORD OUTPUT TO THE CASSETTE *IS COMPLETE. MOVE DATA FROM 0'37' - 0'20' TO 0'77' -O'60'

0'60'.			
S8	LISL	7	LOAD FIRST SOURCE BYTE
			ADDRESS
S9	LISU	3	
S10	LR	A,S	LOAD NEXT BYTE
S11	LISU	7	
S12	LR	D.A	STORE NEXT BYTE
S13	BR7	S9	IF NOT END OF BUFFER,
0.0	D117		RETURN FOR NEXT BYTE
S14	LISU	2	IF END OF FIRST BUFFER,
314	LISO	-	MOVE SECOND BUFFER
S15	LR	A.S	REPEAT MOVE FOR SECOND
515	<u>L</u> n	A,5	8 BYTE
	LICH	6	BUFFER
	LISU	-	BUFFLIN
	LR	Ď,A	
	BR7	S14	
S16	LISU	5	INPUT NEXT EIGHT BYTES
0.0			FROM KEYBOARD TO
C17	PI	INKB	SCRATCHPAD BUFFER O'57'
\$17	Γı	HAND	TO O'50'
			10 0 00

31	3	Liou	•	FROM KEYBOARD TO
S2	0	PI	INKB	SCRATCHPAD BUFFER O'47'
				TO 0'40'
*B	UFFER I	IS NOW F	READY TO	BE OUTPUT TO CASSETTE.
S2		Li	H'3F'	LOAD BUFFER INITIAL
				ADDRESS
S2	2	LR	0.A	(O'77') INTO SCRATCHPAD
-	_			BYTE 0
S2	3	LI	ONC	TURN CASSETTE ON
SZ	-	OUTS	5	
52	5	BR	START	RETURN FOR NEXT RECORD
*11	UPLIT SI	JBROUTI	NE INKB S	TORES A BYTE OF DATA INPUT
*6	DOM K	FYROARI	INTO SCI	RATCHPAD BYTE ADDRESSED
	YISAR		,	
	TISAN			

519

LISU

INPUT NEXT EIGHT BYTES

INKB	LR	K,P	SAVE RETURN ADDRESS IN K
LO	CLR	0	CLEAR PORT 0
LOOP	OUTS INS	ō	INPUT STATUS
L1	BP	LOOP	MINIST DATA
L2	INS	1	INPUT DATA
L3	LR	D,A	STORE IN ISAR BUFFER
LU	BR7	LO	RETURN IF NOT EIGHTH BYTE
L4	PK		RETURN
*INTERR	UPT SER	VICE ROUT	INE, EXECUTED TO WRITE ONE

*BYTE TO CASSETTE.

	ORG	H'0280'	
E0	LR	1, A	SAVE ACCUMULATOR IN
			SCRATCHPAD BYTE 1
E1	LR	A,IS	SAVE ISAR IN SCRATCHPAD
	_		BYTE 2
E2	LR	2,A	LOAD SCRATCHPAD BYTE 0
E3	LR	A,0	CONTENTS INTO ISAR
		IS.A	CONTENTS INTO ISAN
E4	LR INS	15,A 5	RECEIVE STATUS FROM
E5	1145	5	CASSETTE, INS SETS STATUS
E7	ΒZ	FO	0,7000112,000000000000000000000000000000
E8	LR	A.S	IF NOT END OF CASSETTE,
E9	OUTS	4	OUTPUT NEXT BYTE
E10	LR	A,IS	MOVE ISAR TO A
E11	Al	H'FF'	DECREMENT ALL 6 BITS OF
			ADDRESS
E12	CI	0'37'	TEST IF RESULT IS 0'37'
E13	BZ	E17	RETURN IF NOT
E14	LI	STOP	IF IT IS, ISSUE A STOP
			COMMAND
E15	OUTS	4	TO TOO FOR NEVT
E16	Ll	0'77'	RESET TO TOP FOR NEXT
			OUTPUT SAVE ISAR ADDRESS FOR
E17	LR	0,A	NEXT BYTE
-40		A.2	BEFORE RETURNING,
E18	LR	A,Z	RESTORE ACCUMULATOR
	LR	IS.A	AND ISAR
	LR	A.1	,,,,,,
	Εl	,.	
	POP		
FO	LI	REW	IF CASSETTE IS FULL, ISSUE
	OUTS	4	REWIND COMMAND
	BR	E18	

The logic of this program is relatively simple. Scratchpad bytes O'77' to O'40' constitute a 32-byte buffer, the contents of which is output as a record to the cassette. It is assumed that this record can be written to the cassette in less time than an operator takes to enter 16 digits at the keyboard. Therefore instructions START through S7, input 16 digits into the 16 scratchpad bytes addressed by O'37' through O'20'.

Data is input from the keyboard using programmed I/O via subroutine INKB. Notice that subroutine INKB saves its return address in the K scratchpad registers and uses the PK instruction to return; therefore a stack register is available for the interrupt. Subroutine INKB is almost identical to the input subroutine described in Section 8.1.1. The principle difference is that separate ports are being used for status and data. Observe that throughout this program data is input into scratchpad bytes, one scratchpad 8-byte buffer at a time.

Once 16 digits have been input from the keyboard, they are moved from scratchpad bytes O'37' - O'20' to O'77' - O'60'. This entire data movement will take 208 microseconds which is not a noticeable delay to an operator entering data at the keyboard.

The next 16 bytes of data entered at the keyboard go directly into scratchpad bytes O'57' through O'50' and O'47' through O'40'.

After 32 bytes have been entered into the scratchpad buffer, a buffer counter is initialized in scratchpad byte 0 (instructions 21 et. seq.); then the cassette is turned on by instructions S23 and S24. ONC is used as a symbol representing the one byte code which will be recognized by the cassette control logic as a turn-on signal. Once the cassette has been turned on, program logic branches back to the start of data entry for the next record.

Notice that nowhere in the main program has the interrupt service routine been mentioned. It is assumed that once the cassette has been turned on, cassette control logic will issue an interrupt request signal each time it is ready to receive another byte of data from the microprocessor. The interrupt service routine therefore may be executed at any time. It is as though there were a floating call to a subroutine that could randomly be executed at any point in the program where interrupts were being allowed.

Observe that the interrupt service routine has to save the contents of the accumulator and the ISAR in scratchpad bytes because the accumulator and ISAR are going to be needed.

The illustrated interrupt service routine is probably somewhat simpler than most real interrupt service routines would be. Control logic associated with the cassette drive is assumed capable of sending status inputs to the microprocessor telling the microprocessor when to rewind the cassette. It is also assumed that housekeeping associated with the start and end of each record is handled by the cassette control logic. In all probability much of this housekeeping could be done by the microprocessor, but to include it in the example would detract from the purpose of the example, which is to show how an interrupt service routine is handled.

The origins of the main program and interrupt service routine have been randomly selected. Note that since the origin of the interrupt service routine has been selected at H'0280',

this is the address which must be in the 3851 interrupt address register.

The symbols STOP and REW in the interrupt service routine must be equated to the actual bit pattern that the cassette controller logic will interpret as stop and rewind commands, respectively.

8.3 LOCAL TIMERS (PROGRAMMABLE TIMERS)

Programmable timers are a more useful microprocessor programming tool than is initially apparent to a programmer.

Programmable timers are shift registers which, after being loaded with some initial value, count down to 0, then send an interrupt request signal to the CPU. (See Section 2.5.4.) The 3851 PSU and the 3853 SMI device both have programmable timers.

Here are some applications for which timers are useful:

- 1) In control applications, such as an operations monitor alarm, to insure that some maximum time interval is not exceeded between consecutive readings from sensitive data inputs. For example, suppose a temperature must be measured in a chemical reactor at least once every second to prevent runaway conditions. 253 maximum time intervals on a local timer approximate 1 second. Whenever a temperature is input, the local timer is reset to start counting down one second. If one second is counted down, the program can be written to output a signal that triggers an audible alarm.
- To activate refresh logic for external devices. For example, a video display may need to be refreshed at fixed time intervals; the refresh sequence may be initiated by a local timer.
- To maintain the real time of day in any system that has to generate clock times. Such devices include badge readers and numerous small office business systems.

8.3.1 Local Timer I/O Ports

Local timer logic uses the local interrupt control I/O ports to enable local timer interrupts, as described in Section 8.2.2 and Table 8-1.

The interrupt control I/O port must have the value H'O3' loaded into it under program control in order to enable local timer interrupts at that one device. Therefore either external interrupts or local timer interrupts, but not both, may be enabled at one device.

If interrupts have been disabled at the 3850 CPU, local timer interrupt requests will be ignored until a subsequent interrupt enable. At this time any interrupt request will still be active unless cleared prior to the interrupt enable.

The timer I/O ports have I/O port addresses one higher than the local interrupt control I/O port. Therefore 3851 PSU port addresses are:

B'xxxxxx10' for the local interrupt control I/O port B'xxxxxx11' for the local timer I/O port

For the 3853 SMI, port addresses are:

H'OE' for the local interrupt control I/O port H'OF' for the local timer I/O port

8.3.2 Programming Local Timers

Programming a local timer requires the value H'03' to be loaded into the selected device's local interrupt control I/O port. A number between 0 and 254, identified as a timer constant, is loaded into the associated local timer I/O port. A value of 255 loaded into the local timer I/O port stops the clock

The value loaded into a local timer, as a timer constant, is converted (by the assembler) to a binary value, as given in Appendix C; that is why numbers should be entered as timer constants.

A local timer interrupt will be generated after the time interval given by the product:

(system clock pulse interval) * (local timer constant) * 31

For example, a value of T'200' loaded into a local timer I/O port will generate an interrupt after 3.1 ms if the system clock pulse interval is 500 ns.

Instructions needed to enable a local timer are as follows:

_		
_		
_		
LI	T'200'	LOAD TIMER CONSTANT
OUT\$	7	OUTPUT TO TIMER I/O PORT 7
LIS	3	LOAD TIMER INITIATION CONTROL
OUTS	6	OUTPUT TO CONTROL I/O PORT 6
_		
El		ENABLE INTERRUPTS AT THE 3850 CPU

In the above example, the timer constant T'200' has been arbitrarily selected. Any value from T'0' to T'256' could be used. T'256', remember, will stop the clock.

The selection of I/O ports 7 and 6 is also arbitrary; any pair of I/O ports with addresses given in Section 8.3.1 could be used. Note, however, that the control I/O port number is always one less than the timer port number it controls.

The value H'03' must be loaded into a local timer control I/O port if the associated timer port is to operate. When this value is loaded into the control I/O port any pending timer interrupt is cleared. Any subsequent zero value of the timer will set the timer interrupt.

If the value H'03' is in the control I/O port before the timer constant is output to the timer I/O port, then the timer which is constantly running may interrupt before being set with a timer constant. Once the timer I/O port holds a zero value, an interrupt request signal will be generated once every 3.953 ms (for a 500 ns clock pulse). Providing the ICB bit is 1 within the 3850 CPU, every timer interrupt request will be acknowledged and serviced if the timer interrupt is enabled.

The program that is executed after a timer interrupt is acknowledged is a service routine which, like the service routine illustrated in Section 8.2.7, is never called or referenced by any other program. The service routine must start executing at the memory address provided by the 3851 or 3853 device's interrupt address I/O ports; however, recall that the 7 bit of the address is automatically set to 0 for a timer interrupt, or to 1 for an external interrupt. If the external interrupt service routine is origined at H'0680', as illustrated in Section 8.2.7, then for the same device, the local timer interrupt service routine will be origined at H'0600'.

8.3.3 A Programming Example - The Time of Day

The program below creates the time of day by storing hours in scratchpad byte 8, minutes in scratchpad byte 7 and seconds in scratchpad byte 6. Scratchpad byte 5 is used as a counter.

This program uses the maximum timer interval (3.953 ms between interrupts). The local timer must be initialized with the main program as follows:

LIS	0	ZERO HOURS, MINUTES AND
LR	8,A	SECONDS PORTS, ASSUM-
LR	7,A	ING THE DEVICE WILL BE
LR	6,A	SWITCHED ON EXACTLY AT
	·	MIDNIGHT
LI	253	INITIALIZE THE LOCAL
LR	5,A	COUNTER TO 253
LI	T'0'	CLEAR LOCAL TIMER PORT
OUTS	7	•
LIS	H'03'	ENABLE THE LOCAL TIMER
OUTS	6	PORT INTERRUPTS
El		ENABLE INTERRUPTS AT
		THE CPU

The local timer interrupt service routine is assumed to be origined at H'0200'. It executes as follows:

ORG	H'0200'	
DS	5	DECREMENT THE LOCAL
		COUNTER
BNZ	OUT	CONTINUE IF IT IS NOT ZERO
		(ONE SEC).
Li	253	IF IT IS ZERO, RESET TO 253
LR	5,A	
LR	A,6	INCREMENT THE SECONDS
	-	COUNTER
INC		
CI	60	TEST IF SECONDS EQUAL 60

		BZ	T10	IF THEY DO, ADJUST
				MINUTES
		LR	6,A	IF THEY DO NOT, END
	OUT	El		
1		POP		
7	*MINUTE	S ADJUS	T BEGINS	HERE
•	T10	LIS	0	ZERO SECONDS
		LR	6,A	
		LR	A,7	LOAD MINUTES
		INC		INCREMENT MINUTES
		CI	60	TEST FOR 60 MINUTES
		BZ.	T20	
		LR		AT 60 MINUTES, ADJUST
		LN	7,A	HOURS OTHERWISE RETURN
				MINUTES
		Ēl		
		POP		
		adjust i	BEGINS HE	RE
٦	Γ20	LIS	0	ZERO MINUTES
		LR	7,A	
		LI	153	CORRECT 0.392 SECOND
				ERROR EVERY HOUR
		LR	5.A	CHION EVENT HOOK
		LR	A.8	LOAD HOURS
		INC	~,0	
				INCREMENT HOURS
		CI	24	TEST FOR 24 HOURS
		BNZ	T30	AT 24 HOURS, RESET TO 0
		LIS	0	OTHERWISE RETURN HOURS
Ţ	30	LR	8,A	
		El		
		POP		

8.4 DIRECT MEMORY ACCESS

Direct memory access (DMA) allows data to be transferred between any F8 microprocessor system memory and an external device, bypassing the 3850 CPU. Data is transferred in parallel with any CPU operations. DMA has been described, as a concept, in Sections 2.6.3 and 2.8.

One 3852 DMI device must be present in a microprocessor system that supports DMA. Up to four 3854 DMA devices may be present in the system; each 3854 DMA device provides one DMA channel.

8.4.1 When to Use DMA

DMA is used to transfer data into, or out of, a microprocessor system that has heavy I/O requirements. For example, using programmed I/O, the theoretically maximum data transfer rate is implemented by the following instruction sequence for data input:

LOOP	INS	0	INPUT A DATA BYTE VIA
			PORT 0
	ST		STORE IN RAM MEMORY
	DS	1	TEST FOR END OF TRANS-
			MISSION
	BNZ	LOOP	RETURN FOR NEXT CHAR-
			ACTER

Scratchpad register 1 is assumed to hold the initial character count.

These four instructions execute in 9.5 instruction cycles, equal to 19 μ s, using a 500 ns clock pulse. Assuming that external logic is synchronized to input one byte of data every 19 μ s, the maximum data transfer rate is approximately 50,000 bytes/second.

The maximum data transfer rate supported by programmed I/O is not of itself a limiting factor. A 256 byte buffer, for example, can be transferred in 4.86 ms. The problem is that this maximum data transfer rate requires external logic that processes data at a rate of one byte every 19 μs . Most applications will not meet this requirement, usually because data transfer rates are set by logic considerations beyond the microprocessor system; that is, external logic determines data transfer rates, not the microprocessor system.

Suppose external logic is inputting data to the microprocessor system at some rate, which we will label R bytes/second. The time that elapses between each byte transferred will be $(1,000,000/R)~\mu s$. The local timer can be used to generate an interrupt shortly before each byte of data is due, in which case the local timer interrupt service routine will input the data byte. Assuming that data will always be in the I/O port before the local timer interrupt service routine is executed, the following service routine will input data bytes from an I/O port:

ISRI	LR	0, A	SAVE ACCUMULATOR CONTENTS IN O
	XDC		SWITCH DC0 AND DC1
	Li	TCNT	RESTART TIMER
	OUTS	7	
	INS	0	INPUT DATA BYTE
	ST		SAVE IN MEMORY
	XDC		SWITCH DC0 AND DC1
	LR	A,0	RESTORE ACCUMULATOR
			FROM 0
	EI		ENABLE INTERRUPTS
	POP		RETURN

TCNT is a symbol defined by the equate directive:

TNCT EQU T'VAL'

where VAL is a number between 0 and 255. Each count represents 31 clock periods and the total time is equal to (1,000,000/R) but less than 3.953 ms.

It will take approximately 38 μs for interrupt service routine ISRI to execute; this means that approximately 9.7 ms will be required to input 256 bytes of data. This 9.7 ms will be spread over whatever time interval the external device requires to transfer 256 bytes of data. But there are some problems associated with the method of inputting data:

- 1) Recall that there are certain privileged instructions which inhibit acknowledgement of an interrupt. It is quite feasible for a 2 to 4 µs delay to randomly get inserted between each execution of ISRI if, by chance, a privileged instruction is being executed at the instant the local timer times out. Over 256 bytes of data transfer, this means that it is feasible for a 500 µs slew to develop, which will result in the loss of a byte of data, if the data transfer rate exceeds 2,000 bytes/s.
- 2) If the microprocessor is handling interrupts other than the local timer, clearly other interrupts must be serviced by routines which are themselves interruptable, since one interrupt service routine blocking out ISRI for any significant period of time would almost certainly create irrecoverable timing errors.

3) Observe that ISRI uses the DC1 register and uses one scratchpad register to store accumulator contents. This means that the DC1 register and the scratchpad register cannot be used by any other program that is being executed during the same time period.

If subroutine ISRI is expanded to include a status test plus logic to compute the timer constant that will compensate for timing slews, the new expanded version of ISRI might easily take 200 μs to execute. Under these circumstances the microprocessor system would spend a significant amount of its time merely moving data between memory and an I/O port.

In all but the simplest I/O transfer applications, therefore, DMA becomes the preferable way of moving data between memory and external devices.

8.4.2 Programming DMA

The actual programming steps required in order to initiate a DMA operation are simple, as follows:

LI OUT	ADLO BUFA	LOAD BUFFER STARTING ADDRESS INTO ADDRESS 1/O PORTS
LI OUT LI	ADHI BUFB CTLO	LOAD LOW ORDER BYTE OF BYTE COUNT
OUT LI	BUFC CTRL	LOAD HIGH ORDER 4 BITS OF BYTE COUNT
OUT	BUFD	PLUS CONTROL BITS

Symbols must be equated as follows:

1) The I/O port addresses, BUFA, BUFB, BUFC and BUFD

are given in Table 2-2 for the four 3854 DMA devices that may be present in an F8 microprocessor system. Whether a DMA device uses the first, second, third or fourth set of addresses is a function of device hardware configuration and of no concern to the programmer, so long as the correct port addresses are used.

- ADLO and ADHI represent the low order and high order bytes of the beginning address of the memory buffer into which data will be written, or from which data will be read.
- 3) Data buffers may be up to 4,096 bytes long. CTLO represents the low order eight bits of the buffer length, as illustrated in Figure 8-4. CTRL provides the controls which select DMA options and also the high order four bits of the buffer length, as illustrated in Figure 8-4.

The following instructions will initiate 256 bytes of data being written into a memory buffer, where the data rate is controlled by the external device. The memory buffer starting address is H'A280'. The first DMA channel is used.

_		
Li	н'80'	OUTPUT LOW ORDER BYTE OF ADDRESS
OUT	H'F0'	OUTPUT HIGH ORDER BYTE
LI	H'A2'	OF ADDRESS
OUT	H'F1'	OUTPUT LOW ORDER BYTE
LI	H'00'	OF COUNT
OUT	H'F2'	OUTPUT HIGH ORDER 4
LI	H'C1'	DIGITS OF COUNT (1)
OUT	H'F3'	AND CONTROL DIGIT (C).

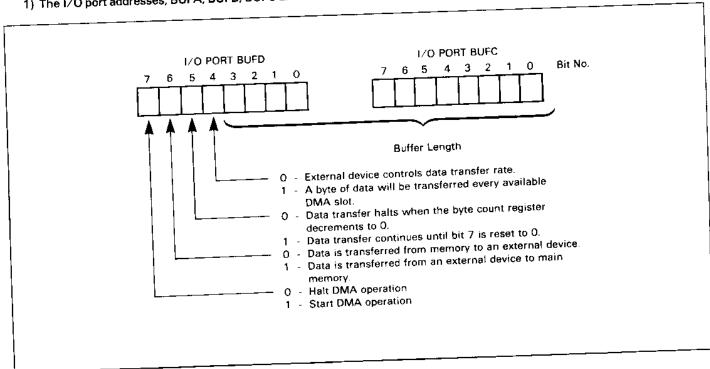


Fig. 8-4. How BUFC and BUFD are used to Control DMA Operations

8.4.3 Catching DMA on the Fly

There are many applications in which data will be transferred via DMA at unpredictable rates. For example, in communications applications, data may come over a telephone line at a fixed baud rate, but the length of messages and the period when no data is being transferred may be completely random. Under such circumstances it is very useful if a program can start and stop DMA operations or interrogate the buffer counter to find out how much data has been transferred via DMA since the last interrogation. The following program sequence catches DMA on the fly, in a way that would be well suited to random data transfer rates in communications applications:

*SUBROUTINE TO INITIALIZE DMA WITH H'FF' IN THE BYTE *COUNTER. THE DATA BUFFER STARTS AT H'2000'

DMA	Li	H'00'	OUTPUT BUFFER STARTING ADDRESS
	OUT	H'FO'	
	LI '	H'20'	
	OUT	H/F1′	
	LI	H'FF'	OUTPUT BYTE COUNTER
	QUT	H'F2'	
	LI	H'C0'	
S2	OUT	H'F3'	
	POP		

*MAIN PROGRAM TO HANDLE COMMUNICATIONS DATA
*TRANSFERRED VIA DMA

	PI	DMA	INITIALIZE DMA
	_		
	-		
	_		
M1	LIS	0	STOP DMA DATA TRANSFER
M2	OUT	H'F3'	
M3	IN	H'F2'	LOAD BYTE COUNT INTO
	COM		SCRATCHPAD BYTE 0
M4	LR	0,A	

(instructions to process data follow here)

Instruction steps to initiate DMA are packaged as a subroutine labeled DMA. The buffer length output is H'FF'. As this buffer length is counted down, the number of bytes transferred via DMA can, at any time, be determined by reading the contents of I/O port F2 into the accumulator and complementing. The control digit C starts data flow via DMA from the external device (assumed to be a communications interface) to the memory buffer, beginning at H'2000'.

The main program starts by initializing DMA via a call to subroutine DMA. At some later point in the program, instructions M1 and M2 are executed in order to load the code digit 0 into I/O port F3 and thus stop DMA transfers. Instructions M3 through M4 determine the number of bytes that have been transferred via DMA, since DMA was initiated, and loads this byte count into scratchpad register 0. Instructions will now follow to move the number of bytes received to some other memory location where the data can be processed. Subroutine DMA will then be recalled to re-initialize DMA data transfers. After data has been processed execution will branch back to instruction M1 and so the program will continue processing whatever data has been transferred in each time interval.

PROGRAM OPTIMIZATION

Optimizing a program is not a routine mechanical task; rather, it is a function of application requirements and hardware configuration. Most microprocessor programs are written either to maximize execution speed, or to minimize the amount of memory used.

Consider a simple example. A microprocessor has 1024 bytes of program memory. An application may only use half of the available memory, but may be too slow to meet product specifications. Converting every subroutine to a macro will speed up program execution time, but may double the size of the program. Since program memory comes in finite increments, economizing on program storage requirements is only meaningful when it reduces the number of devices required by a microprocessor system; therefore, increasing program storage requirements from 500 bytes to 1000 bytes carries no penalty.

In practice, programming for minimum use of program storage should be the goal of microprocessor programmers. Microprocessor instruction sets are very versatile. Many variations of a program can be written to implement any problem; but some programs will be more efficient than others. A novice microprocessor programmer may well write programs that occupy 50% more memory than is really necessary. Inefficiencies of this type are not important in minicomputer systems, which usually include bulk storage devices such as disk units. The only penalty paid for having unnecessarily long programs is a few extra milliseconds, making otherwise unnecessary transfers of program segments between disk and memory. Unnecessarily long programs are very uneconomical in microprocessor systems, where the entire program sits in one or more memory devices. If a microprocessor system has two more memory devices than the most compact program would require, these two memory devices can become 20,000 memory devices, if the microprocessor system is to be reproduced 10,000 times.

In many ways, the logic designer will find it easier to become an efficient microprocessor programmer than will a systems analyst, who has gained experience programming minicomputers and larger systems. The systems analyst has continuously striven to write programs which are general purpose. For example, a subroutine that performs multibyte addition must be able to add two number buffers of any length. located anywhere in memory, storing the result in a third number buffer. Such a multibyte addition subroutine, once written, could be frequently reused in almost any application, thus reducing future programming expenses. This is economical thinking in the world of minicomputers, but it is very uneconomical thinking in the world of microprocessors. A microprocessor application may be able to define two number buffers of specific length, in specific areas of memory, as the only number buffers which will ever be involved in mathematical operations. A multibyte addition subroutine, working within these restrictions, may have to be rewritten for every new microprocessor application, but the subroutine that results may use less than half of the memory storage requirements demanded by the equivalent general purpose routine. When microprocessor systems are likely to be reproduced tens of thousands of times, extra front-end programming expense becomes trivial compared to the cost of extra memory devices, multiplied ten thousand fold.

In the following sub-sections, program optimization information is presented in the following sequence:

- The concept of counting memory bytes and execution cycles is described.
- Some basic techniques that will always make F8 programs more efficient are listed.
- Some examples of execution speed versus memory utilization tradeoffs are given.

9.1 COUNTING CYCLES AND BYTES

The F8 instruction set is summarized in Appendix D, where the number of object program bytes is listed for every instruction.

Consider the data movement program described in Figure 5-1. This program is reproduced in Figure 9-1, along with number of execution cycles and memory bytes required by each instruction.

Counting bytes is usually unnecessary, since the assembler listing prints the memory location where each object program byte will be stored. Thus subtracting memory addresses yields the length of any program, program segment or subroutine.

9.2 ELEMENTARY OPTIMIZATION TECHNIQUES

There are a number of instruction choices where one selection is always preferable. These obvious instruction choices are described in the following sub-sections.

9.2.1 Scratchpad and RAM Memory

Always fill up the scratchpad before using RAM memory to store constants or data buffers. It takes one cycle to move a byte of data between the accumulator and a scratchpad byte; it takes 2.5 cycles to move a byte of data between the accumulator and external RAM. Both sets of instructions generate one byte of object code.

9.2.2 Immediate Instructions

Immediate instructions are 2 or 3-byte instructions that specify data in the instruction operand.

Consider the 2-byte immediate instructions; these instructions specify a 1-byte operand, which is combined with the contents of the accumulator in some way. An instruction such as;

IM LF CNT LOAD COUNTER INTO ACCUMULATOR

executes in 2.5 cycles and occupies two bytes of memory. If this instruction occurs identically (with the same operand) many times in a program, consider loading CNT into a scratchpad register, as follows:

ONE	LI	CNT	
rwo	LR	1,A	
	_		
	_		
THRE	LR	A,1	LOAD COUNTER INTO
			ALLUNNII AILIM

Oycles 0 0 0 0 0 0 0 0 0 0 6 2 6 2.5 1 2.5 2 1.5 3.5 0 31.5	Bytes 0 0 0 0 0 0 0 0 0 3 1 3 2 1 1 1 1 2 0 17	BUFA BUFB ONE TWO THREE FOUR FIVE LOOP SIX SEVEN EIGHT NINE	TITLE MAXCPU SYMBOL XREF BASE EQU ORG DCI XDC DCI LI LR LM XDC ST XDC DS BNZ END	"SAMPLI 50 HEX H'0800' H'0100' BUFA BUFB H'80' 1,A	E PROGRAM TO MOVE DATA BETWEEN BUFFERS'' LIMIT OF 50 SECONDS CPU TIME SPECIFIED A SYMBOL TABLE WILL FOLLOW SOURCE PROGRAM SYMBOLS CROSS LISTING WILL FOLLOW SOURCE PROGRAM HEXADECIMAL NUMBERS SPECIFIED FOR ASSEMBLY LISTING SET THE VALUE OF SYMBOL BUFA SET THE VALUE OF SYMBOL BUFA SET DCO TO BUFA STARTING ADDRESS STORE IN DC1 SET DCO TO BUFB STARTING ADDRESS LOAD BUFFER LENGTH INTO ACCUMULATOR SAVE BUFFER LENGTH IN SCRATCHPAD BYTE 1 LOAD CONTENTS OF MEMORY BYTE ADDRESSED BY DCO EXCHANGE DCO AND DC1 STORE ACCUMULATOR IN MEMORY BYTE ADDRESSED BY DCO EXCHANGE DCO AND DC1 DECREMENT SCRATCHPAD BYTE 1 IF SCRATCHPAD BYTE 1 IF SCRATCHPAD BYTE 1 IS NOT ZERO, RETURN TO LOOP
---	--	--	--	--	---

^{*} BNZ will usually return to LOOP

Total Bytes = 17
Total Cycles = 31.5
Total Cycles within iterative loop = 14
Assuming 2 μ s cycle time, time to move 128 bytes = 2*(14*128+17.5)
= 3619 μ s

Fig. 9-1. Counting Cycles and Bytes

Instructions ONE and TWO execute in 3.5 cycles and occupy three bytes of memory. Instruction THRE executes in one cycle, occupies one byte of memory and replaces instruction IM.

Clearly instruction IM is better than ONE, TWO and THRE, if IM occurs just once; however, if instruction IM occurs identically n times, then it accumulates 2.5n cycles and 2n bytes of memory, whereas ONE, TWO and THRE accumulate (3.5+n) cycles and (3+n) bytes of memory, respectively. Therefore ONE, TWO and THRE will execute faster when:

ONE, TWO and THRE occupy less memory when:

In conclusion, if a 2-byte immediate instruction occurs identically (same operand) three or more times in a program, it is more efficient to load the immediate operand into a scratch-pad byte out of which it is referenced (providing a scratchpad byte is available).

9.2.3 Short Instructions

Always go over a source program, making sure that the short instructions LIS, INS and OUTS have been used wherever the operand is small enough.

9.2.4 Use of DS Instruction to Decrement and Test

Recall that when a DS instruction is used, the decremented scratchpad byte may be tested for "decrement-from-zero".

Since the DS instruction adds H'FF' to the designated scratchpad byte contents, the carry status will always be set unless the scratchpad byte contained 0 before it was decremented. Therefore the instruction sequence:

> DS n BC BACK

will decrement scratchpad byte n, return to BACK if byte n did not contain 0, but continue if byte n did contain 0.

9.2.5 Use of the BR7 Instruction

The BR7 instruction is very useful when manipulating data buffers in scratchpad memory, as described in Section 7.1.

9.3 PROGRAMMING FOR SPEED OR MEMORY ECONOMY

In the following subsections, programming techniques that tradeoff between execution speed and the amount of memory used are described.

9.3.1 Macros and Subroutines

To gain execution speed, possibly with a heavy increase in the amount of memory required, convert subroutines into macros as described in Section 7.4. Always carefully examine subroutines, particularly those which are infrequently called or receive parameters from the calling program, to see if converting the subroutine into a macro would save memory bytes and, at the same time, increase execution speed.

As described in Section 7.3, programs can be made much faster and will require less memory if subroutine nesting is limited to a first level. If a main program calls a subroutine, the subroutine can then call another subroutine. However, a subroutine cannot call another subroutine if it was, itself, called by a subroutine. Limiting subroutine nesting to a level of one means that return addresses can be stored in the stack register (PC1) and in the K registers of the scratchpad, eliminating the need for memory stacks.

9.3.2 Table Lookups Versus Data Manipulation

Program execution speed can frequently be increased by looking up data out of tables in ROM.

The concept is illustrated below, for the simple case of a 1-of-8 decoder.

An octal digit is input into the low order three bits of I/O port 0. The CPU must output, via I/O port 1, a data byte as follows:

Input From Port 0	Output At Port 1
0000001	00000001
00000010	00000010
00000011	00000100
00000100	00001000
00000110	00100000
00000111	01000000
00000000	10000000

*ONE OF EIGHT DECODER PROGRAM, NOT USING TABLE *LOOKUP

	INS	0	INPUT OCTAL CODE
	BNZ	110	INPUT IS NOT ZERO
	LIS	8	LOOP COUNTER
110	LR	0, A	TO LOOP COUNTER
	LIS	1	LOAD OUTPUT FOR 1
LOOP	DS	0	DECREMENT INPUT
	BZ	OUT	BRANCH OUT IF END
	\$L	1	SHIFT LEFT ONE BIT IF
			NOT END
	BR	LOOP	
OUT	OUTS	1	OUTPUT RESULT

*ONE	OF	EIGHT	DECODER	PROGRAM	USING	TABLE
*LOOK	UPS					
LKUP		oc .	0			
	- [OC .	2			
		С	4			
		oc	8			
	[OC .	16			
		oc	32			
	0	С	64			
		OC .	128			
	_	_				
	_	_				
	_	_				
	1	NS	0 1	NPUT OCTAL	CODE	
		OCI	LKUP I	OAD TABLE	BAŞE	
				ADDRESS		
	1	ADC	,	ADD INPUT C	ODE TO	BASE
			,	ADDRESS		
	L	.M	l	OAD OUTPU	T	
	(DUTS		OUTPUT RESI		

Efficiencies compare as follows:

		Non-Table Lookup	Table Looku
Instructions		10	5
Memory bytes		13	15
Execution cycles	min:	15	15
	max:	69.5	15

SOME USEFUL PROGRAMS

Some generally useful programs are given in this section. Programs are not shown as subroutines or as macros. The instructions implementing required logic are given, making it easy to incorporate an example into a program as a subroutine, a macro or directly as a section of main memory. These programs are intended to show programming techniques, rather than to demonstrate optimum program efficiency.

10.1 GENERATING TEXT

10.1.1 Simple and Dedicated Text Programs

The simplest text generation logic takes characters out of a memory buffer and outputs them via an I/O port. The I/O operation may be under program control, or interrupt I/O may be used. In each case, text is fetched via an elementary instruction sequence such as:

	DCI	TEXT	LOAD TEXT BUFFER
			STARTING ADDRESS
LOOP	LM		LOAD NEXT TEXT BYTE
*TEST F	OR END	-OF-RECORI	D CHARACTER, INSTRUCTIONS
*FOR TH	IS TEXT	ARENOTSH	OWN, SINCE THEY ARE A FUNC-
*TION O	F THE A	PPLICATION	l <u>.</u>

OUT	PRTN	OUTPUT CHARACTER VIA
		PORT N
BR	LOOP	RETURN FOR NEXT
		CHARACTER

10.1.2 Unpacking Decimal Digits

A byte containing two BCD digits is converted into two ASCII digits as follows:

LM		LOAD BYTE WITH TWO BCD DIGITS
LR	0,A	SAVE BYTE IN SCRATCHPAD BYTE 0
SL	4	
SR	4	ISOLATE LOW ORDER DIGIT
AS	1	ADD HIGH ORDER FOUR
		ASCII BITS
LR	2,A	SAVE IN SCRATCHPAD
		BYTE 2
LR	A,0	LOAD TWO BCD DIGITS
SR	4	ISOLATE HIGH ORDER DIGIT
AS	1	ADD HIGH ORDER FOUR
		BITS

^{*}CHARACTER OUTPUT SEQUENCE FOLLOWS HERE

This instruction sequence assumes that scratchpad byte 0 is available for temporary storage and that scratchpad byte 1 contains H'30'. Refer to Appendix B. A decimal digit becomes an ASCII character as follows:

Decimal digit, 0000 through 1001

This code identifies an ASCII decimal digit

If scratchpad byte 0 is not available, any other byte may be used for data storage.

If scratchpad byte 1 is not available, any other scratchpad byte, or the immediate instruction:

Al H'30'

may be used.

10.1.3 Variable Text

It is possible to have a text generation program in ROM that outputs variable text, temporarily stored in RAM. In other words, a fixed ROM program outputs messages of variable length and content. This is useful in word processing or human dialog applications. For example, an F8 microprocessor may drive a CRT used to collect data from convention attendees; the text program described below allows the dialog that will be displayed to be changed at any time, without changing the text generation program.

The text table (labeled TEXT below) contains characters in any mixed sequence.

The index table (labeled TIND below) consists of the following 3-byte sequence:

This variable text generation program uses two data tables: a text table and an index table.

Bytes 1 and 2 - Displacement from TEXT to first character to be output. If Byte 1 = H'FF', end of message is indicated. Byte 1 displacement cannot be H'FF'.

Byte 3 - Number of characters to be printed.

Messages are identified by number, starting at 1. A message's number is its sequential location, as identified by H'FF' codes in TIND.

Consider the following very simple example. The following four messages are to be generated:

- 1) ENTER PRODUCT NUMBER:
- 2) NO SUCH PRODUCT RE-ENTER:
- 3) NUMBER OF UNITS:
- 4) PRODUCT SHIP DATE:

The following TEXT table will be needed:

RE-ENTERUPRODUCT BNUMBER: BNOWSUCH BOFWUNITS: SHIPED ATE: B

				LR	DC,H	
Byte No.	Contents		L3	LM		LOAD NEXT CHARACTER TO
(Hexadecimal)	(Hexadecimal)					BE OUTPUT
•	(00	Message 1 is 20		Pi	COUT	OUTPUT CHARACTER
0 1	03 }	characters, starting at	*ANY C	UTPUT C	ODE MAY	REPLACE THE CALL TO SUB-
-	14	character 4	*ROUTII	NE COUT		
2	FF	End of message 1		DS	2	DECREMENT CHARACTER
3	00)	End of message				COUNTER
4	19 }	NO SUCH		BNZ	L3	RETURN FOR MORE
5	08	NO SOCH				CHARACTERS
6				XDC		AT END OF MESSAGE
7	00)	PRODUCT		BR	T10	SEGMENT, RESTORE TIND
8	09 }	PRODUCT				ADDRESS TO DCO
9	08 J		OUT			END OF PROGRAM. ANY
A	00)	DE ENTED				OTHER INSTRUCTIONS MAY
В	00 }	RE-ENTER		•		FOLLOW HERE
c	09)	F-1-6		_		
D	FF OO V	End of message 2		_		
E	00)	MUMARER				
F	11 }	NUMBER	TIND	ORG	X'0800'	ORIGIN ARBITRARILY
10	06 J			•		SELECTED
11	00)	05 10070		DC	H'00'	DISPLACEMENT TO HIGH
12	20 }	OF UNITS				BYTE
13	OA J			DC	H'03'	DISPLACEMENT TO LOW
14	FF .	End of message 3				BYTE
15	00)			DC	H'16'	NUMBER OF CHARACTERS
16	09 }	PRODUCT				IN THIS SEGMENT
17	08 /			DC	H'FF'	END OF MESSAGE 1
18	00)			_		
19	2A }	SHIP DATE:		_		
1A	OB)			_		
1B	FF	End of message 4		DC	H'OB'	
The following	program assumes	s that the message number		DC	H'FF'	
				-		

The following program assumes that the message number is in the accumulator. The program generates the specified message.

TGEN	LR	0,A	SAVE MESSAGE NUMBER IN BYTE 0
	DCI	TIND	LOAD TEXT INDEX STARTING ADDRESS
L1	DS	0	DECREMENT MESSAGE COUNTER
L2	BZ LM	T10	MESSAGE FOUND SEEK NEXT H'FF' BYTE IN TIND
	COM BNZ	L2	BYTE LOADED IS NOT H'FF'
T10	BR LM	L1	BYTE LOADED IS H'FF' MESSAGE FOUND. LOAD
	LR COM	0,A	NEXT THREE BYTES OF TIND AND SAVE IN SCRATCHPAD
	BZ LM	OUT	BYTES 0, 1 AND 2. TEST FIRST BYTE FOR H'FF' SIGNIFYING END OF MESSAGE
	LR LM	1,A	
	LR XDC	2,A	SAVE TIND ADDRESS IN DC1
	DCI	TEXT	LOAD TEXT ADDRESS INTO DCO
	LR ADC	A,0	ADD SCRATCHPAD BYTES 1 AND 0 TO DC0
	LR LR	H,DC A,10	

AS

1

10.2 MULTIBYTE ADDITION AND SUBTRACTION

10,A

LR

10.2.1 16-Bit, Binary Addition and Subtraction

The following program adds a 16-bit value in scratchpad bytes 1 (high) and 0 (low) to another 16-bit value in scratchpad bytes 3 (high) and 2 (low), as follows:

	LR	A,0	LOAD LOW ORDER
			AUGEND BYTE
	AS	2	ADD LOW ORDER
			ADDEND BYTE
	LR	2,A	SAVE ANSWER
	LR	A,1	LOAD HIGH ORDER
			AUGEND BYTE
	LNK		ADD ANY CARRY
	BNO	A1	IF NO OVERFLOW,
			CONTINUE
	BR	ERROR	MAKE ERROR EXIT FOR
			CARRY
A 1	AS	3	ADD HIGH ORDER
			ADDEND BYTE
	LR	3,A	SAVE ANSWER
	BNO	NEXT	IF NO OVERFLOW,
			CONTINUE
	BR	ERROR	MAKE ERROR EXIT FOR
			CARRY

To perform 16-bit binary subtraction, the two's complement of the 16-bit value in scratchpad bytes 1 and 0 is added to the 16-bit value in H. Instructions required are as follows:

To perform multibyte decimal subtraction, the routine should be changed as follows:

LR LR	DC,H A,O	MOVE SUBTRAHEND TO DC LOAD LOW ORDER BYTE OF MINUEND
COM		COMPLEMENT IT
ADC		ADD TO SUBTRAHEND
LIS ADC	1	ADD 1 TO SUBTRAHEND
LR	H,DC	RESTORE PARTIAL SUM TO H
LR	A,1	LOAD HIGH ORDER BYTE
2014		OF MINUEND
сом		COMPLEMENT
A\$	10	ADD HU TO ACCUMULATOR
LR	10,A	STORE ANSWER BACK

10.2.2 Multibyte Binary or Decimal Addition and Subtraction

Subroutine MADD, in any of the forms and variations described in Section 7, performs multibyte binary addition.

To perform multibyte binary subtraction make changes as follows. (Refer to the program version in Section 7.2.2):

Replace

EIGHT	сом		INITIALLY CLEAR THE
LOOP NINE	LR LM LR LNK	W,J J,W	CARRY BIT
with:			
EIGHT	LI INC	H'FF'	INITIALLY SET THE CARRY BIT BY LOADING H'FF' INTO
	LR	J,W	A, THEN INCREMENTING SAVE STATUS TO FORCE
LOOP	COM		TWOS COMPLEMENT LOAD NEXT BYTE COMPLEMENT THE
NINE	LR LNK	L,W	ACCUMULATOR RESTORE STATUS ADD CARRY, IF PRESENT

To perform multibyte decimal addition, referring again to the multibyte addition program as described in Section 7.2.2, replace

TWEL	AM		ADD CORRESPONDING ADDEND BYTE
with:			
TWEL	Al	H'66'	PRIME AUGEND FOR
	AMD		DECIMAL ADDITION ADD ADDEND DECIMAL

ONE LIS CNT USE SCRATCHPAD TWO LR O,A REGISTER O AS A COUNTER FOUR LR Q,DC STARTING ADDRESS IN Q FIVE DCI BUFA SAVE THE SOURCE BUFFER ADDRESSES IN DCO AND DC1 SEVEN DCI BUFB EIGHT LI H'66' LOAD IMMEDIATE H'66' LR 2,A AND SAVE FOR LATER USE INITIALLY SET CARRY TO 1 COM LR 8,A SCRATCHPAD BYTE 8 USED TO SAVE CARRY LOAD SUBTRAHEND INTO ACCUMULATOR COM AND MINUEND ADD MINUEND AS 8 ADD PRIOR BYTE'S CARRY ASD 2 DECIMAL CORRECT BY ADDING H'66' NNTN BNC TWTY+1 TEST IF DECIMAL CORRECT CREATES A CARRY THRT XDC READDRESS AUGEND BUFFER FRTN LR H,DC SAVE AUGEND ADDRESS IN H FFTN LR DC,Q LOAD ANSWER BUFFER ADDRESS IN Q EGTN LR DC,H MOVE AUGEND ADDRESS SYN ST STORE THE ANSWER SYTN LR Q,DC SAVE ANSWER BUFFER ADDRESS IN Q EGTN LR DC,H MOVE AUGEND ADDRESS BACK TO H US 2 LOAD CARRY FROM AMD STATUS IN Q OR ASD AND WITH SAVED STATUS IN Q OR ASD AND WITH SAVED STATUS IN S STATUS IN S STATUS IN S STATUS IN Q OR ASD AND WITH SAVED STATUS IN S SAVE IN SCRATCHPAD BYTE 1 TWT1 DS O DECREMENT COUNTER RETURN FOR MORE	BUFA BUFB BUFC CNT	EQU	H'092	20' AND BUFB ARE ADDED. THE
EIGHT LI H'66' LOAD IMMEDIATE H'66' LR 2,A AND SAVE FOR LATER USE INITIALLY SET CARRY TO 1 LOOP LR 8,A SCRATCHPAD BYTE 8 USED TO SAVE CARRY LM LOAD SUBTRAHEND INTO ACCUMULATOR COM AMD ADD MINUEND ADD MINUEND ADD MINUEND AS 8 ADD PRIOR BYTE'S CARRY ADDING H'66' NNTN BNC TWTY+1 TEST IF DECIMAL CORRECT CREATES A CARRY IF IT DOES, SAVE CARRY READDRESS AUGEND BUFFER FRTN LR H,DC SAVE AUGEND ADDRESS IN H FFTN LR DC,Q LOAD ANSWER BUFFER ADDRESS IN Q EGTN LR Q,DC SAVE ANSWER BUFFER ADDRESS IN Q EGTN LR DC,H MOVE AUGEND ADDRESS BACK TO H LIS 2 LOAD CARRY FROM AMD NS 9 OR ASD AND WITH SAVED STATUS IN J SR 1 SAVE IN SCRATCHPAD BYTE 1 TWT1 DS 0 DECREMENT COUNTER	TWO THREI FOUR FIVE	LR E DCI LR DCI	O,A BUFC Q,DC	REGISTER 0 AS A COUNTER SAVE THE ANSWER BUFFER STARTING ADDRESS IN Q SAVE THE SOURCE BUFFER ADDRESSES IN DCO
LOOP LR 8,A SCRATCHPAD BYTE 8 USED TO SAVE CARRY LOAD SUBTRAHEND INTO ACCUMULATOR COM ELEV XDC AMD ADD MINUEND ADD MINUEND ADD MINUEND ADD PRIOR BYTE'S CARRY ADDING H'66' NNTN BNC TWTY+1 TEST IF DECIMAL CORRECT CREATES A CARRY IF IT DOES, SAVE CARRY READDRESS AUGEND BUFFER FRTN LR H,DC SAVE AUGEND ADDRESS IN H FFTN LR DC,Q LOAD ANSWER BUFFER ADDRESS IN Q SXTN ST STORE THE ANSWER SUFFER ADDRESS IN Q EGTN LR DC,H MOVE AUGEND ADDRESS BACK TO H LIS 2 LOAD CARRY FROM AMD OR ASD AND WITH SAVED STATUS IN J SR 1 SAVE IN SCRATCHPAD BYTE 1 TWT1 DS 0 DECREMENT COUNTER		LI LR	H'66' 2,A	AND SAVE FOR LATER USE
ELEV XDC ADDRESS MINUEND AMD ADD MINUEND LR J,W SAVE STATUS AS 8 ADD PRIOR BYTE'S CARRY ASD 2 DECIMAL CORRECT BY ADDING H'66' NNTN BNC TWTY+1 TEST IF DECIMAL CORRECT CREATES A CARRY THRT XDC READDRESS AUGEND BUFFER FRTN LR H,DC SAVE AUGEND ADDRESS IN H FFTN LR DC,Q LOAD ANSWER BUFFER ADDRESS SXTN ST STORE THE ANSWER SVTN LR Q,DC SAVE ANSWER BUFFER ADDRESS IN Q EGTN LR DC,H MOVE AUGEND ADDRESS BACK TO H LIS 2 LOAD CARRY FROM AMD NS 9 OR ASD AND WITH SAVED STATUS IN J SR 1 SAVE IN SCRATCHPAD BYTE 1 TWT1 DS 0 DECREMENT COUNTER	LOOP	LR LM	-	SCRATCHPAD BYTE 8 USED TO SAVE CARRY LOAD SUBTRAHEND INTO
ADDING H'66' TWTY+1 TEST IF DECIMAL CORRECT CREATES A CARRY IF IT DOES, SAVE CARRY READDRESS AUGEND BUFFER FRTN LR H,DC SAVE AUGEND ADDRESS IN H FFTN LR DC,Q LOAD ANSWER BUFFER ADDRESS SXTN ST STORE THE ANSWER SVTN LR Q,DC SAVE ANSWER BUFFER ADDRESS IN Q EGTN LR DC,H MOVE AUGEND ADDRESS BACK TO H LIS 2 LOAD CARRY FROM AMD NS 9 OR ASD AND WITH SAVED STATUS IN J SR 1 SAVE IN SCRATCHPAD BYTE 1 TWT1 DS 0 DECREMENT COUNTER	ELEV	XDC AMD LR AS	8	ADDRESS MINUEND ADD MINUEND SAVE STATUS ADD PRIOR BYTE'S CARRY
THRT XDC IF IT DOES, SAVE CARRY READDRESS AUGEND BUFFER FRTN LR H,DC SAVE AUGEND ADDRESS IN H FFTN LR DC,Q LOAD ANSWER BUFFER ADDRESS SXTN ST STORE THE ANSWER SVTN LR Q,DC SAVE ANSWER BUFFER ADDRESS IN Q EGTN LR DC,H MOVE AUGEND ADDRESS BACK TO H LIS 2 LOAD CARRY FROM AMD OR ASD AND WITH SAVED STATUS IN J SR 1 SAVE IN SCRATCHPAD BYTE 1 TWT1 DS 0 DECREMENT COUNTER	NNTN	BNC	TWTY+1	ADDING H'66' TEST IF DECIMAL CORRECT
FFTN LR DC,Q LOAD ANSWER BUFFER ADDRESS STORE THE ANSWER SVTN LR Q,DC SAVE ANSWER BUFFER ADDRESS IN Q EGTN LR DC,H MOVE AUGEND ADDRESS BACK TO H LIS 2 LOAD CARRY FROM AMD NS 9 OR ASD AND WITH SAVED STATUS IN J SR 1 SAVE IN SCRATCHPAD BYTE 1 TWT1 DS 0 DECREMENT COUNTER			J,W	IF IT DOES, SAVE CARRY READDRESS AUGEND
FFTN LR DC,Q LOAD ANSWER BUFFER ADDRESS SXTN ST STORE THE ANSWER SVTN LR Q,DC SAVE ANSWER BUFFER ADDRESS IN Q EGTN LR DC,H MOVE AUGEND ADDRESS BACK TO H LIS 2 LOAD CARRY FROM AMD NS 9 OR ASD AND WITH SAVED STATUS IN J SR 1 SAVE IN SCRATCHPAD BYTE 1 TWT1 DS 0 DECREMENT COUNTER	FRTN	LR	H,DC	
SXTN ST STORE THE ANSWER SVTN LR Q,DC SAVE ANSWER BUFFER ADDRESS IN Q EGTN LR DC,H MOVE AUGEND ADDRESS BACK TO H LIS 2 LOAD CARRY FROM AMD NS 9 OR ASD AND WITH SAVED STATUS IN J SR 1 SAVE IN SCRATCHPAD BYTE 1 TWT1 DS 0 DECREMENT COUNTER		LR	DC,Q	LOAD ANSWER BUFFER
EGIN LR DC,H MOVE AUGEND ADDRESS BACK TO H LIS 2 LOAD CARRY FROM AMD NS 9 OR ASD AND WITH SAVED STATUS IN J SR 1 SAVE IN SCRATCHPAD BYTE 1 TWT1 DS 0 DECREMENT COUNTER			Q,DC	STORE THE ANSWER SAVE ANSWER BUFFER
LIS 2 LOAD CARRY FROM AMD NS 9 OR ASD AND WITH SAVED STATUS IN J SR 1 SAVE IN SCRATCHPAD BYTE 1 TWT1 DS 0 DECREMENT COUNTER	EGTN	LR	DC,H	MOVE AUGEND ADDRESS
SR 1 SAVE IN SCRATCHPAD BYTE 1 TWT1 DS 0 DECREMENT COUNTER				LOAD CARRY FROM AMD OR ASD AND WITH SAVED
TWT1 DS 0 DECREMENT COUNTER		SR	1	SAVE IN SCRATCHPAD
	TWT1		_	DECREMENT COUNTER

10.3 MULTIPLICATION

There are a number of possible multiplication routines.

Consider first the binary multiplication of two 8-bit, positive numbers (in scratchpad bytes 0 and 1) to give a 16-bit prodduct in scratchpad bytes 7 (high) and 6 (low). The following program performs the required multiplication:

*BINARY	MULTIPLY	Y SUBROU	TINE
*SCRATC	H REG 1	CONTAINS	MULTIPLIER
*SCRATC	H REG 2	CONTAINS	MULTIPLICAND
*SCRATC	H REGS 6	AND 7 C	ONTAIN PRODUCT (SR7=MSB)
BMPY	LIS	8	INITIALIZE COUNTER TO 8
	LR	5,A	
	LIS	0	ZERO PRODUCT
	LR	6,A	
	LR	7,A	
BMP1	LR	A,6	SHIFT PARTIAL
	AS	6	PRODUCT LEFT 1
	LR	6,A	
	LR	A,7	
	LNK		
	AS	7	
	LR	7,A	
	LR	A,1	SHIFT MULTIPLIER
	AS	1	LEFT 1, BY ADD
	LR	1,A	IF CARRY IF SET
	BNC	BMP2	ADD MULTIPLICAND TO
			PRODUCT
	LR	A,2	ADD
	AS	6	MULTIPLICAND
	LR	6,A	то
	LR	A,7	PRODUCT
	LNK		
	LR	7,A	
BMP2	DS	5	DECREMENT COUNT
	BNZ	BMP1	NOT FINI, REPEAT
	_		
T (1			E hisse and avacutos in a maxi-
The above	e program	occupies 2	6 bytes and executes in a maxis is with the program in Section
mum of a	3/3 μs. υ	ontrast tin	bytes, but executes in between
			bytes, but executes in between
20μs and	d 1800.5 /	us.	
Vary fact	docimal	multinlicati	on can be achieved using table
lookuna	Consider I	a 2-digit :	decimal number in scratchpad
wokups.	Consider	a z-uigit i	document from the control of

Very fast decimal multiplication can be achieved using table lookups. Consider a 2-digit decimal number in scratchpad byte 0, multiplied by a 2-digit decimal number in scratchpad byte 1, to give a 4-digit answer in scratchpad bytes 7 (high) and 6 (low). The routine uses 100 bytes of ROM, to hold the following table:

TABX+00 01 02 03 04 0	05 06 07 08 09 0A	OB OC OD OE OF
holds: 00 00 00 00 00 0	00 00 00 00 00	Not Used

TABX+10 11	12 13 14 1	5 16 17 18 19 14	4 1B 1C 1D 1E 1F
holds: 00 01	02 03 04 0	5 06 07 08 09	Not Used

TABX+20 21	22 2	3 24	25	26	27	28	29	2A	2B	2C	2D	2E	2F
holds: 00 02	04.0	ഒ റമ	10	12	14	16	18		N.	lot l	Jse	d	

TABX+30 31	32 33 34	35 36 3	7 38 39 3A	3B 3C 3D 3E 3F
holds: 00 03	06 09 12	2 15 18 2	1 24 27	Not Used

TABX+40 41 42 43	44 45 46 47 48 49	4A 4B 4C 4D 4E 4F
1 14 00 04 00 40		

TABX+80 81 82 83 84 85 86 87 88 89 8A 8B 8C 8D 8E 8F holds: 00 08 16 24 32 40 48 56 64 72 Not Used

TABX+90 91 92 93 94 95 96 97 98 99 9A 9B 9C 9D 9E 9F holds: 00 09 18 27 36 45 54 63 72 81 Not Used

All numbers above are hexadecimal. Suppose TABX is equated to H'2000'; then byte H'2008' contains H'00'; byte H'2024' contains H'08'; byte H'2094' contains H'36'; etc.

The table lookup proceeds as follows:

LR	A,0	ISOLATE MULTIPLIER
SL	4	LOW ORDER DIGIT
SR	4	
LR	2,A	STORE IN BYTE 2
LR	A,1	LOAD MULTIPLICAND
SL	4	ISOLATE LOW ORDER DIGIT
	2	ADD MULTIPLIER LOW
AS	2	ORDER DIGIT X16
		
DCI	TABX	LOAD TABLE BASE
		ADDRESS
LR	H,DC	SAVE BASE FOR FURTHER
		USE
ADC		ADD ACCUMULATOR INDEX
LM		LOAD PRODUCT FROM
LIVI		TABLE
		STORE IN LOW ORDER
LR	6,A	
		BYTE OF ANSWER
LR	Α,Ο	LOAD MULTIPLIER
SR	4	ISOLATE HIGH ORDER DIGIT
LR	3,A	SAVE IN BYTE 3
LR	A,1	LOAD MULTIPLICAND
SR	4	ISOLATE HIGH ORDER DIGIT
SL	4	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,
AS	3	ADD MULTIPLIER HIGH
AS	3	
		ORDER DIGIT
LR	DC,H	LOAD TABLE BASE
		ADDRESS
ADC		ADD ACCUMULATOR INDEX
LM		LOAD PRODUCT FROM
		TABLE
LR	7,A	STORE IN HIGH ORDER BYTE
LR	,, <u>,</u>	OF ANSWER
		LOAD LOW ORDER DIGIT OF
LR	A,1	
SL	4	MULTIPLICAND
AS	3	ADD HIGH ORDER DIGIT OF
		MULTIPLIER
LR	DC,H	OBTAIN PRODUCT
ADC		
LM		
LR	3.A	SAVE IN BYTE 3
SL	4	ADD LOW ORDER DIGIT TO
	•	ADD LOVE ON BELL BIGHT TO
Al	H'66'	WOULDEDER DIGIT OF
ASD	6	HIGH ORDER DIGIT OF
		BYTE 6
LR	J,W	
LR	6,A	
LR	A,3	ISOLATE HIGH ORDER DIGIT
SR	4	OF PRODUCT IN LOW
O-11	•	ORDER POSITION
LR	L,W	C.1.2 L.1. 1 C.1.10.1
	V V J	OF ACCUMULATOR, ADD
LNK		
		LINK

Al	H'66'	
ASD	7	ADD HIGH ORDER BYTE OF ANSWER
LR	7,A	RESTORE HIGH ORDER BYTE OF ANSWER
LR	A,1	LOAD HIGH ORDER DIGIT
SR	4	OF MULTIPLICAND
SL	4	
AS	2	ADD LOW ORDER DIGIT OF MULTIPLIER
LR	DC.H	OBTAIN PRODUCT
ADC	,	30.7 1.102001
LM		SAVE IN BYTE 3
LR	3,A	
SL	4	ADD LOW ORDER DIGIT TO
ΑI	H'66'	
ASD	6	HIGH ORDER DIGIT OF BYTE 6
LR	J,W	BITE O
LR	6.A	
LR	A.3	ISOLATE HIGH ORDER DIGIT
SR	4	OF PRODUCT IN LOW ORDER POSITION

LR	W,J	
LNK		OF ACCUMULATOR.
		ADD LINK
Αi	H'66'	
ASD	7	ADD HIGH ORDER BYTE
		OF ANSWER
LR	7,A	RESTORE HIGH ORDER
		BYTE OF ANSWER

More compact versions of this program could be written, but they would take longer to execute.

10.4 DIVISION

Division of positive numbers can be performed by a program using successive subtraction as follows:

- 1) Zero the answer
- 2) Subtract the divisor from the dividend
- 3) Test for a negative result
- 4) For a positive result, increment the answer and return to 2
- 5) For a negative result, the division is finished. Add the divisor to the dividend to obtain remainder.

APPENDIX A - BINARY NUMBER SYSTEM

The binary number system is a system of counting which utilizes the digits 1 and 0 to represent numeric quantities. The binary digits, referred to as BITs, are arranged in a sequence of decreasing significance based upon powers of two. Each bit is numbered. By convention, the most significant bit is on the left, and the least significant bit is on the right.

For example, consider the binary number:

Binary number	0	1	1	0	0	1
Bit number	5	4	3	2	1	0
Power of base two	25	24	2 ³	22	21	20
Significance	32	16	8	4	2	1

As in any number system, the quantity represented by a binary number is calculated by multiplying each digit by its significance, then summing products.

The binary number example is evaluated as follows:

Quantity =
$$0*2^6+1*2^4+1*2^3+0*2^2+0*2^1+1*2^0$$

= $0 + 16 + 8 + 0 + 0 + 1$
= 25

Binary numbers may be used to represent any real number positive or negative.

Non-integer numbers are represented in the same binary format shown above except that the significance of the bits changes. To indicate the correct interpretation of a binary number, a "binary point" (which is analogous to a decimal point in the decimal number system) is inserted. Consider the binary number below:

Binary number	0	1	1	0	0	1	. 1
Bit number	6	5	4	3	2	1	0
Power of base two	25	24	23	2 ²	21	20	2-1
Significance	32	16	8	4	2	1	1/2

The number is evaluated as follows:

Quantity =
$$0*2^5+1*2^4+1*2^3+0*2^2+0*2^1+1*2^0+1*2^{-1}$$

= 0 + 16 + 8 + 0 + 0 + 0 + .5
= 25.5

The bits of a binary number may be grouped in fours and transposed into the hexadecimal number system which includes the following digits:

The following example illustrates the procedure:

In this manual, hexadecimal numbers are written within quotation marks and preceded by an H. Consider the example:

H'27', H'AE10', H'F'

The octal number system includes the following digits:

Binary numbers are transposed into octal numbers by arranging the bits into groups of three as illustrated below:

101001	Binary number
101 001	
5 1	Octal number

The Indirect Scratchpad Address Register (ISAR) uses two octal digits to address 64 scratchpad registers.

Octal numbers are written within quotation marks preceded by an O as follows:

Table A-1 illustrates the relationship between binary, decimal, hexadecimal and octal numbers.

BINARY	DECIMAL	HEXADECIMAL	OCTAL
0000	0	0	0
0001	1 1	1	Ĭ
0010	2	2	2
0011	3	3	3
0100	4	4	4
0101	5	5	5
0110	6	6	6
0111	7	7	7
1000	8	8	10
1001	9	9	11
1010	10	Ā	12
1011	11	В	13
1100	12	- c	14
1101	13	Ď	15
1110	14	Ē	16
1111	15		17

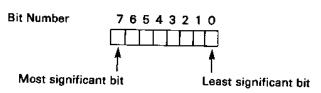
Table A-1. Binary, Decimal, Hexadecimal and Octal Numbers

THE BYTE

The Fairchild F8 microprocessor is an 8-bit device, which means that data is handled in eight binary digit (or one byte) units. An 8-bit byte may represent 256 (28) possible permutations of eight digits.

When referencing the 8-bit byte, this manual has established the following conventions.

The bits are numbered from right to left with numbers 0 through 7. The most significant bit is on the left; the least significant bit is on the right.



An 8-bit byte may represent an instruction object code, an ASCII code or a data word.

An 8-bit data word may be interpreted as a signed binary number with a value of from 127 to -128 as illustrated in Table A-2.

It will become clear after reading the sections which follow on binary arithmetic, that the signed binary number system is a natural fallout of two's complement subtraction.

BINARY	DECIMAL	HEXADECIMAL
10000000	-128	80
100000001	-127	81
10000010	-126	82
10000010		-
	_	i –
		_
11111110	-2	FE
11111111	-1	FF
00000000	o	0
00000001	1	1
00000010	2	2
	_	-
		_
_	į	_
01111101	+125	7D
01111110	+126	7E
01111111	+127	7F

Table A-2. Signed Binary Numeric Interpretations

Binary Number Addition

Addition of binary numbers is accomplished by following three rules.

Consider the addition of two positive 8-bit binary numbers:

A carry out of bit 7 has occurred as a result of the addition. The carry bit is set to indicate that the results of the addition cannot be represented in the existing 8-bits. However, if the carry bit represents the next higher significant bit, the results are valid.

In a multiple byte addition, the carry bit from the most significant bit position of a byte is added to the least significant

bit of the next (higher order) byte as follows:

Binary Number Subtraction

Subtracting a binary number is the same as adding the two's complement of the number.

The two's complement of a number is generated by complementing the number (replacing 0 with 1 and 1 with 0) and adding one to the complement. Here is an example:

Observe that negative numbers in Table A-2 are the two's complement of their positive equivalents. In this fashion, an 8-bit number can contain sign and value information for numbers between 128 and -127.

When adding signed binary numbers, care must be taken to indicate when the result exceeds the boundaries of the two's complement notation.

To exemplify the need for such indicators, consider some simple examples using the set of 3-bit signed binarynumbers from 3 to -4.

Signed Binary Numbers	Decimal
011	3
010	2
001	1
000	0
111	-1
110	-2
101	-3
100	-4

Any number greater than 3 or less than -4 is outside the boundaries of the set of 3-bit signed binary numbers.

The addition of two numbers within this set may result in a number which is not defined as part of the set.

Consider the addition of two numbers with like signs:

In example 1, no carry out of the two high order bits occured. The result is defined and valid.

In example 2, carry out from the bit which precedes the sign bit (carry out from bit 2) occurred. The result is undefined and therefore invalid.

In example 3, a carry from bit 2 and 3 occurred. The result is defined and valid.

In example 4, a carry from the sign bit occurred. The result is undefined and invalid.

The explanation of the four examples illustrates the rules which govern the error indication mechanism in the Fairchild F8 microprocessor. If the addition of two 8-bit numbers causes a result which is outside the boundary defined for 8-bit signed binary numbers, (illustrated in Table A-1), an overflow status bit is set.

The overflow status bit is defined as the EXCLUSIVE-OR of the carry out of bit 6 and the carry out of bit 7. (EXCLUSIVE-OR is defined later in this appendix.)

Consider binary number subtraction, (the addition of a binary number to a two's complement number).

1) two's	Bit No. H'52' s complement		0	1	0	1	3 0 1	ō	1	ŏ
	H'34'		0	0	1	1	0	1	o	0
	<u>-H'52'</u>	_	1	0	1	0	1	1	1	0
	~H'18'	0	1	1	1	0	0	0	1	ō
two's	s complement	_								
	H'18'		0	0	0	1	1	0	0	0
2)	Bit No.		7	6	5	4	3	2	1	0
	H'2A'		0	0	1	0	1	0	1	0
two's	s complement		1	1	0	1	0	1	1	0
	H'B6'		1	0	1	1	0	1	1	0
	<u>-H'2A'</u>			1	0	1	0	1	1	0
	H '8A '	1	1	0	0	0	1	1	Ō	0

In example 1, the subtrahend is larger than the minuend, indicating a negative answer. In unsigned binary number arithmetic, a negative result is indicated by no carry out of the most significant bit and is in two's complement form. There is no overflow because there is no carry out of either bit 6 or bit 7.

In example 2, the subtrahend is smaller than the minuend indicating a positive answer. In unsigned binary arithmetic, a positive result is indicated by a carry from the most significant bit position and is in straight binary form. There is no overflow because there is a carry out of both bit 6 and bit 7.

Multiplication of binary numbers may be performed in two ways: repetitive addition or in the fashion illustrated below, which is similar to the long hand method for multiplying decimal numbers;

Division of binary numbers may be accomplished by repetitive subtraction of one operand from another, or by an operation similar to long hand division:

COMPUTER LOGIC

Assembly language instructions exist which perform logical operations on operands. Three such logical operations are described below (logical-OR, AND, and EXCLUSIVE-OR).

The logical-OR operation is illustrated for the two operands I and J with the statement:

If I or J equals 1, then the result is 1. Otherwise, the result is zero.

The symbol used to indicate the logical-OR operation is the sign (V). Consider the logical-OR of two binary numbers:

The logical AND operation is illustrated for the two operands I and J with the following statement:

If both I and J are 1, then the result is 1. Otherwise, the result is zero.

The symbol used for the logical AND operation is (\land) .

Consider the logical AND of two binary numbers:

The logical EXCLUSIVE-OR operation is illustrated for the operands I and J with the following statement:

If both I and J equal 1 or both I and J equal 0, the result is zero, otherwise the result is 1.

The symbol used to indicate the logical EXCLUSIVE-OR operation is a circled sign (\oplus),

Consider the logical EXCLUSIVE-OR of two binary numbers:

APPENDIX B - ASCII CODES

	GRAPHIC OR CONTROL	ASCII (HEXADECIMAL)
	NULL	00
ł	SOM	01
	EOA	02
	EOM	03
i	EOT	04
1	WRU	05
	RU	06
	BELL	07
	FE	08
	H. Tab	09
	Line Feed	0A
	V. Tab	OB
	Form	OC .
	Return	OD .
	SO	OE
	\$I	OF .
	DCO	10
	X-On	11
	Tape Aux. (
	X-Off	13
	Tape Aux.	
	Error	15
	Sync	16
	LEM	17
	\$0	18
ĺ	S1	19
	S2	1A
	S3	1B
	S4	1C
	\$5	1D
	S6	1£
	S7	1F

GRAPHIC OR	ASCII
CONTROL	(HEXADECIMAL)
ACK	7C
Alt. Mode	7D
Rubout	7F
!	21
"	22
#	23
\$	24
%	25
&	26
•	27
(28
)	29
*	2A
+	2B
•	2C
	2D
· / : ; < = > ? [\]	2E
/	2F
:	3A
;	3B
<	3C
=	3D
>	3F
?	3F
[5B
	5C
]	5D
†	5E
	5F
@	40
blank	20
0	30

GRAPHIC OR	ASCII
CONTROL	(HEXADECIMAL)
1	31
2	32
3	33
4	34
2 3 4 5	35
6	36
7	37
8	38
9	39
Α	41
В	42
С	43
D	44
E	45
F	46
G	47
Н	48
1	49
J	4A
K	4B
L	4C
М	4D
N	4E
0	4F
P	50
Q	51
R	52
S	53
Т	54
U	55
V	56
W	57
X	58
Υ	5 9
Z	5A

APPENDIX C - CONVERSION TABLES/TIMER COUNTS

POWERS OF TWO

```
n 2<sup>-n</sup>
                                          0 1.0
                                          1 0.5
                                          2 0.25
                                          3 0.125
                                    16
                                         4 0.062 5
                                          5 0.031 25
                                          6 0.015 625
                                          7 0.007 812 5
                                         8 0.003 906 25
                                        9 0.001 953 125
                                1 024 10 0.000 976 562 5
                               2 048 11 0.000 488 281 25
                              4 096 12 0.000 244 140 625
8 192 13 0.000 122 070 312 5
16 384 14 0.000 061 035 156 25
                              32 768 15 0.000 030 517 578 125
                            65 536 16 0.000 015 258 789 062 5
131 072 17 0.000 007 629 394 531 25
                            262 144 18 0.000 003 814 697 265 625
                            524 288 19 0.000 001 907 348 632 812 5
                         1 048 576 20 0.000 000 953 674 316 406 25
                         2 097 152 21 0.000 000 476 837 158 203 125
4 194 304 22 0.000 000 238 418 579 101 562 5
                         8 388 608 23 0.000 000 119 209 289 550 781 25

    16
    777
    216
    24
    0.000
    000
    059
    604
    644
    775
    390
    625

    33
    554
    432
    25
    0.000
    000
    029
    802
    322
    387
    695
    312
    5

    67
    108
    864
    26
    0.000
    000
    014
    901
    161
    193
    847
    656
    25

    134
    217
    728
    27
    0.000
    000
    007
    450
    580
    596
    923
    828
    125

                      268 435 456 28 0.000 000 003 725 290 298 461 914 062 5
                   536 870 912 29 0.000 000 001 862 645 149 230 957 031 25
1 073 741 824 30 0.000 000 000 931 322 574 615 478 515 625
                   2 147 483 648 31 0.000 000 000 465 661 287 307 739 257 812 5
                     294 967 296 32 0.000 000 000 232 830 643 653 869 628 906 25
                 8 589 934 592 33 0.000 000 000 116 415 321 826 934 814 453 125 17 179 869 184 34 0.000 000 000 058 207 660 913 467 407 226 562 5
                 34 359 738 368 35 0.000 000 000 029 103 830 456 733 703 613 281 25
                 68 719 476 736 36 0.000 000 000 014 551 915 228 366 851 806 640 625
               137 438 953 472 37 0.000 000 000 007 275 957 614 183 425 903 320 312 5 274 877 906 944 38 0.000 000 000 003 637 978 807 091 712 951 660 156 25
               549 755 813 888 39 0.000 000 000 001 818 989 403 545 856 475 830 078 125
               796 093 022 208 43 0.000 000 000 000 113 686 837 721 616 029 739 379 882 812 5
         17 592 186 044 416 44 0.000 000 000 000 056 843 418 860 808 014 869 689 941 406 25 35 184 372 088 832 45 0.000 000 000 000 028 421 709 430 404 007 434 844 970 703 125 70 368 744 177 664 46 0.000 000 000 000 014 210 854 715 202 003 717 422 485 351 562 5 140 737 488 355 328 47 0.000 000 000 000 007 105 427 357 601 001 858 711 242 675 781 25
         281 474 976 710 656 48 0.000 000 000 000 003 552 713 678 800 500 929 355 621 337 890 625
      562 949 953 421 312 49 0.000 000 000 000 001 776 356 839 400 250 464 677 810 668 945 312 5 1 125 899 906 842 624 50 0.000 000 000 000 000 888 178 419 700 125 232 338 905 334 472 656 25 2 251 799 813 685 248 51 0.000 000 000 000 000 444 089 209 850 062 616 169 452 667 236 328 125
      4 503 599 627 370 496 52 0.000 000 000 000 000 222 044 604 925 031 308 084 726 333 618 164 062 5
    9 007 199 254 740 992 53 0.000 000 000 000 000 111 022 302 462 515 654 042 363 166 809 082 031 25 18 014 398 509 481 984 54 0.000 000 000 000 055 511 151 231 257 827 021 181 583 404 541 015 625
        028 797 018 963 968 55 0.000 000 000 000 000 027 755 575 615 628 913 510 590 791 702 270 507 812 5
    72 057 594 037 927 936 56 0.000 000 000 000 000 013 877 787 807 814 456 755 295 395 851 135 253 906 25
   144 115 188 075 855 872 57 0.000 000 000 000 000 006 938 893 903 907 228 377 647 697 925 567 676 950 125 288 230 376 151 711 744 58 0.000 000 000 000 003 469 446 951 953 614 188 823 848 962 783 813 476 562 5
   576 460 752 303 423 488 59 0.000 000 000 000 000 001 734 723 475 976 807 094 411 924 481 391 906 738 281 25
9 223 372 036 854 775 808 63 0.000 000 000 000 000 000 108 420 217 248 550 443 400 745 280 086 994 171 142 578 125
```

TABLE OF POWERS OF SIXTEEN $_{10}$

											-		
						16 ⁿ	n			16	i-n		
						1	0	0.10000	00000	00000	00000	x	10
						16	1	0.62500	00000	00000	00000	×	10 ^{~1}
						256	2	0.39062	50000	00000	00000	x	10^{-2}
					4	096	3	0.24414	06250	00000	00000	×	10^{-3}
					65	536	4	0.15258	78906	25000	00000	×	10^{-4}
				1	048	576	5	0.95367	43164	06250	00000	×	10 ⁻⁶
				16	777	216	6	0.59604	64477	53906	25000	×	10^{-7}
				268	435	456	7	0.37252	90298	46191	40625	×	10 ⁻⁸
			4	294	967	296	8	0.23283	06436	53869	62891	x	10 ⁻⁹
			68	719	476	736	9	0.14551	91522	83668	51807	×	10^{-10}
		1	099	511	627	776	10	0.90949	47017	72928	23792	x	10^{-12}
		17	592	186	044	416	11	0.56843	41886	08080	14870	×	10-13
		281	474	976	710	656	12	0.35527	13678	80050	09294	×	10 ⁻¹⁴
	4	503	599	627	370	496	13	0.22204	46049	25031	30808	×	10^{-15}
	72	057	594	037	927	936	14	0.13877	78780	78144	56755	×	10^{-16}
1	152	921	504	606	846	976	15	0.86736	17379	88403	54721	x	10^{-18}

TABLE OF POWERS OF 10_{16}

			10 ⁿ	n		10	-n			
			1	0	1.0000	0000	0000	0000		
			Α	1	0,1999	9999	9999	999A		
			64	2	0.28F5	C28F	5C28	F5C3	x	16-1
			3E8	3	0.4189	374B	C6A7	EF9E	x	16 ⁻²
			2710	4	0,68DB	8BAC	710C	B296	x	16^{-3}
		1	86A0	5	0.A7C5	AC47	1B47	8423	×	16 ⁻⁴
		F	4240	6	0.1006	F7A0	85ED	8D37	×	16 ⁻⁴
		98	9680	7	0.1AD7	F29A	BCAF	4858	х	16 ⁻⁵
		5F5	E100	8	0.2AF3	1DC4	6118	73BF	×	16 ⁶
		3B9A	CA00	9	0.44B8	2FA0	9B5A	52CC	×	16^{-7}
	2	540B	E400	10	0.6DF3	7 F67	SEF6	EADF	x	16 ⁻⁸
	17	4876	E800	11	0.AFEB	FF0B	CB24	AAFF	×	16^{-9}
	E8	D4A5	1000	12	0.1197	9981	2DEA	1119	x	16 ⁻⁹
	918	4E72	A000	13	0.1C25	C268	4976	81C2	×	16 ⁻¹⁰
	5AF3	107A	4000	14	0.2D09	370D	4257	3604	×	16 ⁻¹¹
3	8D7E	A4C6	8000	15	0.480E	BE7B	9D58	566D	х	16^{-12}
23	8652	6FC1	0000	16	0.734A	CA5F	6226	F0AE	x	16 ⁻¹³
163	4578	5D8A	0000	17	0.B877	AA32	36A4	B449	x	16^{-14}
DE0	B6B3	A764	0000	18	0.1272	5DD1	D243	ABA1	x	16 ^{- 14}
BAC7	2304	89E8	0000	19	0.1D83	C94F	B6D2	AC35	x	16^{-15}

HEXADECIMAL-DECIMAL INTEGER CONVERSION

The table below provides for direct conversions between hexadecimal integers in the range 0-FFF and decimal integers in the range 0-4095. For conversion of larger integers, the table values may be added to the following figures:

			5 5
Hexadecimal	Decimal.	Hexadecimal	Decimal
01 000	4 096	20 000	131 072
02 000	8 192	30 000	196 608
03 000	12 288	40 000	262 144
04 000	16 384	50 000	327 680
05 000	20 480	60 000	393 216
06 000	24 576	70 000	458 752
07 000	28 672	80 000	524 288
08 000	32 768	90 000	589 824
09 000	36 864	AD 000	655 360
0A 000	40 960	B0 000	720 896
0B 0 0 0	45 056	C0 000	786 432
0C 000	49 152	D0 000	851 968
0D 000	53 248	E0 000	917 504
0E 000	57 344	F0 000	983 040
0F 000	61 440	100 000	1 048 576
10 000	65 536	200 000	2 097 152
11 000	69 632	300 000	3 145 728
12 000	73 728	400 000	4 194 304
13 000	77 824	500 000	5 242 880
14 000	81 920	600 000	6 291 456
15 000	86 016	700 000	7 340 032
16 000	90 112	800 000	8 388 608
17 000	94 208	900 000	9 437 184
18 000	98 304	A00 000	10 485 760
19 000	102 400	B00 000	11 534 336
1A 000	106 496	C00 000	12 582 912
1B 000	110 592	D00 000	13 631 488
1C 000	114 688	E00 000	14 680 064
1D 000	118 784	F00 000	15 728 640
1E 000	122 880	1 000 000	16 777 216
1F 000	126 976	2 000 000	33 554 432

	0	11	2	3	4	5	6	7	8	9		В	С	D		
000	0000	0001	0002	0003	0004	0005	0006	0007	0008	0009	0010	0011	0012	0013	0014	0015
010	0016	0017	0018	0019	0020	0021	0022	0023	0024	0025	0026	0027	0028	0029	0030	0013
020	0032	0033	0034	0035	0036	0037	0038	0039	0040	0041	0042	0043	0044	0045	0046	0031
030	0048	0049	0050	0051	0052	0053	0054	0055	0056	0057	0058	0059	0060	0061	0062	0063
040	0064	0065	0066	0067	0068	0069	0070	0071	0072	0073	0074	0075	0076	0077	0078	0079
050	0080	0081	0082	0083	0084	0085	0086	0087	0088	0089	0090	0091	0092	0093	0094	0095
060	0096	0097	0098	0099	0100	0101	0102	0103	0104	0105	0106	0107	0108	0109	0110	0111
070	0112	0113	0114	0115	0116	0117	0118	0119	0120	0121	0122	0123	0124	0125	0126	0127
080	0128	0129	0130	0131	0132	0133	0134	0135	0136	0137	0138	0139	0140	0141	0142	0143
090	0144	0145	0146	0147	0148	0149	0150	0151	0152	0153	0154	0155	0156	0157	0158	0159
0A0	0160	0161	0162	0163	0164	0165	0166	0167	0168	0169	0170	0171	0172	0173	0174	0175
080	0176	0177	0178	0179	0180	0181	0182	0183	0184	0185	0186	0187	0188	0189	0190	0191
000	0192	0193	0194	0195	0196	0197	0198	0199	0200	0201	0202	0203	0204	0205	0206	0207
0D0	0208	0209	0210	0211	0212	0213	0214	0215	0216	0217	0218	0219	0220	0221	0222	0223
0E0	0224	0225	0226	0227	0228	0229	0230	0231	0232	0233	0234	0235	0236	0237	0238	0239
0F0	0240	0241	0242	0243	0244	0245	0246	0247	0248	0249	0250	0251	0252	0253	0254	0255

10	г					4	5	6	7	8	9	Α	В	С	D	E	F
100	r												0267	0268	0269	0270	0271
170 170	1																
120	l I																
130 0304 0305 0307 0308 0307 0308 0307 0307 0308 0	: 1																
140 0320 0327 0332 0339 0340 0341 0342 0343 0346 0346 0347 0348 0349 0350 0351 160 0352 0353 0354 0355 0356 0357 0358 0359 0350 0351 0352 0363 0364 0365 0368 0367 0371 0372 0373 0374 0375 0376 0377 0378 0379 0380 0381 0362 0363 0364 0365 0368 0367 0371 0372 0373 0374 0375 0376 0377 0378 0379 0380 0381 0382 0381 0381 0382 0383 0381 0382 0383 0381 0382 0383 0380 0381 0382 0383 0380 0381 0382 0383 0380 0381 0382 0383 0380 0380 0381 0382 0383 03	130	0304	0305	0306	0307	0308	0309	0310	0311	0312	0313	0314	0313	0010			
150	140	0320	0321	0322	0323	0324	0325	0326	0327	0328	0329	0330	0331	0331	0333		
1860								0342	0343	0344	0345	0346	0347	0348	0349	0350	l l
170						-	-	0358	0359	0360	0361	0362	0363	0364	0365		0367
180	: .							0374		0376	0377	0378	0379	0380	0381	0382	0383
180	'''	0300	0303	0370	00	00/-	•••								0007	0000	0000
190 0400 0416 0417 0418 0419 0420 0421 0422 0423 0424 0425 0426 0427 0428 0429 0430 0441 0442 0443 0444 0445 0446 0	180	0384	0385	0386	0387	0388	0389	0390	0391		-						
140	190	0400	0401	0402	0403	0404	0405	0406	0407	0408							
180	1A0	0416	0417	0418	0419	0420	0421	0422	0423	0424							
100		0432	0433	0434	0435	0436	0437	0438	0439	0440	0441	0442	0443	0444	0445	0446	0447
100							0.450	0454	0455	DAEC	0457	UVES	0460	0460	0461	0462	0463
	1C0								_								
180 0496 0497 0498 0497 0498 0499 0500 0501 0502 0503 0504 0505 0506 0507 0508 0509 0510 0511 0511 0520 0531 0522 0533 0534 0535 0536 0537 0538 0539 0540 0541 0542 0542 0542 0542 0542 0542 0542 0542 0542 0542 0542 0543 0540 0541 0560 0561 0562 0563 0564 0565 0566 0567 0566 0565 0566 0567 0568 0569 0570 0571 0572 0573 0574 0575 0568 0569 0560 0561 0562 0563 0564 0565 0566 0567 0568 0569 0570 0571 0572 0573 0574 0575 0588 0589 0596 0	1D0	0464	0465				-					-		_	-		
10	1E0	0480	0481														L L
200 0528 0529 0530 0531 0532 0533 0534 0535 0536 0537 0538 0539 0540 0541 0542 0543 220 0544 0545 0566 0567 0568 0550 0551 0552 0553 0554 0555 0556 0557 0558 0559 0550 0551 0552 0553 0554 0555 0556 0557 0558 0559 0550 0551 0552 0553 0554 0555 0556 0557 0558 0559 0550 0551 0552 0553 0554 0555 0556 0557 0558 0559 0550 0550 0559 0550 0550 0550 0550 0550 0550 0559 0550 0559 0550 05	1F0	0496	0497	0498	0499	0500	0501	0502	0503	0504	0505	0506	0507	0506			
200 0528 0529 0530 0531 0532 0533 0534 0535 0536 0537 0538 0539 0540 0541 0542 0543 220 0544 0545 0566 0567 0568 0550 0551 0552 0553 0554 0555 0556 0557 0558 0559 0550 0551 0552 0553 0554 0555 0556 0557 0558 0559 0550 0551 0552 0553 0554 0555 0556 0557 0558 0559 0550 0551 0552 0553 0554 0555 0556 0557 0558 0559 0550 0550 0559 0550 0550 0550 0550 0550 0550 0559 0550 0559 0550 05					0545	0516	0517	0610	0510	0520	0521	0522	0523	0524	0525	0526	0527
200 0544 0545 0546 0547 0548 0549 0550 0556 0556 0556 0557 0558 0559 0566 0567 0571 0572 0573 0574 0575 0575 0576 0576 0575 0576 0575 0576 0575 0576 0576 0575 0576 0		1															l.
1940 1944 1945 1946 1947 1948 1947 1948		l															
240 0576 0577 0578 0579 0580 0581 0582 0583 0594 0595 0596 0597 0598 0599 0600 0601 0602 0603 0604 0605 0606 0607 0608 0599 0608 0608 0609 0610 0611 0612 0613 0614 0615 0615 0616 0617 0618 0619 0620 0621 0622 0623 0624 0625 0626 0627 0628 0629 0630 0631 0632 0633 0634 0635 0636 0637 0638 0639 0639 0630 0631 0632 0633 0634 0635 0636 0637 0638 0639 0639 0639 0639 0639 0639 0639 0666 0667 0668 0657 0658 0659 0660 0661 0662 0663 0664 0665 0666 0667 0668 0667 0668 0667 0668 0667 0668 0667 0668 0667 0668 0667 0668 0667 0668 0667 0668 0667 0668 0667 0668 0667 0668 0667 0668 0669 0690 0691 0692 0693 0694 0695 0696 0697 0698 0699 0700 0701 0702 0703 0704 0705 0706 0707 0708 0709 0710 0711 0711 0712 0713 0714 0715 0716 0717 0718 0719 0702 0703 0734 0735 0736 0739 0740 0741 0742 0743 0744 0745 0746 0747 0748 0749 0750 0751 0752 0753 0754 0755 0756 0757 0758 0759 0760 0761 0762 0763 0764 0765 0766 0767 0768 0769 0761 0762 0763 0764 0765 0766 0767 0768 0769 0761 0762 0763 0764 0765 0766 0767 0768 0769 0760 0761 0762 0763 0764 0765 0766 0767 0768 0769 0760 0761 0762 0763 0764 0765 0766 0767 0768 0769 0760 0761 0762 0763 0764 0765 0766 0767 0768 0769 0760 0761 0762 0763 0764 0765 0766 0767 0768 0769 0760 0761 0762 0763 0764 0765 0766 0767 0768 0769 0760 0761 0762 0763 0764 0765 0766 0767 0768 0769 0760 0761 0762 0763 0764 0765 0766 0767 0768 0769 0760 0761 0762 0763 0764 0765 0766 0767 0760 0761 0762 0763 0764 0765 0766 0767 0760 0761 0762 0763 0764 0765 0766 0767 0760 0761 0762 0763 0764 0765 0766 0767 0760 0761 0762 0763 0764 0765 0766 0767 0760 0761 0762 0763 0764 0765 0766 0767 0760 0761 0762 0763 0764 0765 0766 0767 0760 0761 0762 0763 0764 0765 0766 0767 0760 0761 0762 0763 0764 0765 0766 0767 0760 0761 0762 0763 0764 0765 0766 0767 0760 0761 0762 0763 0764 0765 0766 0767 0760 0761 0762 0763 0764 0765 0766 0767 0760 0761 0762 0763 0764 0765 0766 0767 0760 0761 0762 0763 0764 0765 0766 0767 0760 0761 0762 0763 0764 0765 0766 0767 0760 0761 0762 0760 0761 0762 0760 0761 0762 0760 0761 0762 0760 0761 0762 0760 0761 0762 07				•	-	-											
260 0692 0593 0594 0595 0596 0597 0598 0599 0600 0601 0602 0603 0604 0605 0606 0607 0608 0608 0608 0609 0610 0611 0612 0613 0614 0615 0616 0617 0618 0619 0620 0621 0622 0623 0624 0625 0626 0627 0628 0629 0630 0631 0632 0633 0634 0635 0636 0637 0638 0639 0638 0639 0636 0637 0638 0639 0638 0639 0638 0639 0638 0639 0636 0637 0638 0639 0639 0639 0694 0695 0696 0697 0698 0699 0700 0701 0702 0703 0704 0705 0706 0707 0708 0709 0710 0711 0712 0713 0714 0715 0716 0717 0713 0714 0715 0716 0717 0718 0719 0719 0719 0719 0719 0719 0719 0719	230	0560	0561	0562	0563	0564	0565	0555	0567	0500	0009	0570	0371	05,2	0370	557	00.0
250	240	0576	0577	0578	0579	0580	0581	0582	0583	0584	0585	0586	0587	0588	0589	0590	0591
260	L	i								0600		0602	0603	0604	0605	0606	0607
270 0624 0625 0626 0627 0628 0629 0630 0631 0632 0633 0634 0635 0636 0637 0638 0639	1	1										0618	0619	0620	0621	0622	0623
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	620	1568	1569	1570	1571	1572	1573	1574	1575	1576	1577	1578	1579	1580	1581	1582	1583
ŀ	630	1584	1585	1586	1587	1588	1589	1590	1591	1592	1593	1594	1595	1596	1597	1598	1599
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	640	1600	1601	1602	1603	1604	1605	1606	1607	1608	1609	1610	1611	1612	1613	1614	1615
	650	1616	1617	1618	1619	1620	1621	1622	1623	1624	1625	1626	1627	1628	1629	1630	1631
	660	1632	1633	1634	1635	1636	1637	1638	1639	1640	1641	1642	1643	1644	1645	1646	1647
	670	1648	1649	1650	1651	1652	1653	1654	1655	1656	1657	1658	1659	1660	1661	1662	1663
	680	1664	1665	1666	1667	1668	1669	1670	1671	1672	1673	1674	1675	1676	1677	1678	1679
	690	1680	1681	1682	1683	1684	1685	1686	1687	1688	1689	1690	1691	1692	1693	1694	1695
	6A0	1696	1697	1698	1699	1700	1701		1703	1704	1705	1706	1707	1708	1709	1710	1711
İ	6B0	1712	1713	1714	1715		1717	1718	1719	1720	1721	1722	1723	1724	1725	1726	1727
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	6C0	1728	1729	1730	1731	1732	1733		1735	1736	1737	1738	1739	1740	1741	1742	1743
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- [6E0 6F0	1760	1761	1762	1763	1764	1765	1766		1768	1769	1770	1771	1772	1773	1774	1775
l	OPU	1776	1777	1778	1779	1780	1/01	1782	1/63	1784	1785	1786	1787	1788	1789	1790	1791

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700	1792	1793	1794	1795	1796											
710	1808	1809	1810	1811	1812	1813	1814	1815	1816	1817	1818	1819	1820	1821	1822	1823
720	1824	1825	1826	1827	1828	1829	1830	1831	1832	1833	1834	1835	1836	1837	1838	1839
730	1840	1841	1842	1843	1844	1845	1846	1847	1848	1849	1850	1851	1852	1853	1854	1855
740	1856	1857	1858	1859	1860	1861	1862	1863	1864	1865	1866	1867	1868	1869	1870	1871
750	1872	1873	1874	1875	1876	1877	1878	1879	1880	1881	1882	1883	1884	1885	1886	1887
760	1888	1889	1890	1891	1892	1893	1894	1895	1896	1897	1898	1899	1900	1901	1902	1903
770	1904	1905	1906	1907	1908	1909	1910	1911	1912	1913	1914	1915	1916	1917	1918	1919
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780	1920	1921	1922	1923	1924	1925	1926	1927	1928	1929	1930	1931	1932	1933	1934	1935
790	1936	1937	1938	1939	1940	1941	1942	1943	1944	1945	1946	1947	1948	1949	1950	1951
				1955	1956	1957	1958	1959	1960	1961	1962	1963	1964	1965	1966	1967
7A0	1952	1953	1954			1973	1974	1975	1976	1977	1978	1979	1980	1981	1982	1983
7B0	1968	1969	1970	1971	1972	1973	1974	1975	1970	19//	1970	19/5	1500	1561	1502	1963
700	1004	1005	1000	1987	1988	1989	1990	1991	1992	1993	1994	1995	1996	1997	1998	1999
7C0	1984	1985	1986													
7D0	2000	2001	2002	2003	2004	2005	2006	2007	2008	2009	2010	2011	2012	2013	2014	2015
7E0	2016	2017	2018	2019	2020	2021	2022	2023	2024	2025	2026	2027	2028	2029	2030	2031
7F0	2032	2033	2034	2035	2036	2037	2038	2039	2040	2041	2042	2043	2044	2045	2046	2047
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800	2048	2049	2050	2051	2052	2053	2054	2055	2056	2057	2058	2059	2060	2061	2062	2063
810	2064	2065	2066	2067	2068	2069	2070	2071	2072	2073	2074	2075	2076	2077	2078	2079
		2081	2082	2083	2084	2085	2086	2087	2088	2089	2090	2091	2092	2093	2094	2095
820	2080					2101	2102	2103	2104	2105	2106	2107	2108	2109	2110	2111
830	2096	2097	2098	2099	2100	2101	2102	2100	2104	2105	2100	2107	2100	2100	2110	2111
040		2112	0114	2115	2116	2117	2118	2119	2120	2121	2122	2123	2124	2125	2126	2127
840	2112	2113	2114			2133	2134	2135	2136	2137	2138	2139	2140	2141	2142	2143
850	2128	2129	2130	2131	2132								-			
860	2144	2145	2146	2147	2148	2149	2150	2151	2152	2153	2154	2155	215 6	2157	2158	2159
870	2160	2161	2162	2163	2164	2165	2166	2167	2168	2169	2170	2171	2172	2173	2174	2175
880	2176	2177	2178	2179	2180	2181	2182	2183	2184	2185	2186	2187	2188	218 9	2190	2191
890	2192	2193	2194	2195	2196	2197	2198	2199	2200	2201	2202	2203	2204	2205	2206	2207
8A0	2208	2209	2210	2211	2212	2213	2214	2215	2216	2217	2218	2219	2220	2221	2222	2223
880	2224	2225	2226	2227	2228	2229	2230	2231	2232	2233	2234	2235	2236	2237	2238	2239
555	2227	2223	2220													
800	2240	2241	2242	2243	2244	2245	2246	2247	2248	2249	2250	2251	2252	2253	2254	2255
8D0	2256	2257	2258	2259	2260	2261	2262	2263	2264	2265	2266	2267	2268	2269	2270	2271
	ı			2275	2276	2277	2278	2279	2280	2281	2282	2283	2284	2285	2286	2287
8E0	2272	2273				2293		2295	2296		2298	2299		2301		2303
8F0	2288	2289	2290	2291	2292	2293	2294	2295	2290	2297	2296	2299	2300	2301	2302	2303
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900	2304	2305	2306	2307	2308	2309	2310	2311	2312	2313	2314	2315	2316	2317	2318	2319
910	2320	2321	2322	2323	2324	2325	2326	2327	2328	2329	2330	2331	2332	2333	2334	2335
920	2336	2337	2338	2339	2340	2341	2342	2343	2344	2345	2346	2347	2348	2349	2350	2351
930	2352	2353	2354	2355	2356	2357	2358	2359	2360	2361	2362	2363	2364	2365	2366	2367
550		_000		-												[
940	2368	2369	2370	2371	2372	2373	2374	2375	2376	2377	2378	2379	2380	2381	2382	2383
950	2384	2385	2386	2387	2388	2389	2390	2391	2392	2393	2394	2395	2396	2397	2398	2399
960	2400	2401	2402	2403	2404	2405	2406	2407	2408	2409	2410	2411	2412	2413	2414	2415
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970	2416	2417	2418	2419	4-12U	4741	L762	2723	Z7Z7	2723	2720	2721	2-720	2723	2730	2701
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980	2432	2433												2461	2462	2463
990	2448	2449	2450	2451	2452	2453		2455	2456	2457	2458	2459	2460			1
9A0	2464	2465	2466	2467	2468	2469		2471	2472	2473	2474	2475	2476	2477	2478	2479
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9D0	2512	2513	2514	2515	2516	2517	2518	2519	2520	2521	2522	2523	2524	2525	2526	2527
9E0	2528	2529	2530	2531	2532	2533	2534	2535	2536	2537	2538	2539	2540	2541	2542	2543
1	2544	2545		2547		2549		2551	2552		2554	2555	2556	2557	2558	2559
9F0	2044	2040	2070	£471												

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ARD				2690	2691	2692	2693	2694	2695	2696	2697	2698	2699	2700	2701	2702	2703
ABO	1						2709	2710	2711	2712	2713	2714	2715	2716	2717	2718	2719
ACC 2752 2753 2754 2755 2756 2757 2758 2759 2760 4761 2762 2763 2764 2765 2766 2767 ADO 2768 2769 2770 2771 2772 2773 2774 2775 2776 2779 2780 2781 2782 2783 AEO 2784 2785 2786 2787 2788 2789 2790 2781 2792 2773 2774 2775 2776 2780 2780 2781 2782 2783 AEO 2784 2785 2786 2787 2788 2789 2780 2781 2782 2783 2784 2775 2780 2780 2781 2782 2783 2784 2785 2786 2787 2788 2789 2780 2781 2782 2783 2784 2775 2810 2811 2811 2811 2811 2811 2811 2811								2726	2727	2728	2729	2730	2731	2732	2733	2734	2735
ADD	ABO	2736	2737	2738	2739	2740	2741	2742	2743	2744	2745	2746	2747	2748	2749	2750	2751
ADD	ACO	2752	2753	2754	2755	2756	2757	2758	2759	2760	4761	2762	2763	2764	2765	2766	2767
AFO	1													-			
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	1	3296		3298	3299					3304	3305	3306	3307	3308			
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D00	3328	3329	3330	3331	3332	3333	3334	3335	3336	3337	3338	3339	3340	3341	3342	3343
D10	3344	3345	3346	3347	3348	3349	3350	3351	3352	3353	3354	3355	3356	3357	3358	3359
D20	3360	3361	3362	3363	3364	3365	3366	3367	3368	3369	3370	3371	3372	3373	3374	3375
D30	3376	3377	3378	3379	3380	3381	3382	3383	3384	3385	3386	3387	3388	3389	3390	3391
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D40	3392	3393	3394	3395	3396	3397	3398	3399	3400	3401	3402	3403	3404	3405	3406	3407
D50	3408	3409	3410	3411	3412	3413	3414	3415	3416	3417	3418	3419	3420	3421	3422	3423
D60	3424	3425	3426	3427	3428	3429	3430	3431	3432	3433	3434	3435	3436	3437	3438	3439
D70	3440	3441	3442	3443	3444	3445	3446	3447	3448	3449	3450	3451	3452	3453	3454	3455
D80	3456	3457	3458	3459	3460	3461	3462	3463	3464	3465	3466	3467	3468	3469	3470	3471
D90	3472	3473	3474	3475	3476	3477	3478	3479	3480	3481	3482	3483	3484	3485	3486	3487
DAO	3488	3489	3490	3491	3492	3493	3494	3495	3496	3497	3498	3499	3500	3501	3502	3503
DB0	3504	3505	3506	3507	3508	3509	3510	3511	3512	3513	3514	3515	3516	3517	3518	3519
DC0	3520	3521	3522	3523	3524	3525	3526	3527	3528	3529	3530	3531	3532	3533	3534	3535
CC0	3536	3537	3538	3539	3540	3541	3542	3543	3544	3545	3546	3547	3548	3549	3550	3551
DEO	3552	3553	3554	3555	3556	3557	3558	3559	3560	3561	3562	3563	3564	3565	3566	3567
DF0	3568	3569	3570	3571	3572	3573	3574	3575	3576	3577	3578	3579	3580	3581	3582	3583
E00	3584	3585	3586	3587	3588	3589	3590	3591	3592	3593	3594	3595	3596	3597	3598	3599
E10	3600	3601	3602	3603	3604	3605	3606	3607	3608	3609	3610	3611	3612	3613	3614	3615
E20	3616	3617	3618	3619	3620	3621	3622	3623	3624	3625	3626	3627	3628	3629	3630	3631
E30	3632	3633	3634	3635	3636	3637	3638	3639	3640	3641	3642	3643	3644	3645	3646	3647
E40	3648	3649	3650	3651	3652	3653	3654	3655	3656	3657	3658	3659	3660	3661	3662	3663
E50	3664	3665	3666	3667	3668	3669	3670	3671	3672	3673	3674	3675	3676	3677	3678	3679
E60	3680	3681	3682	3683	3684	3685	3686	3687	3688	3689	3690	3691	3692	3693	3694	3695
E70	3696	3697	3698	3699	3700	3701	3702	3703	3704	3705	3706	3707	3708	3709	3710	3711
E80	3712	3713	3714	3715	3716	3717	3718	3719	3720	3721	3722	3723	3724	3725	3726	3727
E90	3728	3729	3730	3731	3732	3733	3734	3735	3736	3737	3738	3739	3740	3741	3742	3743
EA0	3744	3745	3746	3747	3748	3749	3750	3751	3752	3753	3754	375 5	3756	3757	3758	3759
EB0	3760	3761	3762	3763	3764	3765	3766	3767	3768	3769	3770	3771	3772	3773	3774	3775
EC0	3776	3777	3778	3779	3780	3781	3782	3783	3784	3785	3786	3787	3788	3789	3790	3791
ED0	3792	3793	3794	3795	3796	3797	3798	3799	3800	3801	3802	3803	3804	3805	3806	3807
EE0	3808	3809	3810	3811	3812	3813	3814	3815	3816	3817	3818	3819	3820	3821	3822	3823
EF0	3824	3825	3826	3827	3828	3829	3830	3831	3832	3833	3834	3835	3836	3837	3838	3839
F00	3840	3841	3842	3843	3844	3845	3846	3847	3848	3849	3850	3851	3852	3853	3854	3855
F10	3856	3857	3858	3859	3860	3861	3862	3863	3864	3865	3866	3867	3868	3869	3870	3871
F20	3872	3873	3874	3875	3876	3877	3878	3879	3880	3881	3882	3883	3884	3885	3886	3887
F30	3888	3889	3890	3891	3892	3893	3894	3895	3896	3897	3898	3899	3900	3901	3902	3903
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F40	3904	3905	3906	3907	3908	3909	3910	3911	3912	3913	3914	3915	3916	3917	3918	3919
F50	3920	3921	3922	3923	3924	3925	3926	3927	3928	3929	3930	3931	3932	3933	3934	3935
F60	3936	3937	3938	3939	3940	3941	3942	3943	3944	3945	3946	3947	3948	3949	3950	3951
F70	3952	3953	3954	3955	3956	3957	3958	3959	3960	3961	3962	3963	3964	3965	3966	3967
F80	3968	3969	3970	3971	3972	3973	3974	3975	3976	3977	3978	3979	3980	3981	3982	3983
F90	3984	3985	3986	3987	3988	3989	3990	3991	3992	3993	3994	3995	3996	3997	3998	3999
FA0	4000	4001	4002	4003	4004	4005	4006	4007	4008	4009	4010	4011	4012	4013	4014	4015
FB0	4016	4017	4018	4019	4020	4021	4022	4023	4024	4025	4026	4027	4028	4029	4030	4031
														40.4-	40.40	404-
FC0	4032	4033	4034	4035	4036	4037	4038	4039	4040	4041	4042	4043	4044	4045	4046	4047
FD0	4048	4049	4050	4051	4052	4053	4054	4055	4056	4057	4058	4059	4060	4061	4062	4063
FE0	4064	4065	4066	4067	4068	4069	4070	4071	4072	4073	4074	4075	4076	4077	4078	4079
FF0	4080	4081	4082	4083	4084	4085	4086	4087	4088	4089	4090	4091	4092	4093	4094	4095

)	CONTENTS OF COUNTER	COUNTS TO INTERRUPT	CONTENTS OF COUNTER	COUNTS TO INTERRUPT	CONTENTS OF COUNTER	COUNTS TO INTERRUPT	CONTENT OF COUNTER	TO
	FE	254	4D	189	D2	124	9F	59
	FD	253	9A	188	A5	123	3D	58
	FB	252	34	187	4B	122	7C	57
	F7	251	69	186	96	121	F8	56
	EΕ	250	D3	185	2D	120	F1	55
	DC	249	A7	184	5B	119	E2	54
	B8	248	4F	183	В7	118	C5	53
	71	247	9E	182	6E	117	8A	52
	E3	246	3C	181	DD	116	15	51
	<u>C7</u>	245	<u>78</u>	180	BA	115	2 <u>A</u>	50
	8E 1D	244 243	FO EO	179	75 50	114	55	49
	3B	243 242	C1	1 7 8 177	EB D6	113 112	AA 54	48 47
	76	241	82	176	AD	111	A8	46
	<u>EĎ</u>	240	04	175	5A	110	50	45
	DA	239	09	174	B5	109	AO	44
	В4	238	12	173	6A	108	, 41	43
	68	237	24	172	D5	107	83	42
	D1	236	48	171	AB	106	06	41
	A3	235	90	170	56	105	OD	40
	47	234	21	169	AC	104	1A	39
	8F 1F	233 232	42	168	58	103	35	38
	3F	232	85 0A	167 166	B1 62	102 101	6B	37
	7E	230	14	165	C4	100	D7 AF	36 35
	FC	229	28	164	88	99	5E	34
	F9	228	51	163	11	98	BD	33
	F3	227	A2	162	22	97	78	32
	E6	226	45	161	44	96	F6	31
	CD	225	8B	160	89	95	EC	30
	9B	224	17	159	13	94	D8	29
	36	223	2E	158	26	93	BO	28
	6D	222	5D	157	4C	92	60	27
	DB	221	BB	156	98	91	co	26
	B6 6C	220 219	<u>77</u> EF	<u>155</u> 164	30	90	<u>80</u> 00	25 24
	D9	218	DE	153	61 C2	89 88	C1	23
	B2	217	BC	152	84	87	03	22
	64	216	79	151	03	86	07	21
	C8	215	F2	150	10	85	OF	20
•	91	214	E4	149	20	84	1E	19
	23	213	C9	148	40	83	3D	18
	46	212	93	147	81	82	7A	17
	8D	211	27	146	02	81	F4	16
-	1 <u>B</u>	210	4E	145	<u> 05</u>	80	<u>E8</u>	15
	37 6F	209 208	9C 38	144	0B	79 79	D0	14
	DF	207	38 70	143 142	16 2C	78 77	A1 43	13 12
	BE	206	70 E1	141	59	76	43 87	11
	7D	205	C3	140	B3	75	0E	10
-	FA	204	86	139	66	74	1C	9 -
	F5	203	OC	138	CC	73	39	8
	ĒΑ	202	18	137	99	72	72	7
	D4	201	31	136	32	71	E5	6
-	A9	200	<u>63</u> .	135	65	70	<u>CB</u>	5
	52	199	C6	134	CA	69	97	4
	A4 49	198 197	8C 19	133	95 38	68 67	2F	3
	92	196	33	132 313	2B 5.7	67 66	5F	2
	25	195	67	130	57 AE	65	BF 7F	1 0
-	4A	194	CE	129	5C	64	FE FE	254
	94	193	9D	128	B9	63	1 L	234
	29	192	3A	127	73	62		
	53	191	74	126	£7	61		
_	A6	190	E9	125	CF	60		

APPENDIX D - INSTRUCTION SUMMARY

ACCUMULATOR GROUP INSTRUCTIONS

OP CODE	OPER- AND(S)	OBJECT CODE	FUNCTION	OVF		TUS BITS		CYCLES	BYTES OF OBJECT CODE	INTERRUPT PRIVILEGE 1)	DMA SLOTS ²
SR	1	12	SHIFT RIGHT ONE	0	1/0	0	1	1	1	_	1
SR	4	14	SHIFT RIGHT ONE	0	1/0	0	1	1	1	_	1
SL	1	13	SHIFT LEFT ONE	0	1/0	0	1/0	1	1	_	1
SL	4	15	SHIFT LEFT FOUR	0	1/0	0	1/0	1	1	_	1
сом	_	18	ACC (ACC) ⊕ H'FF'	0	1/0	0	1/0	1	1	_	1
LNK	_	19	ACC (ACC) + CB	1/0	1/0	1/0	1/0	1	1	_	1
INC	_	1 F	ACC (ACC) + 1	1/0	1/0	1/0	1/0	t	1	-	1
LIS	i	7i	ACC H'i'			_		1	1	_	1
CLR	_	70	ACC H'00'			_		1	1	_	1
LI	ii	20 ii	ACC H'ii'			_		2.5	2	_	2
NI	ii	21 ∔i	ACC (ACC) H'ii'	0	1/0	0	1/0	2.5	2	_	2
OI	ii	22 ii	ACC (ACC) V H'ii'	0	1/0	0	1/0	2.5	2	_	2
ΧI	ij	23 ii	ACC (ACC) ⊕ H'ii'	0	1/0	0	1/0	2.5	2	_	2
Al	ii	24 ii	ACC (ACC) + H'ii' (Binary Add)	1/0	.1/0	1/0	1/0	2.5	2	_	2
CI	ii	25 ii	H'ii' + (ACC)+1	1/0	1/0	1/0	1/0	2.5	2	_	2

¹⁾ An interrupt request cannot be acknowledged until an instruction without interrupt privilege has completed execution.
2) This number of bytes can be transferred via DMA_during the instruction's execution.

SCRATCHPAD REGISTER INSTRUCTIONS

OP CODE	OPER- AND(S)	OBJECT CODE	FUNCTION	STA [*] OVF ZERO	TUS BITS			BYTES OF OBJECT CODE	INTERRUPT 1) PRIVILEGE 1)	DMA SLOTS
LR	у,х		GENERAL LOAD REGISTER FORMAT ALLOWABLE OPER- ANDS LISTED BELOW				1	_		_
	A,r*	4г	ACC (r)		_			1	_	1
	A,KU	00	ACC (r12)		_			1		1
	A,KL	01	ACC (r13)		_			í	_	1
	A,QU		ACC (r14)					1	_	1
	A,QL	03	ACC (r15)					1	_	1
	r,A	5r	r (ACC)		_			1	_	1
	KU,A	04	r12 (ACC)		_			1	_	1
	KL,A	05	r13 (ACC)					1	_	1
	QU,A	06	r14 (ACC)					1	_	1
	QL,A	07	r15 (ACC)		_			1	-	1
AŞ	r	Cr	ACC (ACC)+(r)(Binary)	1/0 1/0	1/0	1/0	1	1	_	1
ASD	r	Dr	ACC (ACC)+(r) (Decimal)		1/0	1/0	2	1	_	2
NS	r	Fr	ACC (ACC) (r)	0 1/0	0	1/0	1	1	_	1
XS	r		ACC (ACC) ⊕ (r)	0 1/0	0	1/0	1	1	_	1
DS	r	3r	r (r)+H'FF'(Decrement)	1/0 1/0	1/0	1/0	1.5	1	_	1
* Opera	and r form	nats are:	Direct Addressing		Indi	rect Ad	dressing			
			0 through 11 (Decimal H'0' through H'B' (hexa		m)	S or	12 13			
			no through no thexa	decimal for	111)	D or	14			

DATA COUNTER INSTRUCTIONS

_	OPER- AND(S)			FUNCTION	STATUS BITS OVF ZERO CARRY SIGN		BYTES OF OBJECT CODE	INTERRUPT 1)	DMA SLOTS ²
LR	Q,DC	0E	r14	(DCU) ; r15 (DCL)		4	1	_	3
LR	H.DC	11		(DCU); r11 (DCL)	_	4	1	_	3
_R	DC.Q	0F		(r14); DCL (r15)	_	4	1		3
_n. _R	DC.H	10		(r10); DCL (r11)	_	4	1		3
ADC	_	8E		(DC) + (ACC)	_	2.5	1		2
DCI	iiii	2A ii		H'iiii'	_	6	3	_	5
XDC	_	ii 2C	[Men	DC ₁ hory Interface uit Only]	-	2	1	_	2

INDIRECT SCRATCHPAD ADDRESS REGISTER INSTRUCTIONS

		OBJECT CODE	1	FUNCTION	STATUS BITS OVF ZERO CARRY SIGN	CYCLES	BYTES OF OBJECT CODE	INTERRUPT 1)	DMA SLOTS ²
LR	A,IS	0A	ACC	(ISAR)	_	1	1	_	1
LR	IŞ,A	QВ	ISAR	(ACC)	_	1	1		1
LISU	a	01100a*	ISARU	l a	_	1	1		1
LISL	а	01101a*	ISARL	а	_	1	1		1

^{*} a is 3 bits

MEMORY REFERENCE INSTRUCTIONS

OP CODE	OPER- AND(S)	OBJECT CODE	FUNCTION	OVF		TUS BITS		CYCLES	BYTES OF OBJECT CODE	INTERRUPT 1)	DMA SLOTS ²
LM		16	ACC ((DC))			_		2.5	1	_ _	2
ST	_	17	(DC) (ACC)			_		2.5	1	_	1
AM	_	88	ACC (ACC)+((DC))	1/0	1/0	1/0	1/0	2.5	1	_	2
AMD	_	89	(Binary) ACC (ACC)+((DC)) (Decimal)	1/0	1/0	1/0	1/0	2.5	1	_	2
NM	_	8A	ACC (ACC) ((DC))	0	1/0	0	1/0	2.5	1	_	2
OM		8B	ACC (ACC) ((DC))	0	1/0	0	1/0	2.5	1	_	2
XM	_	8C	ACC (ACC) ⊕ ((DC))	0	1/0	0	1/0	2.5	1	_	2
СМ	_	8D	((DC)) + (ACC) + 1)	1/0	1/0	1/0	1/0	2.5	1		2

STATUS REGISTER INSTRUCTIONS

	OPER- AND(S)	OBJECT	FUNCTION	STATUS BITS OVF ZERO CARRY SIGN		BYTES OF OBJECT CODE	INTERRUPT 1)	DMA 2)
LR	W,J	1D	W (r9) W4 W3 W2 INT OVF ZERO	W ₁ W ₀ CARRY SIGN	2	1	Yes*	2
LR	J,W	18	(Privileged Instruct r9 (W)	ion)*	1	1 _		1

^{*} As a result of a privileged instruction execution, a request for interrupt service is not acknowledged by the CPU until a subsequent non-privileged instruction is executed.

MISCELLANEOUS INSTRUCTIONS

	OPER- AND(S)	OBJECT	FUNCTION	STATUS BITS OVF ZERO CARRY SIGN	CYCLES	BYTES OF OBJECT CODE	INTERRUPT 1) PRIVILEGE	DMA 2)
NOP	_	28	NO OPERATION		1	1	 -	1

PROGRAM COUNTER INSTRUCTIONS

OP CODE	OPER- AND(S)	OBJECT	FUNCTION	OVF	STATUS BITS ZERO CARRY SIGN		BYTES OF OBJECT CODE	INTERRUPT 1) PRIVILEGE 1)	DMA SLOTS ²⁾
LR	K,P	08	r12 (PC ₁ U); r13	(PC ₁ L)	_	4	1		3
LR	P,K	09	PC ₁ U (r12); PC ₁ L	(r13)	_	4	1	_	3
LR	P0,Q	OD	PCOU (r14) ; PCOL	(r15)	_	4	1	_	3
PK	_	oc	PCOU (r12); PCOL and PC ₁ (PCO) Privileged Instruction	(r13)	_	4	1	Yes*	3
PI	aaaa**	28 ii	PC ₁ (PC ₀); PC ₀		_	6.5	3	Yes*	5
POP	_	ii ' 1C	Privileged Instruction PCO (PC1) Privileged Instruction			2	1	Yes*	2

BRANCH INSTRUCTIONS

OP CODE	OPER- AND(S)	OBJECT CODE	FUNCTION	STATUS BITS OVF ZERO CARRY S		BYTES OF OBJECT CODE	INTERRUPT 1) PRIVILEGE 1)	DMA SLOTS ²⁾
BR	aa	90 aa	PC _O {{PC _O }+1} + H'aa'		3.5	2	_	3
JMP	aaaa 2	29 aa	PC _O H'aaaa'	_	5.5	3	Yes 1	4
		aa	Privileged Instruction*					
вт	t,aa4	8t 4	PCO ((PCO)+ H'aa'	_	3.5 3	2	_	3
		aa	if any test is true		or			
			PC _O (PC _O)+ 2 if no tes STATUS BIT TESTS 2 ² 2 ¹ 2 ^o ZERO CARRY SIGN		3.0			
BP	aa	81	PC _O ((PC _O)+1)+ H'aa' if SIGN=1	_	3.5	2	_	3
		aa	PC_0 (PC ₀)+2 if SIGN=0	0 —	3.0			
вс	aa	82	PCO ((PCO)+1)+ H'aa' i	f CARRY=1 —	3.5	2	_	3
		aa	PCO (PCO)+ 2 if CARR	Y=0 —	3.0			
BZ	aa	84	PCO ((PCO)+1) H'aa' if	ZERO-1 —	3.5	2	_	3
		aa	PCO (PCO)+ 2 if ZERO		3.0			
вм	aa	91	PCO ((PCO)+1)+ H'aa'		3.5	2		3
		aa	PCO (PCO)+ 2 if SIGN=	=1 —	3.0			
BNC	aa	92	PCO ((PCO)+1)+ H'aa' i	if CARRY=0	3.5	2	_	3
		aa	PCO (PCO)+ 2 if CARR	Y=1 —	3.0			
BNZ	aa	94	PCO ((PCO)+1)+ H'aa' i	ıf ZERO≃0 —	3.5			
		aa	PCO (PCO)+ 2 if ZERO	=1 —	3.0			
BF	t5,aa	9t 5	PCO ((PCO)+1)+ H'aa'		3.5 2	2	_	3
		aa	if selected status bits are	e all ''O''				
			PCO (PCO)+2 if any sta TEST CONDITIONS 23 22 21 OVF ZERO CARRY	2 °	— 3.0			
BNO	aa	98	PC _O ((PC _O)+1)+ H'aa' i	if OVF=0 —	3.5 2	2	_	3
		aa	PCO (PCO)+ 2 if OVF=	1 —	3.0			
BRZ	aa	8F	PCO ((PCO)+1)+ H'aa' i	if I\$AR≠7 —	2.5 2	2	_	2
		aa	PCO (PCO)+ 2 if ISAR=	:7 —	2.0			

^{1.} As a result of a privileged instruction execution, a request for interrupt service is not acknowledged by the CPU until a subsequent non-privileged instruction is executed.

^{2.} The contents of the accumulator are destroyed.

^{3. 3,5} cycles if branch is taken. 3.0 cycles if branch is not taken.

^{4.} t is only 3 bits

^{5.} t is four bits6. 2.5 cycles if branch is taken. 2.0 cycles if branch is not taken.

INTERRUPT CONTROL INSTRUCTIONS

OP CODE	OPER- AND(S)	OBJECT CODE	FUNCTION	STATUS BITS OVF ZERO CARRY SIGN		BYTES OF OBJECT CODE	INTERRUPT 1)	DMA SLOTS ²
DI	_	1A	DISABLE INTERRUPT		2	1	_	2
EI	_	18	ENABLE INTERRUPT Privileged Instruction*	_		1	YES*	2

INPUT/OUTPUT INSTRUCTIONS

OP	OPER-	OBJECT			STAT	US BITS	;		BYTES OF OBJECT	INTERRUPT ₁	DMA 2
	AND(S)	CODE	FUNCTION	OVF	ZERO	CARRY	SIGN	CYCLES	CODE	PRIVILEGE "	SLOTS
INS	а	Aa	ACC (INPUT PORT a) Input Ports 00 to 0F only	0	1/0	0	1/0	4**	1	_	3
IN	aa	26 aa	ACC (INPUT PORT aa)	0	1/0	0	1/0	4	2	_	3
OUTS	а	Ва	OUTPUT PORT a (ACC) Output Ports 00 to 0F only			_		4**	1	YES**	3
OUT	aa	27 aa	OUTPUT PORT aa (ACC Output Ports 04 through	()	ıly	_		4	2	YES*	3

^{*} As a result of a privileged instruction execution, a request for interrupt service is not acknowledged by the CPU until a subsequent non-privileged instruction is executed.

** 2 cycles when I/O port address is "0" or "1".